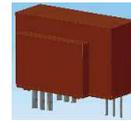


**K-No.:** 24578

**25 A Current Sensor**

For the electronic measurement of currents: DC, AC, pulsed, mixed ..., with a galvanic isolation between the primary circuit (high power) and the secondary circuit (electronic circuit)


**Date:** 20.01.2022

**Customer:** Standard type

**Customers Part no.:**
**Page** 1 **of** 5

**Description**

- Closed loop (compensation) Current Sensor with magnetic field probe
- Printed circuit board mounting
- Casing and materials UL-listed

**Characteristics**

- Excellent accuracy
- Very low offset current
- Very low temperature dependency and offset current drift
- Very low hysteresis of offset current
- Low response time
- Wide frequency bandwidth
- Compact design
- Reduced offset ripple

**Applications**

Mainly used for stationary operation in industrial applications:

- AC variable speed drives and servo motor drives
- Static converters for DC motor drives
- Battery supplied applications
- Switched Mode Power Supplies (SMPS)
- Power Supplies for welding applications
- Uninterruptable Power Supplies (UPS)

**Electrical data – Ratings**

$I_{PN}$	Primary nominal r.m.s. current	25	A
$R_M$	Measuring resistance $V_C = \pm 12V$	10 ... 200	$\Omega$
	$V_C = \pm 15V$	22 ... 400	$\Omega$
$I_{SN}$	Secondary nominal r.m.s. current	25	mA
$K_N$	Turns ratio	1...3 : 1000	

**Accuracy – Dynamic performance data**

		min.	typ.	max.	Unit
$I_{P,max}$	Max. measuring range				
	@ $V_C = \pm 12V, R_M = 10 \Omega (t_{max} = 10sec)$	$\pm 120$			A
	@ $V_C = \pm 15V, R_M = 22 \Omega (t_{max} = 10sec)$	$\pm 130$			A
X	Accuracy @ $I_{PN}, \theta_A = 25^\circ C$		0.1	0.5	%
$\epsilon_L$	Linearity			0.1	%
$I_0$	Offset current @ $I_P = 0A, \theta_A = 25^\circ C$		0.02	0.1	mA
$t_r$	Response time		500		ns
$t_{ra}$	Reaction time at $di/dt = 100 A/\mu s$		200		ns
$f_{BW}$	Frequency bandwidth	DC...200			kHz

**General data**

		min.	typ.	max.	Unit
$\vartheta_A$	Ambient operating temperature	-40		+85	$^\circ C$
$\vartheta_S$	Ambient storage temperature	-40		+90	$^\circ C$
m	Mass		12		g
$V_C$	Supply voltage	$\pm 11.4$	$\pm 12$ or $\pm 15$	$\pm 15.75$	V
$I_C$	Current consumption		18,5		mA
$S_{clear}$	clearance (component without solder pad)	10.2			mm
$S_{creep}$	creepage (component without solder pad)	10.2			mm
$U_{sys}$	System voltage			600	$V_{RMS}$
$U_{AC}$	Working voltage			1020	$V_{RMS}$
$U_{PD}$	Rated discharge voltage			1400	$V_S$
	Max. potential difference acc. to UL 508			600	$V_{AC}$

\*Constructed and manufactured and tested in accordance with EN 61800-5-1:2007 (Pin 1 - 6 to Pin 7 – 9)

Reinforced insulation, Insulation material group 1, Pollution degree 2, overvoltage category 3

Date	Name	Issue	Amendment
20.01.2022	NSch.	82	Applicable document on sheet 4 changed. „The color of the plastic material... added. Minor change
17.08.15	DJ	82	Marking of item-no, value of primary resistance in page 2 (possibilities of wiring).changed. CN-15-420

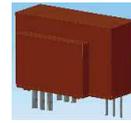
  

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isolation between the primary circuit  
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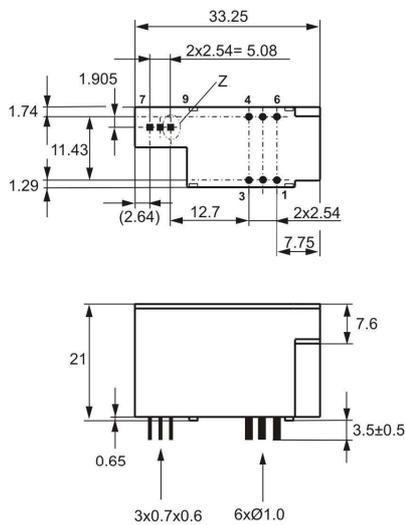
Customer: Standard type

Customers Part no.:

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**Mechanical outline (mm):**

General tolerances DIN ISO 2768-c



Tolerances of grid distance  
±0,2mm

Detail  
Z

Marking

Connections:

1...6: Ø 1.0 mm  
7...9: 0.6x0.7 mm

Marking:

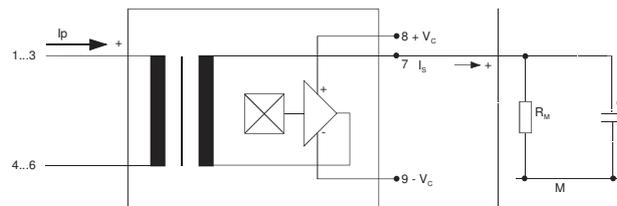
**RU** US  
4646-X400  
F DC

Explanation:

DC = Date Code  
F = Factory

Current direction: A positive output current appears at point I<sub>S</sub>, by primary current in direction of the arrow.

**Schematic diagram**



**Possibilities of wiring for V<sub>C</sub> = ±15V** (@ θ<sub>A</sub> = 85°C, R<sub>M</sub> = 22 Ω)

primary windings N <sub>P</sub>	primary current RMS I <sub>P</sub> [A]	primary current maximal I <sub>P,max</sub> [A]	output current RMS I <sub>S</sub> (I <sub>P</sub> ) [mA]	turns ratio K <sub>N</sub>	primary resistance R <sub>P</sub> [mΩ]	wiring
1	25	130	25	1:1000	0.3	
2	10	65	20	2:1000	1.35	
3	8	43	24	3:1000	2.4	

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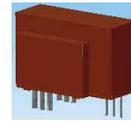
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**Electrical Data** (investigate by a type checking)

		min.	typ.	max.	Unit
$V_{Ctot}$	Maximum supply voltage (without function) $\pm 15.75 \dots \pm 18 \text{ V}$ : for 1s per hour			$\pm 18$	V
$R_S$	Secondary coil resistance @ $\theta_A=85^\circ\text{C}$			88	$\Omega$
$R_p$	Primary coil resistance per turn @ $T_A=25^\circ\text{C}$			1	m $\Omega$
$X_{Ti}$	Temperature drift of X @ $\vartheta_A = -40 \dots +85^\circ\text{C}$			0.1	%
$I_{0ges}$	Offset current (including $I_0, I_{0t}, I_{0T}$ )			0.15	mA
$I_{0t}$	Long term drift Offset current $I_0$		0.05		mA
$I_{0T}$	Offset current temperature drift $I_0$ @ $\vartheta_A = -40 \dots +85^\circ\text{C}$		0.05		mA
$I_{0H}$	Hysteresis current @ $I_P=0$ (caused by primary current $3 \times I_{PN}$ )		0.04	0.1	mA
$\Delta I_0/\Delta V_C$	Supply voltage rejection ratio			0.01	mA/V
$i_{0ss}$	Offset ripple (with 1 MHz- filter first order)			0,15	mA
$i_{0ss}$	Offset ripple (with 100 kHz- filter first order)		0.03	0.05	mA
$i_{0ss}$	Offset ripple (with 20 kHz- filter first order)		0.007	0.015	mA
$C_k$	Maximum possible coupling capacity (primary – secondary)		4		pF
	Mechanical Stress according to M3209/3 Settings: 10 – 2000 Hz, 1 min/Oktave, 2 hours			10g	

**Inspection** (Measurement after temperature balance of the samples at room temperature)

$K_N(N_1/N_2)$	(V)	M3011/6	Transformation ratio ( $I_P=3*10A, 40-80 \text{ Hz}$ )	$1 \dots 3 : 1000 \pm 0.5 \%$	
$I_0$	(V)	M3226	Offset current	$< 0.1$	mA
$V_{P,eff}$	(V)	M3014	Test voltage, rms, 1s Pin 1 - 6 to Pin 7 - 9	2.5	kV
$V_e$	(AQL 1/S4)		Partial discharge voltage acc. M3024 (RMS) with $V_{vor}$ (RMS)	1300 1625	V V

**Type Testing** (Pin 1 - 6 to Pin 7 – 9)

Designed according standard EN 61800-5-1:2007 with insulation material group 1

$V_w$	HV transient test according (to M3064) (1.2 $\mu\text{s}$ / 50 $\mu\text{s}$ -wave form)			8	kV
$V_d$	Testing voltage acc. M3014 (RMS)		(5 s)	5	kV
$V_e$	Partial discharge voltage acc. M3024 (RMS) with $V_{vor}$ (RMS)			1500 1875	V V

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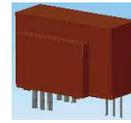
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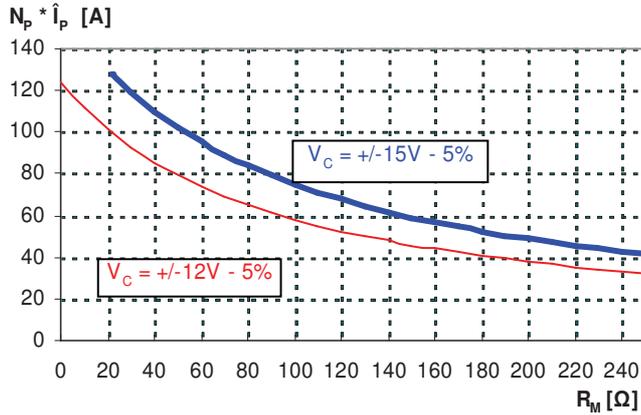
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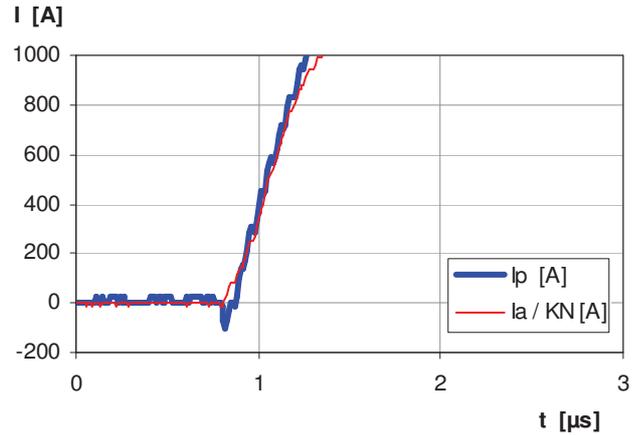
**Limit curve of measurable current  $\hat{I}_p(R_M)$**

@ ambient temperature  $T_A \leq 85^\circ\text{C}$



**Maximum measuring range ( $\mu\text{s}$ -range)**

Output current behaviour of a 3kA current pulse @  $V_c = \pm 15V$  und  $R_M = 25\Omega$



Fast increasing currents (higher than the specified  $I_{p,max}$ ), e.g. in case of a short circuit, can be transmitted because the currents are transformed directly.

The offset ripple can be reduced by an external low pass. Simplest solution is a passive low pass filter of 1st order with

$$f_g = \frac{1}{2\pi \cdot R_M \cdot C_a}$$

In this case is the response time enlarged. It is calculated from:

$$t'_r \leq t_r + 2.5R_M \cdot C_a$$

**Applicable documents**

Constructed and manufactured and tested in accordance with EN 61800.  
 Temperature of the primary conductor should not exceed 100°C.  
 Further standards UL 508 ; file E317483, category NMTR2 / NMTR8  
 „The color of the plastic material is not specified and the current sensor can be supplied in different colors (e.g. brown, black, white, natural). This has no effect on the specifications or UL approval.”

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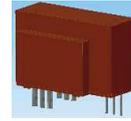
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$I_{0H}$ : Zero variation of  $I_0$  after overloading with a DC of tenfold the rated value ( $R_M = R_{MN}$ )

$I_{0t}$ : Long term drift of  $I_0$  after 100 temperature cycles in the range -40 bis 85 °C.

$t_r$ : Response time (describe the dynamic performance for the specified measurement range), measured as delay time at  $I_P = 0.9 \cdot I_{Pmax}$  between a rectangular current and the output current.

$\Delta t (I_{Pmax})$ : Delay time (describe the dynamic performance for the rapid current pulse rate e.g short circuit current) measured between  $I_{Pmax}$  and the output current  $i_a$  with a primary current rise of  $di/dt = 100 \text{ A}/\mu\text{s}$ .

$X_{ges}(I_{PN})$ : The sum of all possible errors over the temperature range by measuring a current  $I_{PN}$ :

$$X_{ges} = 100 \cdot \left| \frac{I_S(I_{PN})}{K_N \cdot I_{SN}} - 1 \right| \%$$

$X$ : Permissible measurement error in the final inspection at RT, defined by

$$X = 100 \cdot \left| \frac{I_{SB}}{I_{SN}} - 1 \right| \%$$

where  $I_{SB}$  is the output DC value of an input DC current of the same magnitude as the (positive) rated current ( $I_0 = 0$ )

$X_{Ti}$ : Temperature drift of the rated value orientated output term.  $I_{SN}$  (cf. Notes on F<sub>i</sub>) in a specified temperature range, obtained by:

$$X_{Ti} = 100 \cdot \left| \frac{I_{SB}(\theta_{A2}) - I_{SB}(\theta_{A1})}{I_{SN}} \right| \%$$

( $I_{SB}$ : Secondary current  $\theta_{A1}$  or  $\theta_{A2}$ )

$\epsilon_L$ : Linearity fault defined by  $\epsilon_L = 100 \cdot \left| \frac{I_P}{I_{PN}} - \frac{I_{Sx}}{I_{SN}} \right| \%$

Where  $I_P$  is any input DC and  $I_{Sx}$  the corresponding output term.

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