

OPERATING INSTRUCTIONS

Dual Channel Hall Effect Speed Sensor with Differential Output



DSD 1615.73 xHW

Product ID

	Type #	Product #	Drawing #	
	DSD 1615.73 SHW-F150F	3742612298	125348	
	DSD 1615.73 S3HW-F100F	3742614311	129192	
	DSD 1615.73 SHW-F200F	20005051-00	133271	
	DSD 1615.73 SHW-F300F	20001408-00	131047	
	DSD 1620.73 S4HW-C300F	20006053-00	133481	
		·		
General				
Function	The speed sensors DSD 16xx.73 wheel, for generating two phase- proportional to rotary speeds. Th generation is guaranteed down to The monitoring elements consist effect semiconductors. The intern sensor must be oriented. The se Sensor types with DSD16xx.73 S sensor housing.	shifted differential so ey have a static beha o a speed correspond of two magnetically nal dual channel stru- nsor has a flange for	uare wave signals aviour, so that pulse ding to a frequency of 0 Hz biased differential Hall cture requires that the proper installation.	
Technical data				
Supply voltage	9 VDC to 30 VDC, protected against transient overvoltages and reverse polarity			
Nominal supply voltage	15 V			
Current consumption	Max. 20 mA (without load)			
Signal output	 2 phase shifted square wave s gear wheel: minimal phase sh between output 1 (S1) and ou the signal S1. The signal /S2 i Push-pull outputs: Imax = ± 30 Output voltage HI (for I Output voltage LO (for 	$\begin{array}{l} \mbox{iff of 20^{\circ} for gear of t} \\ \mbox{tput 2 (S2). The sign} \\ \mbox{is digitally inverted to} \\ \mbox{mA} \\ \mbox{I} = I_{max}): \\ \mbox{U}_{HI} > U_{s} \\ \mbox{I} = I_{max}): \\ \mbox{U}_{LO} < 1. \end{array}$	he specified module al /S1 is digitally inverted to the signal S2. _{upply} - 1.5 V 5 V	
	 The output stages are current temperature shutdown mecha Thermal shutdown three Thermal re-start thresh Hysteresis: 	nism: eshold: 145 nold: 135	175°C	
Frequency range	0 Hz 20 kHz			

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		C	DPERA	TING INSTRUCTION		
Electrostatic discharge according to IEC 61000-4-2 • Up to \pm 8 kV air discharge • Up to \pm 6 kV contact discharge Radiated electromagnetic field according to IEC 61000-4-3 • Up to 30 V/m, 80% AM, 1 kHz in the range of 80 MHz 1000 MHz • Up to 10 V/m, 80% AM, 1 kHz in the range of 1400 MHz 2500 MHz Electrical fast transients/bursts according to IEC 61000-4-4 direct coupling • Up to \pm 2 kV peak, 5/50 ns, 5 kHz Surges according to IEC 61000-4-5 • \pm 2 kV 1.2/50 µs (common mode) • \pm 1 kV 1.2/50 µs (differential mode) Radio frequency injected current according to IEC 61000-4-6 • Up to 10 V, 80% AM, 1 kHz, 1000 ms in the range of 0.15 MHz 80 MHz with 50 Ω load and 560 Ω pull up resistance Power frequency magnetic field according to IEC 61000-4-8 • 300 A/m (1 min) tested with 16 2/3 Hz, 50 Hz in each axis • 1000 A/m (3 s) tested with 16 2/3 Hz, 50 Hz, 60 Hz in each axis Radiated emission (at 3 m) • 30 MHz230 MHz: 50 dB mV/m						
splashing water, oil, co components potted in	onducting chemical	carbon- or ferrous of and age proof synth	dust and	d salt mist. Electronic		
			t #] C	able length [mm]		
				1500		
				1000		
		8242611785		2000		
		8242611785		3000		
DSD 1620.73 S4HW	/-C300F	8242611785		3000		
Jaquet cable type 8242611785	Tyco Ra Max. op	aychem Zerohal 1000 erating temperature:				
				0 / 1/ 0000		
Toothed wheel of a magnetically permeable material (e.g. Steel 1.0036) Optimal performance with Involute gear Tooth width ≥ 10 mm Side offset < 1.0 mm Eccentricity < 0.2 mm Sensors are optimized to operate with an involute gear of a module 1.5 						
Module 1 0.5 0.7 Module 1.5 0.5 1.3 Module >=2 0.5 1.5						
			 Insulation between electronics and housing: 700 VDC, > 100 MΩ Insulation between shield and housing: 700 VDC, > 100 MΩ 			
		•				
		•				
Insulation between	shield ar	nd housing:	700 V			
-	• Up to \pm 8 kV air dis • Up to \pm 6 kV contac Radiated electromagn • Up to 30 V/m, 80% • Up to 10 V/m, 80% Electrical fast transien • Up to \pm 2 kV peak, Surges according to IB • \pm 2 kV 1.2/50 µs (cr • \pm 1 kV 1.2/50 µs (cr • \pm 1 kV 1.2/50 µs (dr Radio frequency inject • Up to 10 V, 80% AI with 50 Ω load and Power frequency mag • 300 A/m (1 min) tes • 1000 A/m (3 s) test Radiated emission (at • 30 MHz 230 MH • 230 MHz 1 GH Stainless steel 1.4305 splashing water, oil, cr components potted in Dimensions according Type # DSD 1615.73 SHW- DSD 1615.73 SHW- SHW- DSD 1615.73 SHW- DSD 1615.73 SHW- DSD 1615.7	Electrostatic discharge accordin • Up to \pm 8 kV air discharge • Up to \pm 6 kV contact dischar Radiated electromagnetic field • Up to 30 V/m, 80% AM, 1 kH • Up to 10 V/m, 80% AM, 1 kH Electrical fast transients/bursts • Up to \pm 2 kV peak, 5/50 ns, 3 Surges according to IEC 61000 • \pm 2 kV 1.2/50 μ s (common m • \pm 1 kV 1.2/50 μ s (differential Radio frequency injected current • Up to 10 V, 80% AM, 1 kHz, with 50 Ω load and 560 Ω put Power frequency magnetic field • 300 A/m (1 min) tested with • 1000 A/m (3 s) tested with 1 Radiated emission (at 3 m) • 30 MHz 230 MHz: 50 d • 230 MHz 1 GHz: 57 d Stainless steel 1.4305, front side splashing water, oil, conducting components potted in chemical Dimensions according to the dr Type # DSD 1615.73 SHW-F150F DSD 1615.73 SHW-F100F DSD 1615.73 SHW-F200F DSD 1615.73 SHW-F300F DSD 1615.73 SHW-F300F DSD 1615.73 SHW-F300F DSD 1620.73 S4HW-C300F Toothed wheel of a magnetical Optimal performance with • Involute gear • Tooth width \ge 10 mm • Side offset < 1.0 mm	Electrostatic discharge according to IEC 61000-4-2 • Up to ± 8 kV air discharge Radiated electromagnetic field according to IEC 610 • Up to 30 V/m, 80% AM, 1 kHz in the range of 80 • Up to 10 V/m, 80% AM, 1 kHz in the range of 14 Electrical fast transients/bursts according to IEC 610 • Up to ± 2 kV peak, 5/50 ns, 5 kHz Surges according to IEC 61000-4-5 • ± 2 kV 1.2/50 µs (common mode) • ± 1 kV 1.2/50 µs (differential mode) Radio frequency injected current according to IEC 6 • Up to 10 V, 80% AM, 1 kHz, 1000 ms in the range with 50 Ω load and 560 Ω pull up resistance Power frequency magnetic field according to IEC 6 • 300 A/m (1 min) tested with 16 2/3 Hz, 50 Hz, 60 Radiated emission (at 3 m) • 30 MHz 230 MHz: 50 dB mV/m • 230 MHz 1 GHz: 57 dB mV/m Stainless steel 1.4305, front side sealed hermetical splashing water, oil, conducting carbon- or ferrous of components potted in chemical and age proof syntt Dimensions according to the drawing. Type # Cable [Jaquet par DSD 1615.73 SHW-F130F B242611785 DSD 1615.73 SHW-F300F B242611785 DSD 1615.73 SHW-F300F B242611785 Tyco Raychem Zerohal 100 Max. operating temperature (20'000h) Toothed wheel of a magnetically permeable material optima	OPERA Electrostatic discharge according to IEC 61000-4-2 • Up to ± 8 kV air discharge Radiated electromagnetic field according to IEC 61000-4-3 • Up to 30 V/m, 80% AM, 1 kHz in the range of 80 MHz • Up to 10 V/m, 80% AM, 1 kHz in the range of 1400 MHz Electrical fast transients/bursts according to IEC 61000-4-4 • Up to ± 2 kV peak, 5/50 ns, 5 kHz Surges according to IEC 61000-4-5 • ± 2 kV 1.2/50 µs (common mode) • ± 1 kV 1.2/50 µs (differential mode) Radio frequency injected current according to IEC 61000-4 • Up to 10 V, 80% AM, 1 kHz, 1000 ms in the range of 0.1 with 50 Ω load and 560 Ω pull up resistance Power frequency magnetic field according to IEC 61000-4 • 300 A/m (1 min) tested with 16 2/3 Hz, 50 Hz, 60 Hz in each ax • 1000 A/m (3 s) tested with 16 2/3 Hz, 50 Hz, 60 Hz in each ax • 300 MHz230 MHz: 50 dB mV/m • 230 MHz 1 GHz: 57 dB mV/m Stainless steel 1.4305, front side sealed hermetically and r splashing water, oil, conducting carbon- or ferrous dust and components potted in chemical and age proof synthetic rest DSD 1615.73 SHW-F100F 8242611785 DSD 1615.73 SHW-F200F 8242611785 DSD 16		

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Operating temperature	 Sensor head: Continuous operation: Short term exposure according to test report T120541: Cable: according to cable specification (see above) 	-40°C +125°C down to -60°C
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Safety	 All mechanical installations must be carried out by an expert. General safety requirements have to be met. The sensors must be connected according to the sensor drawing. Sensor wires are susceptible to radiated noise. Therefore, the following points have to be considered when connecting a sensor: The sensor wires must be positioned as far as possible from large electrical machines. They must not run in the vicinity of power cables. It is advantageous to keep the distance between sensor and instrument as short as possible. If the signal requirements are met, the sensor cable may be lengthened via a terminal box in accordance with EN 60529. 				
Connection					
Installation	The sensor has to be aligned to the pole wheel according to the sensor drawing. A deviation in positioning may affect the performance and decrease the noise immunity of the sensor. Within the air gap specified the amplitude of the output signals is not influenced by the air gap. The sensor should be positioned such that the center of the sensor face corresponds to the middle of a pole wheel tooth. For larger teeth a misalignment of the sensor center to the middle of a tooth is permissible, however, the center of the sensor must be at a minimum of 4mm from either edge of the pole wheel under all operating conditions. A solid and vibration free mounting of the sensor is important. Sensor vibration relative to the pole wheel may add spurious noise to the signal. The sensors are insensitive to oil, grease etc. and can be installed in arduous conditions.				
Operation	The sensor is designed for normal use in its dedicated environment. The manufacturer cannot take responsibility for any abnormal use that might lead to a reduced lifetime of the sensor.				
Maintenance	Product cannot be repaired.				
Transport	Product must be handled with care to prevent damage of the front face.				
Storage	Product must be stored in dry conditions. The storage temperature corresponds to the operation temperature.				
Disposal	Product must be disposed of properly; it must not be disposed as domestic waste.				

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