AUTOMOTIVE

RoHS

COMPLIANT

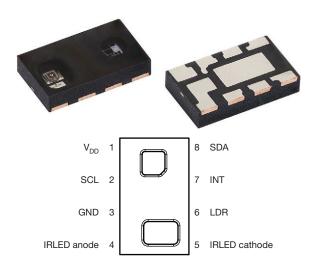
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**GREEN** 



Vishay Semiconductors

# Fully Integrated Proximity and Ambient Light Sensor With Infrared Emitter, I<sup>2</sup>C Interface, and Interrupt Function (with multiple slave addresses)



### **LINKS TO ADDITIONAL RESOURCES**







### **DESCRIPTION**

Rev. 1.3, 07-Jul-2023

VCNL4030X01 integrates a proximity sensor (PS), ambient light sensor (ALS), and a high power IRED into one small package. It incorporates photodiodes, amplifiers, and analog to digital converting circuits into a single chip by CMOS process. The 16-bit high resolution ALS for excellent sensing capabilities with sufficient selections to fulfill most applications whether dark or high transparency lens design. Both ALS and PS offer a programmable interrupt with individual high and low thresholds offers the power savings on the microcontroller.

The proximity sensor features an intelligent cancellation scheme, so that cross talk is eliminated effectively. The proximity's smart persistence feature prevents the misjudgment of proximity sensing with a fast response time. Active force mode, one time trigger by one instruction, offers more design flexibility to fulfill different kinds of applications with more power savings.

The adoption of patented Filtron<sup>TM</sup> technology achieves the closest ambient light spectral sensitivity to real human eye responses and offers the best background light cancellation capability (including sunlight) without utilizing the microcontrollers' resources. VCNL4030X01 provides an excellent temperature compensation capability for keeping the output stable over temperature. ALS and PS functions are easily operated via the simple command format of I<sup>2</sup>C (SMBus compatible) interface protocol. Operating voltage ranges from 2.5 V to 3.6 V. VCNL4030X01 is packaged in a lead-free 8-pin QFN package, which offers the best

market-proven reliability quality.

### **FEATURES**

- · Package type: surface-mount
- Dimensions (L x W x H in mm): 4.0 x 2.36 x 0.75
- AEC-Q101 qualified
- Integrated modules: infrared emitter (IRED), ambient light sensor (ALS), proximity sensor (PS), and signal conditioning IC



- Filtron<sup>TM</sup> technology adoption for robust background light cancellation
- Low power consumption I<sup>2</sup>C (SMBus compatible) interface
- Orderable in four different slave addresses
- Output type: I<sup>2</sup>C bus (ALS / PS)
- Operation voltage: 2.5 V to 3.6 V
- Floor life: 168 h, MSL 3, according to J-STD-020
- Material categorization: for definitions of compliance please see <a href="https://www.vishav.com/doc?99912"><u>www.vishav.com/doc?99912</u></a>

### PROXIMITY FUNCTION

- Immunity to red glow (940 nm IRED)
- Programmable IRED sink current
- Intelligent cancellation to reduce cross talk phenomenon
- Smart persistence scheme to reduce PS response time
- Selectable for 12- / 16-bit PS output data

### **AMBIENT LIGHT FUNCTION**

- High accuracy of ALS ± 10 %
- · Fluorescent light flicker immunity
- Spectrum close to real human eye responses

### **INTERRUPT**

- Programmable interrupt function for ALS and PS with upper and lower thresholds
- Adjustable persistence to prevent false triggers for ALS and PS

### **APPLICATIONS**

- · Proximity sensor for
  - Mobile devices (e.g. smart phones, tablets) for touch screen locking, power saving etc.
  - Automotive for presence detection
- Integrated ambient light function for display / keypad contrast control and dimming of mobile devices
- Collision detection in robots and tovs
- Proximity / optical switch for consumer, computing, automotive and industrial devices, and displays (like notebooks, tablet PCs, and automotive touch panels)
- Dimming control for consumer, computing, industrial, and automotive displays



PRODUCT S	PRODUCT SUMMARY									
PART NUMBER	OPERATING RANGE (mm)	OPERATING VOLTAGE RANGE (V)	VOLTACE	IRED PULSE CURRENT (1) (mA)		AMBIENT LIGHT RESOLUTION (lx)	OUTPUT	ADC RESOLUTION PROXIMITY / AMBIENT LIGHT		
VCNL4030X01	0 to 300	2.5 to 3.6	1.8 to 5.5	200	0.004 to 16 768	0.004	16 bit, I <sup>2</sup> C	16 bit / 16 bit		

### Note

<sup>(1)</sup> Adjustable through I<sup>2</sup>C interface

ORDERING INFORMATION							
ORDERING CODE	PACKAGING	VOLUME (1)	REMARKS				
VCNL4030X01-GS08		MOQ: 3300 pcs					
VCNL4030X01-GS18		MOQ: 13 000 pcs					
VCNL40301X01-GS08		MOQ: 3300 pcs					
VCNL40301X01-GS18	Tana and real	MOQ: 13 000 pcs	4.0 mm x 2.36 mm x 0.75 mm				
VCNL40302X01-GS08	Tape and reel	MOQ: 3300 pcs	4.0 mm x 2.36 mm x 0.75 mm				
VCNL40302X01-GS18		MOQ: 13 000 pcs					
VCNL40303X01-GS08		MOQ: 3300 pcs					
VCNL40303X01-GS18		MOQ: 13 000 pcs					

### Note

(1) MOQ: minimum order quantity

SLAVE ADDRESS OPTIONS						
ORDERING CODE	SLAVE ADDRESS (7 bit)					
VCNL4030X01-GS08	0x60					
VCNL4030X01-GS18						
VCNL40301X01-GS08	0.451					
VCNL40301X01-GS18	0x51					
VCNL40302X01-GS08	0x40					
VCNL40302X01-GS18						
VCNL40303X01-GS08	0x41					
VCNL40303X01-GS18	0341					

ABSOLUTE MAXIMUM RATINGS (T <sub>amb</sub> = 25 °C, unless otherwise specified)								
PARAMETER	TEST CONDITION	SYMBOL	MIN.	MAX.	UNIT			
Supply voltage		V <sub>DD</sub>	2.5	3.6	V			
Operation temperature range		T <sub>amb</sub>	-40	+105	°C			
Storage temperature range		T <sub>stg</sub>	-40	+110	°C			

<b>RECOMMENDED OPERATING CONDITIONS</b> (T <sub>amb</sub> = 25 °C, unless otherwise specified)								
PARAMETER	TEST CONDITION	SYMBOL	MIN.	MAX.	UNIT			
Supply voltage		V <sub>DD</sub>	2.5	3.6	V			
Operation temperature range		T <sub>amb</sub>	-40	+105	°C			
I <sup>2</sup> C bus operating frequency		f <sub>(I2CCLK)</sub>	10	400	kHz			



PIN DESCRIPTIONS								
PIN ASSIGNMENT	SYMBOL	TYPE	FUNCTION					
1	V <sub>DD</sub>	-	Power supply input					
2	SCL	I	I <sup>2</sup> C digital bus clock input					
3	GND	-	Ground					
4	IR ANODE	I	Anode for IRED					
5	IR CATHODE	I	Cathode (IRED) connection					
6	LDR	I	IRED driver input					
7	INT	0	Interrupt pin					
8	SDA	I / O (open drain)	I <sup>2</sup> C data bus data input / output					

### **BLOCK DIAGRAM**

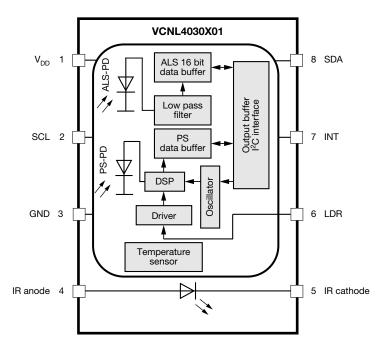


Fig. 1 - Detailed Block Diagram



BASIC CHARA	ACTERISTIC	CS (T <sub>amb</sub> = 25 °C, unless otherw	ise specit	fied)			
PARAMETER		TEST CONDITION	SYMBOL	MIN.	TYP.	MAX.	UNIT
Supply voltage			$V_{DD}$	2.5	-	3.6	V
Cumply assurant		Excluded LED driving	I <sub>DD</sub>	-	300	-	μΑ
Supply current		Light condition = dark, V <sub>DD</sub> = 3.3 V	I <sub>DD</sub> (SD)	-	0.2	-	μΑ
I <sup>2</sup> C supply voltage			V <sub>PULL UP</sub>	1.8	-	5.5	V
ALS shut down		ALS disable, PS enable	I <sub>ALSSD</sub>	-	200	-	μΑ
PS shut down		ALS enable, PS disable	I <sub>PSSD</sub>	-	260	-	μΑ
	Logic high	V 22V	V <sub>IH</sub>	1.55	-	-	V
I <sup>2</sup> C signal input	Logic low	$V_{DD} = 3.3 \text{ V}$	V <sub>IL</sub>	-	=	0.4	V
I-O signal input	Logic high	V <sub>DD</sub> = 2.6 V	V <sub>IH</sub>	1.4	=	-	V
	Logic low	v <sub>DD</sub> = 2.6 v	V <sub>IL</sub>	-	-	0.4	V
Peak sensitivity war ALS	velength of		$\lambda_{p}$	-	550	-	nm
Peak sensitivity wa	velength of PS		$\lambda_{p}$	-	850	-	nm
Full ALS counts		16-bit resolution		-	-	65 535	steps
Full PS counts		12-bit / 16-bit resolution		-	-	4096 / 65 535	steps
ALS sensing tolerar	nce	White LED light source		-	-	± 10	%
Detectable	Minimum	ALS_IT = 800 ms, 1 step (1)(2)		-	0.004	-	1
intensity Maximum		ALS_IT = 50 ms, 65 535 step <sup>(1)(2)</sup>		-	16 768	-	lx
ALS dark offset		ALS_IT = 50 ms, normal sensitivity (1)		0	-	3	steps
PS detection range		Kodak gray card		0	-	300	mm
Operating temperature range			T <sub>amb</sub>	-40	-	+105	°C
LED_Anode voltage	)			-	-	5.5	V
IRED driving current		(3)		-	200	-	mA

### **Notes**

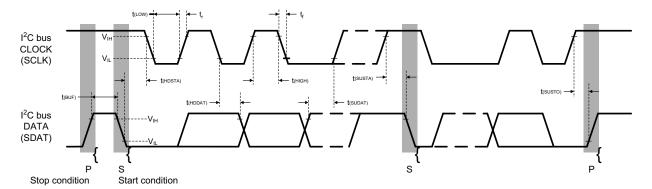
 $<sup>^{(1)}</sup>$  Test condition:  $V_{DD}$  = 3.3 V, temperature: 25  $^{\circ}C$ 

<sup>(2)</sup> Maximum detection range to ambient light can be determined by ALS refresh time adjustment and two sensitivity bits (ALS\_HD and ALS\_NS). Refer to table "ALS Resolution and Maximum Detection Range"

 $<sup>^{(3)}</sup>$  Programmable between 50 mA and 200 mA; based on IRED on / off duty ratio = 1/40, 1/80, 1/160, and 1/320



I <sup>2</sup> C BUS TIMING CHARACTERISTICS (T <sub>amb</sub> = 25 °C, unless otherwise specified)							
DADAMETED	CYMPOL	STANDA	RD MODE	FAST	LINUT		
PARAMETER	SYMBOL	MIN.	MAX.	MIN.	MAX.	UNIT	
Clock frequency	f <sub>(I2CCLK)</sub>	10	100	10	400	kHz	
Bus free time between start and stop condition	t <sub>(BUF)</sub>	4.7	-	1.3	-	μs	
Hold time after (repeated) start condition; after this period, the first clock is generated	t <sub>(HDSTA)</sub>	4.0	-	0.6	-	μs	
Repeated start condition setup time	t <sub>(SUSTA)</sub>	4.7	-	0.6	-	μs	
Stop condition setup time	t <sub>(SUSTO)</sub>	4.0	-	0.6	-	μs	
Data hold time	t <sub>(HDDAT)</sub>	-	3450	-	900	ns	
Data setup time	t <sub>(SUDAT)</sub>	250	-	100	-	ns	
I <sup>2</sup> C clock (SCK) low period	t <sub>(LOW)</sub>	4.7	-	1.3	-	μs	
I <sup>2</sup> C clock (SCK) high period	t <sub>(HIGH)</sub>	4.0	-	0.6	-	μs	
Clock / data fall time	t <sub>f</sub>	-	300	-	300	ns	
Clock / data rise time	t <sub>r</sub>	-	1000	-	300	ns	



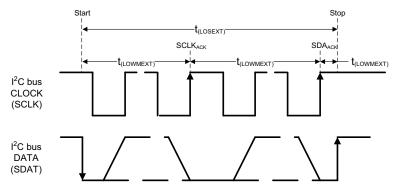


Fig. 2 - I<sup>2</sup>C Bus Timing Diagram

### PARAMETER TIMING INFORMATION

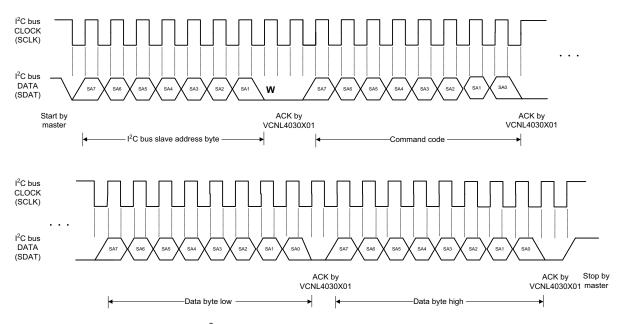


Fig. 3 - I<sup>2</sup>C Bus Timing for Sending Word Command Format

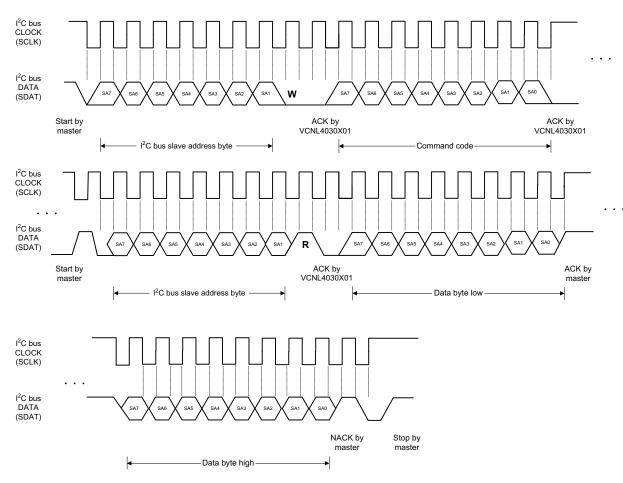


Fig. 4 - I<sup>2</sup>C Bus Timing for Receiving Word Command Format

### **TYPICAL PERFORMANCE CHARACTERISTICS** (T<sub>amb</sub> = 25 °C, unless otherwise specified)

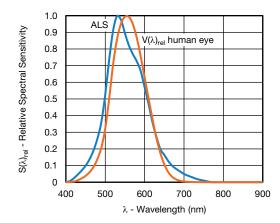


Fig. 5 - Normalized Spectral Response (ALS channel)

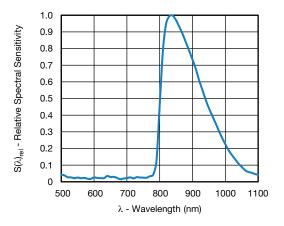


Fig. 6 - Normalized Spectral Response (PS channel)

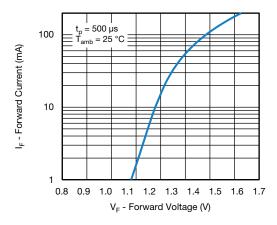


Fig. 7 - Forward Current  $I_F = f(V_F)$ for  $I_FD$ 

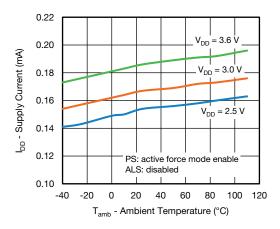


Fig. 8 - Supply Current vs. Ambient Temperature With Only PS = Active

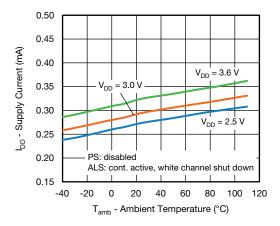


Fig. 9 - Supply Current vs. Ambient Temperature With Only ALS = Active

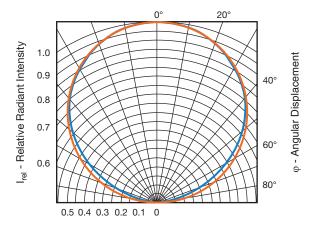
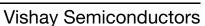


Fig. 10 - Relative Radiant Intensity Emitter vs.

Angular Displacement





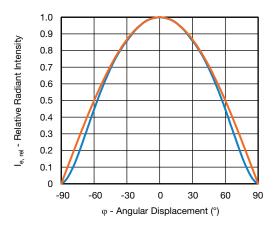


Fig. 11 - Relative Radiant Intensity Emitter vs.
Angular Displacement

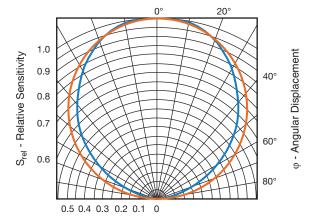


Fig. 12 - Relative Sensitivity vs. Angular Displacement (ALS)

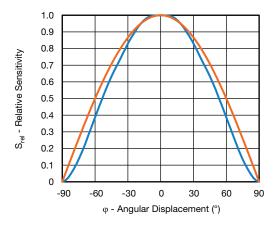


Fig. 13 - Relative Sensitivity vs. Angular Displacement

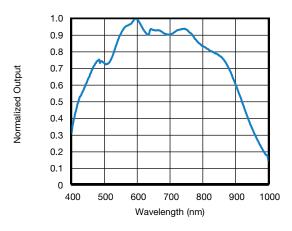


Fig. 14 - White Channel Spectral Response

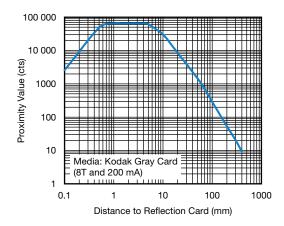


Fig. 15 - Proximity Value vs. Distance to Reflecting Card

### **APPLICATION INFORMATION**

### Pin Connection with the Host

VCNL4030X01 integrates proximity sensor, ambient light Sensor, and IRED all together with I<sup>2</sup>C interface. It is very easy for the baseband (CPU) to access PS and ALS output data via I<sup>2</sup>C interface without extra software algorithms. The hardware schematic is shown in the following diagram.

Two additional capacitors in the circuit can be used for the following purposes: (1) the 0.1  $\mu$ F capacitor near the V<sub>DD</sub> pin is used for power supply noise rejection, (2) the 2.2  $\mu$ F capacitor - connected to the anode - is used to prevent the IRED voltage from instantly dropping when the IRED is turned on, and (3) 2.2  $\mu$ C is suitable for the pull up resistor of I<sup>2</sup>C except for the 8.2  $\mu$ C applied on the INT pin.

### Note

· IR cathode and LDR: pins need to be connected together externally

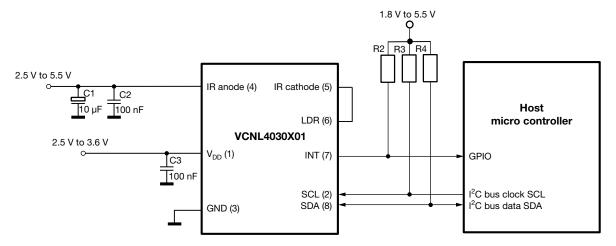


Fig. 16 - Circuitry with Two Separate Power Supply Sources

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### **Digital Interface**

VCNL4030X01 is available in four different salve addresses (0x60, 0x51, 0x40, and 0x41). Please refer to the table "Salve Address Options" at the beginning of the datasheet for an overview of the corresponding ordering codes. All operations can be controlled by the command register. The simple command structure helps users easily program the operation setting and latch the light data from VCNL4030X01. As Fig. 17 shows, VCNL4030X01's I<sup>2</sup>C command format is simple for read and write operations between VCNL4030X01 and the host. The white sections indicate host activity and the gray sections indicate VCNL4030X01's acknowledgement of the host access activity. Write word and read word protocol is suitable for accessing registers particularly for 16-bit data ALS and 12-bit / 16-bit PS data. Interrupt can be cleared by reading data out from register: INT\_Flag. All command codes should follow read word and write word protocols.

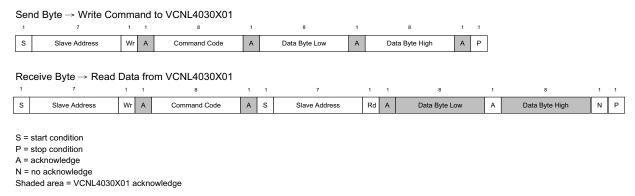


Fig. 17 - Write Word and Read Word Protocol

### **Function Description**

VCNL4030X01 applies a 16-bit high resolution ALS that provides the best ambient light sensing capability down to 0.004 lux/step which works well under a low transmittance lens design (dark lens). A flexible interrupt function of ALS (register: ALS\_CONF) is also supported. The INT signal will not be asserted by VCNL4030X01 if the ALS value is not over high INT threshold window level, or lower than low INT threshold window level of ALS. As long as the ALS INT is asserted, the host can read the data from VCNL4030X01. VCNL4030X01 detects different light sources such as fluorescent light, incandescent light, sunlight, and white LED with high accuracy ALS data output after detecting algorithm is implemented.

For proximity sensor function, VCNL4030X01 supports different kinds of mechanical designs to achieve the best proximity detection performance for any color of object with more flexibility. The basic PS function settings, such as duty ratio, integration time, interrupt, and PS enable / disable, and persistence, are handled by the register: PS\_CONF1. Duty ratio controls the PS response time. Integration time represents the duration of the energy being received. The interrupt is asserted when the PS detection levels over the high threshold level setting (register: PS\_THDH) or lower than low threshold (register: PS\_THDL). If the interrupt function is enabled, the host reads the PS output data from VCNL4030X01 that saves host loading from periodically reading PS data. More than that, INT flag (register: INT\_Flag) indicates the behavior of INT triggered under different conditions. PS persistence (PS\_PERS) sets up the PS INT asserted conditions as long as the PS output value continually exceeds the threshold level. The intelligent cancellation level can be set on register: PS\_CANC to reduce the cross talk phenomenon.

VCNL4030X01 also supports an easy use of proximity detection logic output mode that outputs just high / low levels saving loading from the host. Normal operation mode or proximity detection logic output mode can be selected on the register: PS\_MS. A smart persistence is provided to get faster PS response time and prevent false trigger for PS. Descriptions of each slave address operation are shown in table 1



COMMAND CODE	DATE BYTE LOW / HIGH	REGISTER NAME	R/W	DEFAULT VALUE	FUNCTION DESCRIPTION
0x00	L	ALS_CONF1	R/W	0x01	ALS integration time, ALS dynamic range, persistence, interrupt, and function enable / disable
	Н	ALS_CONF2	R/W	0x01	ALS sensitivity, white channel enable / disable
0x01	L	ALS_THDH_L	R/W	0x00	ALS high interrupt threshold LSB byte
UXUT	Н	ALS_THDH_M	R/W	0x00	ALS high interrupt threshold MSB byte
0x02	L	ALS_THDL_L	R/W	0x00	ALS low interrupt threshold LSB byte
0x02	Н	ALS_THDL_M	R/W	0x00	ALS low interrupt threshold MSB byte
0x03	L	PS_CONF1	R/W	0x01	PS duty ratio, integration time, persistence, and PS enable / disable
UXUS	Н	PS_CONF2	R/W	0x00	PS gain, PS output resolution, PS interrupt trigger
0x04	L	PS_CONF3	R/W	0x00	PS smart persistence, active force mode
UXU4	Н	PS_MS	R/W	0x00	LED current selection
0x05	L	PS_CANC_L	R/W	0x00	PS cancellation level setting
UXUS	Н	PS_CANC_M	R/W	0x00	PS cancellation level setting
000	L	PS_THDL_L	R/W	0x00	PS low interrupt threshold setting LSB byte
0x06	Н	PS_THDL_M	R/W	0x00	PS low interrupt threshold setting MSB byte
0x07	L	PS_THDH_L	R/W	0x00	PS high interrupt threshold setting LSB byte
UXU7	Н	PS_THDH_M	R/W	0x00	PS high interrupt threshold setting MSB byte
0,400	L	PS_Data_L	R	0x00	PS LSB output data
0x08	Н	PS_Data_M	R	0x00	PS MSB output data
000	L	Reserved	R	0x00	Reserved
0x09	Н	Reserved	R	0x00	Reserved
0x0A	L	Reserved	R	0x00	Reserved
UXUA	Н	Reserved	R	0x00	Reserved
000	L	ALS_Data_L	R	0x00	ALS LSB output data
0x0B	Н	ALS_Data_M	R	0x00	ALS MSB output data
0x0C	L	White_Data_L	R	0x00	White LSB output data
UXUC	Н	White_Data_M	R	0x00	White MSB output data
0,00	L	Reserved	R	0x00	Reserved
0x0D	Н	INT_Flag	R	0x00	ALS, PS interrupt flags, PS sunlight protection mode flag
	L	ID_L	R	0x80	Device ID LSB
0x0E	Н	ID_M	R	0x00	For version with 0x60 as device address; 0x10 for version with 0x51, 0x for version with 0x40 and 0x30 for version with 0x41 as device addres

### Note

### **Command Register Format**

VCNL4030X01 provides an 8-bit command register for ALS and PS controlling independently. The description of each command format is shown in following tables.

TABLE 2 - RE	TABLE 2 - REGISTER: ALS_CONF1 DESCRIPTION									
REGISTER NAME		COMMAND CODE: 0x00_L (0x00 DATA BYTE LOW)								
Command	Bit	7	6	5	4	3	2	1	0	
			COMMAND CODE: 0x00_L (0x00 DATA BYTE LOW)							
Command	Bit				Desci	ription				
ALS_IT	7:5		(0:0:0) = 50 ms; $(0:0:1) = 100$ ms; $(0:1:0) = 200$ ms; $(0:1:1) = 400$ ms; $(1:0:0)$ to $(1:1:1) = 800$ ms ALS integration time setting, longer integration time has higher sensitivity							
ALS_HD	4	0 = typical	dynamic rang	je x 1, 1 = typ	cal dynamic r	ange x 2				
ALS_PERS	3:2		(0:0) = 1, (0:1) = 2, (1:0) = 4, (1:1) = 8 ALS interrupt persistence setting							
ALS_INT_EN	1	0 = ALS interrupt disable, 1 = ALS interrupt enable								
ALS_SD	0	0 = ALS p	ower on, $1 = A$	LS shut down	, default = 1		•			

<sup>·</sup> All of reserved register are used for internal test. Please keep as default setting



TABLE 3 - RI	TABLE 3 - REGISTER: ALS_CONF2 DESCRIPTION					
		COMMAND CODE: 0x00_H (0x00 DATA BYTE HIGH)				
Command	Bit	Description				
Reserved	7:2	Default = (0 : 0 : 0 : 0 : 0)				
ALS_NS	1	0 = typical sensitivity x 2, 1 = typical sensitivity x 1				
WHITE_SD	0	0 = WHITE channel power on, 1 = WHITE channel shut down, default = 1				

TABLE 4 - REGISTER ALS_THDH_L AND ALS_THDH_M DESCRIPTION						
		COMMAND CODE: 0x01_L (0x01 DATA BYTE LOW) OR 0x01_H (0x01 DATA BYTE HIGH)				
Register	Bit	Description				
ALS_THDH_L	7:0	0x00 to 0xFF, ALS high interrupt threshold LSB byte				
ALS_THDH_M	7:0	0x00 to 0xFF, ALS high interrupt threshold MSB byte				

TABLE 5 - REGISTER: ALS_THDL_L AND ALS_THDL_M DESCRIPTION							
COMMAND CODE: 0x02_L (0x02 DATA BYTE LOW) AND 0x02_H (0x02 DATA BYTE HIGH)							
Register	Bit	Description					
ALS_THDL_L	7:0	0x00 to 0xFF, ALS low interrupt threshold LSB byte					
ALS_THDL_M	7:0	0x00 to 0xFF, ALS low interrupt threshold MSB byte					

TABLE 6 - REGISTER: PS_CONF1 DESCRIPTION								
REGISTER: PS_CONF1		COMMAND CODE: 0x03_L (0x03 DATA BYTE LOW)						
Command	Bit	Description						
PS_Duty	7:6	(0 : 0) = 1/40, (0 : 1) = 1/80, (1 : 0) = 1/160, (1 : 1) = 1/320 PS IRED on / off duty ratio setting						
PS_PERS	5:4	(0:0) = 1, (0:1) = 2, (1:0) = 3, (1:1) = 4 PS interrupt persistence setting						
PS_IT	3:1	(0:0:0) = 1T, (0:0:1) = 1.5T, (0:1:0) = 2T, (0:1:1) = 2.5T, (1:0:0) = 3T, (1:0:1) = 3.5T, (1:1:0) = 4T, (1:1:1) = 8T, PS integration time setting						
PS_SD	0	0 = PS power on, 1 = PS shut down, default = 1						

TABLE 7 - REGISTER: PS_CONF2 DESCRIPTION								
REGISTER: PS_	REGISTER: PS_CONF2 COMMAND CODE: 0x03_H (0x03 DATA BYTE HIGH)							
Command	Bit	Description						
Reserved	7:6	(0:0), reserved						
PS_Gain	5:4	(0:0) and (0:1) = two step mode, (1:0) = single mode x 8, (1:1) = single mode x 1						
PS_HD	3	0 = PS output is 12 bits, 1 = PS output is 16 bits						
PS_NS	2	0 = typical sensitivity (two step mode x 4), 1 = typical sensitivity mode (two step mode)						
PS_INT	1:0	(0 : 0) = interrupt disable, (0 : 1) = trigger by closing, (1 : 0)= trigger by away, (1 : 1) = trigger by closing and away						



TABLE 8 - REGISTER: PS_CONF3 DESCRIPTION								
REGISTER: PS_CO	NF3	COMMAND CODE: 0x04_L (0x04 DATA BYTE LOW)						
Command	Bit	Description						
LED_I_LOW	7	0 = disabled = normal current, 1 = enabled = 1/10 of normal current, with that the current is accordingly: 5 mA, 7.5 mA, 10 mA, 12 mA, 14 mA, 16 mA, 18 mA, 20 mA						
Reserved	6:5	(0:0)						
PS_SMART_PERS	4	0 = disable; 1 = enable PS smart persistence						
PS_AF	3	0 = active force mode disable (normal mode), 1 = active force mode enable						
PS_TRIG	2	0 = no PS active force mode trigger, 1 = trigger one time cycle VCNL4030X01 output one cycle data every time host writes in '1' to sensor. The state returns to '0' automatically.						
PS_MS	1	0 = proximity normal operation with interrupt function, 1 = proximity detection logic output mode enable						
PS_SC_EN	0	0 = turn off sunlight cancel; 1 = turn on sunlight cancel PS sunlight cancel function enable setting						

TABLE 9 - REGISTER: PS_MS DESCRIPTION							
REGISTER: PS_MS		COMMAND CODE: 0x04_H (0x04 DATA BYTE HIGH)					
Command	Bit	Description					
Reserved	7	0					
PS_SC_CUR	6:5	$(0:0) = 1 \times \text{typical sunlight cancel current}, (0:1) = 2 \times \text{typical sunlight cancel current}, (1:0) = 4 \times \text{typical sunlight cancel current}, (1:1) = 8 \times \text{typical sunlight cancel current}$					
PS_SP	4	0 = typical sunlight capability, 1 = 1.5 x typical sunlight capability					
PS_SPO	3	0 = output is 00h in sunlight protect mode, 1 = output is FFh in sunlight protect mode,					
LED_I	2:0	(0:0:0)=50 mA; $(0:0:1)=75$ mA; $(0:1:0)=100$ mA; $(0:1:1)=120$ mA $(1:0:0)=140$ mA; $(1:0:1)=160$ mA; $(1:1:0)=180$ mA; $(1:1:1)=200$ mA LED current selection setting					

TABLE 10 - REGISTER PS_CANC_L AND PS_CANC_M DESCRIPTION								
COMMAND CODE: 0x05_L (0x05 DATA BYTE LOW) AND 0x05_H (0x05 DATA BYTE HIGH)								
Register	Bit	Description						
PS_CANC_L	7:0	0x00 to 0xFF, PS cancellation level setting_LSB byte						
PS_CANC_M	7:0	0x00 to 0xFF, PS cancellation level setting_MSB byte						

TABLE 11 - REGISTER: PS_THDL_L AND PS_THDL_M DESCRIPTION								
	COMMAND CODE: 0x06_L (0x06 DATA BYTE LOW) AND 0x06_H (0x06 DATA BYTE HIGH)							
Register	Bit	Description						
PS_THDL_L	7:0	0x00 to 0xFF, PS interrupt low threshold setting_LSB byte						
PS_THDL_M	7:0	0x00 to 0xFF, PS interrupt low threshold setting_MSB byte						

TABLE 12 - REGISTER: PS_THDH_L AND PS_THDH_M DESCRIPTION								
	COMMAND CODE: 0x07_L (0x07 DATA BYTE LOW) AND 0x07_H (0x07 DATA BYTE HIGH)							
Register	Bit	Description						
PS_THDH_L	7:0	0x00 to 0xFF, PS interrupt high threshold setting_LSB byte						
PS_THDH_M	7:0	0x00 to 0xFF, PS interrupt high threshold setting_MSB byte						



TABLE 13 - R	EAD OUT REGISTER DESCR	IPTIO	N
Register	Command Code	Bit	Description
PS_Data_L	0x08_L (0x08 data byte low)	7:0	0x00 to 0xFF, PS1 LSB output data
PS_Data_M	0x08_H (0x08 data byte high)	7:0	0x00 to 0xFF, PS1 MSB output data
Reserved	0x09_L (0x09 data byte low)	7:0	Reserved
Reserved	0x09_H (0x09 data byte high)	7:0	Reserved
Reserved	0x0A_L (0x0A data byte low)	7:0	Reserved
Reserved	0x0A_H (0x0A data byte high)	7:0	Reserved
ALS_Data_L	0x0B_L (0x0B data byte low)	7:0	0x00 to 0xFF, ALS LSB output data
ALS_Data_M	0x0B_H (0x0B data byte high)	7:0	0x00 to 0xFF, ALS MSB output data
White_Data_L	0x0C_L (0x0C data byte low)	7:0	0x00 to 0xFF, white LSB output data
White_Data_M	0x0C_H (0x0C data byte high)	7:0	0x00 to 0xFF, white LSB output data
Reserved	0x0D_L (0x0D data byte low)	7:0	Default = 0x00
INT_Flag	0x0D_H (0x0D data byte high)	7 6 5 4 3 2 1 0	Reserved Reserved ALS_IF_L, ALS crossing low THD INT trigger event ALS_IF_H, ALS crossing high THD INT trigger event Reserved PS_SPFLAG, PS entering sunlight protection mode PS_IF_CLOSE, PS rises above PS_THDH INT trigger event PS_IF_AWAY, PS drops below PS_THDL INT trigger event
ID_L	0x0E_H (0x0E data byte low)	7:0	0x80
		7:6	(0:0)
ID_M	0x0E_H (0x0E data byte high)	5:4	(0:0) = slave address = 0x60 (7-bit) (0:1) = slave address = 0x51 (7-bit) (1:0) = slave address = 0x40 (7-bit) (1:1) = slave address = 0x41 (7-bit)
		3:0	Version code (0 : 0 : 0 : 0)

### **Adjustable Sampling Time**

VCNL4030X01's embedded LED driver drives the internal IRED with the "LDR" pin by a pulsed duty cycle. The IRED on / off duty ratio is programmable by I<sup>2</sup>C command at register: PS\_Duty which is related to the current consumption and PS response time. The higher the duty ratio adopted, the faster response time achieved with higher power consumption. For example, PS\_Duty = 1/320, peak IRED current = 100 mA, averaged current consumption is 100 mA/320 = 0.3125 mA.

### Initialization

VCNL4030X01 includes default values for each register. As long as power is on, it is ready to be controlled by host via I<sup>2</sup>C bus.



### **Threshold Window Setting**

ALS Threshold Window Setting (Applying ALS INT)

Register: ALS\_THDH\_L and ALS\_THDH\_M defines 16-bit ALS high threshold data for LSB byte and MSB byte. Register: ALS\_THDL\_L and ALS\_THDL\_M defines 16-bit ALS low threshold data for LSB byte and MSB byte. As long as ALS INT function is enabled, INT will be asserted once the ALS data exceeds ALS\_THDH or goes below ALS\_THDL. To easily define the threshold range, multiply the value of the resolution (lux/step) by the threshold level (refer to table 14).

TABLE 14 - ALS RESOLUTION AND MAXIMUM DETECTION RANGE									
AL	S_IT	SENSITIVITY	MAXIMUM DETECTION RANGE						
ALS_IT (7 : 5)	INTEGRATION TIME (typ.)	UNIT (lx/step)	UNIT (lx)						
(0, 0, 0)	50 ms	0.064	4192						
(0, 0, 1)	100 ms	0.032	2096						
(0, 1, 0)	200 ms	0.016	1048						
(0, 1, 1)	400 ms	0.008	524						
(1, 0, 0) to (1, 1, 1)	800 ms	0.004	262						

### · ALS HD and ALS NS

These two options enhance the dynamic range by a factor of two each. With this the sensitivity shown within table 14 will be reduced by the factor 2, but the maximum possible detection range will be doubled for both options. With this the max. detection range goes up to 4192  $lx \times 2 \times 2 = 16768 lx$ 

### ALS Persistence

The ALS INT is asserted as long as the ALS value is higher or lower than the threshold window when ALS\_PERS (1, 2, 4, 8 times) is set to one time. If ALS\_PERS is set to four times, then the ALS INT will not be asserted if the ALS value is not over (or lower) than the threshold window for four continued refresh times (integration time)

### • Programmable PS Threshold

VCNL4030X01 provides both high and low thresholds for PS (register: PS\_THDL, PS\_THDH)

### PS Persistence

The PS persistence function (PS\_PERS, 1, 2, 3, 4) helps to avoid false trigger of the PS INT. For example, if PS\_PERS = 3 times, the PS INT will not be asserted unless the PS value is greater than the PS threshold (PS\_THDH) value for three periods of time continuously

### • PS Active Force mode

An extreme power saving way to use PS is to apply PS active force (register: PS\_CONF3 command: PS\_FOR = 1) mode. Anytime host would like to read out just one of PS data, write in '1' at register: PS\_CONF3 command: PS\_FOR\_Trig. Without commands placed, there is no PS data output. VCNL4030X01 stays in standby mode constantly

### • PS detection object

Any color of object is detectable by VCNL4030X01

### **Data Access**

All of VCNL4030X01 command registers are readable. To access 16-bit high resolution ALS output data, it is suitable to use read word protocol to read out data by just one command at register: ALS\_DataL and ALS\_DataM. To represent the 16-bit data of ALS, it has to apply two bytes. One byte is for LSB, and the other byte is for MSB as shown in table 18. In terms of reading out 8-bit PS data, it is also very convenient to read PS at register: PS\_Data.

TABLE 15 - 16-BIT ALS DATA FORMAT																
		VCNL4030X01														
Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Register		ALS_DataM										ALS_	DataL			

### **Intelligent Cancellation**

VCNL4030X01 provides an intelligent cancellation method to reduce cross talk phenomenon for the proximity sensor. The output data will be subtracted by the input value on register: PS\_CANC.

### Interruption (INT)

VCNL4030X01 has ALS and PS interrupt feature operated by a single pin "INT". The purpose of the interrupt feature is to actively inform the host once INT has been asserted. With the interrupt function applied, the host does not need to be constantly pulling data from the sensor, but to read data from the sensor while receiving interrupt request from the sensor. As long as the host enables ALS interrupt (register: ALS\_INT\_EN) or PS interrupt (register: PS\_INT) function, the level of INT pin (pin 7) is pulled low once INT asserted. All registers are accessible even if INT is asserted.

ALS INT asserted when ALS value cross over the value set by register: ALS\_THDH or lower than the value set by register: ALS\_THDL. To effectively adopt PS INT function, it is recommended to use PS detection mechanism at register: PS\_INTT = 1 for the best PS detection performance which can be adjusted by high / low THD level of PS. PS INT trigger way is defined by register: PS\_INT.

### Interruption Flag

Register: INT\_Flag represents all of interrupt trigger status for ALS and PS. Any flag value changes from '0' to '1' state, the level of INT pin will be pulled low. As long as host reads INT\_Flag data, the bit will change from '1' state to '0' state after reading out, the INT level will be returned to high afterwards.

### PROXIMITY DETECTION LOGIC OUTPUT MODE

VCNL4030X01 provides a proximity detection logic output mode that uses INT pin (pin 7) as a proximity detection logic high / low output (register: PS\_MS). When this mode is selected, the PS output (pin 7; INT/P<sub>out</sub>) is pulled low when an object is closing to be detected and returned to level high when the object moves away. Register: PS\_THDH / PS\_THDL defines how sensitive PS detection is.

One thing to be stated is that whenever proximity detection logic mode applied, INT pin is only used as a logic high / low output. If host would like to use ALS with INT function, register: PS\_MS has to be selected to normal operation mode (PS\_MS = 0). Meanwhile, host has to simulate the GPIO pin as an INT pin function. If not, host needs to periodically reading the state of INT at this GPIO pin.

### PROXIMITY DETECTION HYSTERESIS

A PS detection hysteresis is important that keeps PS state in a certain range of detection distance. For example, PS INT asserts when PS value over PS\_THDH. Host switches off panel backlight and then clears INT. When PS value is less than PS\_THDL, host switches on panel backlight. Any PS value lower than PS\_THDH or higher than PS\_THDL, PS INT will not be asserted. Host does keep the same state.

### APPLICATION CIRCUIT BLOCK REFERENCE

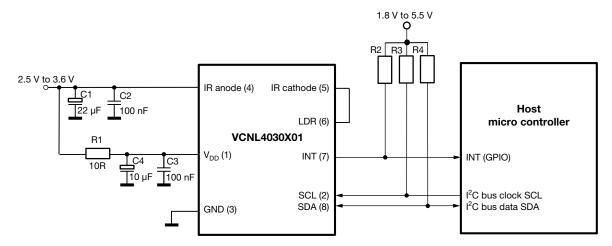
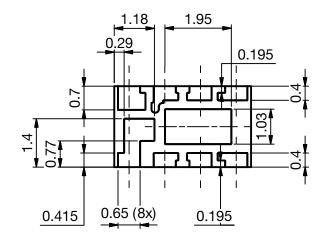
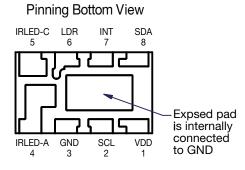


Fig. 18 - Circuitry with Just One Common Power Supply Source

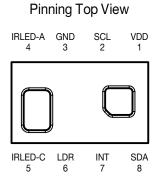


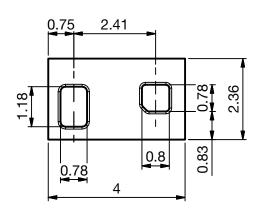
### **PACKAGE DIMENSIONS** in millimeters

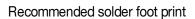


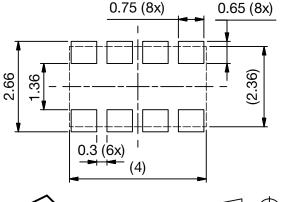


# 1.05 (3x)









Drawing No.: 6.550-5326.01-4 Issue: 2, 27.07.2020

Not indicated tolerances ± 0.1 mm



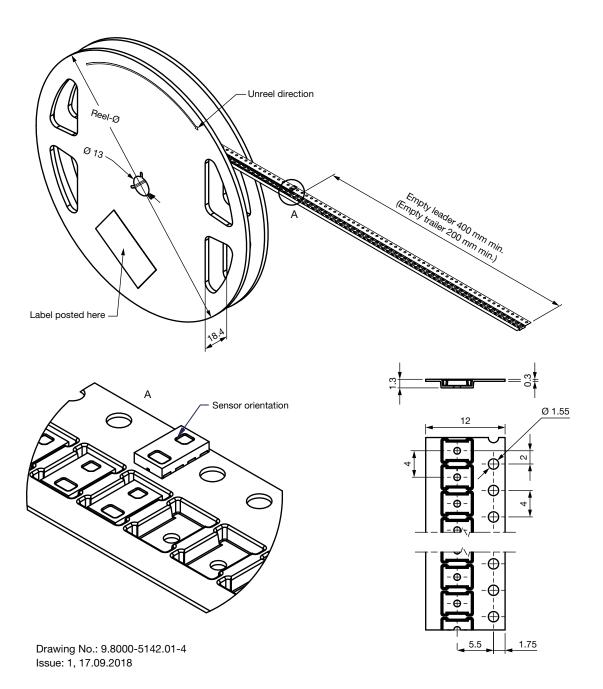


### TAPE AND REEL DIMENSIONS in millimeters

Reel-Size:

GS 08: Ø 180 mm  $\pm$  2 mm = 3300 pcs. GS 18: Ø 330 mm  $\pm$  2 mm = 13 000 pcs. Reel-design is representative for different types

Non tolerated dimensions ± 0.1 mm





### **SOLDER PROFILE**

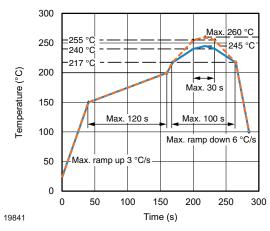


Fig. 19 - Lead (Pb)-free Reflow Solder Profile According to J-STD-020

### **DRYPACK**

Devices are packed in moisture barrier bags (MBB) to prevent the products from moisture absorption during transportation and storage. Each bag contains a desiccant.

### **FLOOR LIFE**

Floor life (time between soldering and removing from MBB) must not exceed the time indicated on MBB label:

Floor life: 168 h

Conditions:  $T_{amb}$  < 30 °C, RH < 60 %

Moisture sensitivity level 3, according to J-STD-020.

### **DRYING**

In case of moisture absorption devices should be baked before soldering. Conditions see J-STD-020 or label. Devices taped on reel dry using recommended conditions 192 h at 40  $^{\circ}$ C (+ 5  $^{\circ}$ C), RH < 5 %.

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