



- Magnetoresisitve sensor technology
- Linear signal output
- Over increased field range
- Very low hysteresis
- High sensititvity
- Substitutes KMZ10C / NXP

#### DESCRIPTION

Due to its featured properties - high sensitivity and almost no hysteresis – the **KMZ10CM** sensor is used in a wide range of applications, like magnetic field measurement, revolution counters, proximity detecting, and position measurement.

#### **FEATURES**

## APPLICATIONS

- Wheatsone bridge
- Passive output signal
- Linear signal output proportional to magnetic field strength
- 4 lead package for measurement of z direction

Detection of small magnetic fields, as in:

- Contactless switch
- Contactless displacement measurement
- Current measurement Polarity detection of small magnetic fields



### PERFORMANCE SPECS

Parameter	Symbol	Condition	Min	Тур	Мах	Unit
A. Operating Limits 1)				·		
max. supply voltage	V <sub>CC,max</sub>				10	V
operating temperature	T <sub>op</sub>		-40		+150	°C
storage temperature	T <sub>st</sub>		-65		+165	°C
B. Sensor Specificatior	ns (T = 25 °C	; H <sub>X</sub> = 3 kA/m)				
supply voltage	V <sub>cc</sub>			5	10	V
bridge resistance	R <sub>b</sub>		1000	1400	1800	Ω
offset voltage	V <sub>OFF</sub> /V <sub>CC</sub>	H <sub>x</sub> =0	-1.5	0	+1.5	mV/V
sensitivity	S	note 2	1	1.2	2	(mV/V)/(kA/m)
hysteresis	V <sub>HYST</sub>	note 3	-	-	100	μV/V
linearity deviation	FL	note 4	-	-	6.5	%
C. Sensor Specification	ns (T <sub>low</sub> = 30	°C ; T <sub>high</sub> = 80 °C ;	H <sub>X</sub> = 3 kA/m	; V <sub>CC</sub> = 5 V)		
TC of sensitivity	TCS	note 5	-	- 0.35	-	%/K
TC of resistance	TCBR	note 6	-	+ 0.45	-	%/K
TC of offset	TCV <sub>off</sub>	note 7,8, H <sub>x</sub> =0	-4	0	+4	μV/V/K

- 1) Stress above one or more of the limiting values may cause permanent damage to the device. Exposure to limiting values for extended periods may affect device reliability.
- 2) The sensitivity is defined as the average slope of characteristic between Hy=0 and 6 kA/m and Hx=3kA/m:

$$S = \frac{V_0(H_y = 6kA/m) - V_0(H_y = 0)}{6*V_{CC}}$$

 Hysteresis is defined as the difference between offset voltages measured without Hy-field after premagnetization by negative and positive Hy=±6 kA/m field:

$$V_{HYST} = V_0(H_1 \to H_0) - V_0(-H_1 \to H_0); H_0 = 0; H_1 = 6\frac{kA}{m}; H_X = 3\frac{kA}{m}; V_{CC} = 5V$$

4) The linearity error is the deviation of output voltage measured at Hy=3 kA/m from the average of Hy=0 and 6 kA/moutput voltages, expressed as percentage of the output voltage difference measured between 0 and 6 kA/m:

$$FL = \left| \frac{1}{2} - \frac{V_0(H_y = 3kA/m) - V_0(H_y = 0)}{V_0(H_y = 6kA/m) - V_0(H_y = 0)} \right| *100\%$$

5) The temperature coefficient of sensitivity is defined as the percentage change of the sensitivity per K referred to the value at  $T_1 = -25$  °C;  $T_2$ = operating temperature:

$$TCS = \frac{1}{(T_2 - T_1)} * \frac{S(T_2) - S(T_1)}{S(T_1)} * 100\%$$

6) The temperature coefficient of resistance is defined as the percentage change of the resistance per K referred to the value at  $T_1 = -25$  °C;  $T_2$ = operating temperature:

**measuren** 

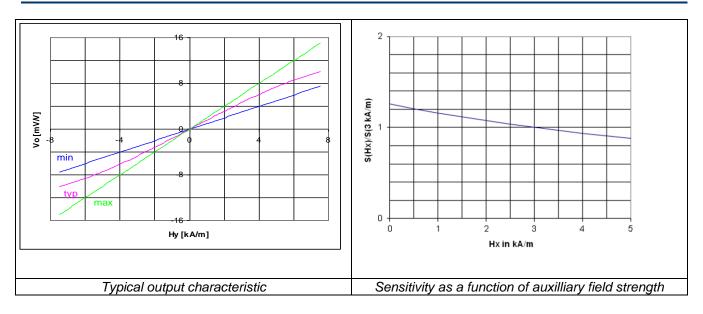
$$TCBR = \frac{1}{(T_2 - T_1)} * \frac{R(T_2) - R(T_1)}{R(T_1)} * 100\%$$

7) Temperature coefficient of offset voltage is defined as the voltage change per K expressed in µV/V:

$$TCV_{off} = \frac{V_{off}(T_2) - V_{off}(T_1)}{(T_2 - T_1)}$$

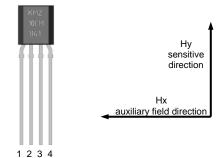
8) Linear behaviour assumed

#### **TYPICAL PERFORMANCE CURVES**



#### **FUNCTION**

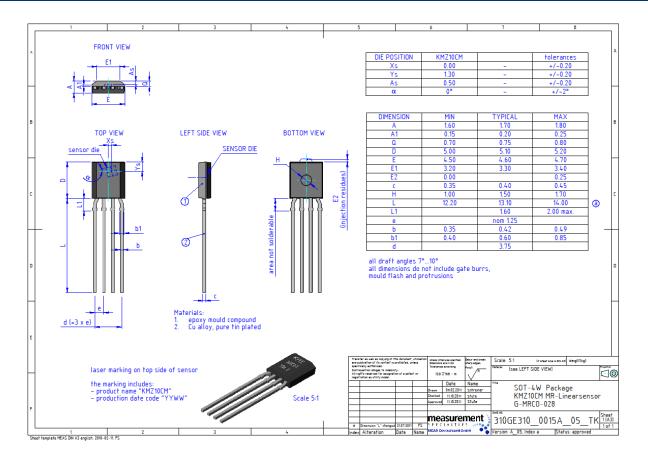
#### **TERMINAL CONNECTIONS**



Pin	Symbol	Function
1	+Vo	positive output voltage
2	GND	negative supply voltage
3	-Vo	negative output voltage
4	+Vcc	positive supply voltage



### **BLOCK DIAGRAM**



#### **ORDERING CODE**

Product	Description	Part number
KMZ10CM	KMZ10 CM Linear Field Sensor	G-MRCO-028



## **TECHNICAL CONTACT INFORMATION**

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