

AFM60A-TDKK002048

AFS/AFM60 SSI

MOTOR FEEDBACK SYSTEMS ROTARY INCREMENTAL



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Ordering information

Туре	Part no.
AFM60A-TDKK002048	1100794

Illustration may differ

Other models and accessories → www.sick.com/AFS_AFM60_SSI



Detailed technical data

Performance

Number of steps per revolution (max. resolution)	2,048 (11 bit)
Number of revolutions	4,096 (12 bit)
Max. resolution (number of steps per revolution x number of revolutions)	11 bit x 12 bit (2,048 x 4,096)
Error limits G	0.03° ¹⁾
Repeatability standard deviation σ_{r}	0.002° ²⁾

¹⁾ In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

Interfaces

Communication interface	SSI
Communication Interface detail	SSI + Sin/Cos
Initialization time	50 ms ¹⁾
Position forming time	< 1 µs
Code type	Gray
Code sequence parameter adjustable	CW/CCW (V/R) parameter adjustable
Clock frequency	≤ 2 MHz ²⁾
Set (electronic adjustment)	H-active (L = $0 - 3 \text{ V}$, H = $4,0 - U_s \text{ V}$)
CW/CCW (counting sequence when turning)	L-active (L = 0 - 1,5 V, H = 2,0 - Us V)
Sine/cosine periods per revolution	1,024
Output frequency	≤ 200 kHz
Load resistance	≥ 120 Ω
Signal before differential generation	$0.5 V_{pp}$, ± 20 %, 120 Ω
Signal offset before differential generation	2.5 V ± 10 %
Signal after differential generation	$1 V_{pp}$, $\pm 20 \%$

 $^{^{1)}\,\}mathrm{Valid}$ positional data can be read once this time has elapsed.

 $^{^{2)}}$ In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

²⁾ Minimum, LOW level (Clock +): 250 ns.

Electrical data

Connection type	Cable, 12-wire, radial, 1.5 m
Supply voltage	4.5 32 V
Power consumption	≤ 0.7 W (without load)
Reverse polarity protection	✓
MTTFd: mean time to dangerous failure	250 years (EN ISO 13849-1) ¹⁾

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

Mechanical design	Through hollow shaft
Shaft diameter	10 mm
Weight	0.2 kg ¹⁾
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	< 0.8 Ncm (+20 °C)
Operating torque	< 0.6 Ncm (+20 °C)
Permissible movement static	± 0.5 mm (axial) ± 0.3 mm (radial)
Permissible movement dynamic	± 0.1 mm (axial) ± 0.05 mm (radial)
Operating speed	≤ 9,000 min ^{-1 2)}
Moment of inertia of the rotor	40 gcm ²
Bearing lifetime	3.0 x 10^9 revolutions
Angular acceleration	≤ 500,000 rad/s²

¹⁾ Based on devices with male connector.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3 ¹⁾
Enclosure rating	IP65, shaft side (IEC 60529) IP67, housing side (IEC 60529) ²⁾
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C +100 °C ³⁾
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	60 g, 6 ms (EN 60068-2-27)
Resistance to vibration	20 g, 10 Hz 2,000 Hz (EN 60068-2-6)

 $^{^{1)}}$ EMC according to the standards quoted is achieved if shielded cables are used.

Classifications

ECLASS 5.0	27270502
ECLASS 5.1.4	27270502

 $^{^{2)}}$ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

 $^{^{\}rm 2)}$ For devices with male connector: with mounted mating connector.

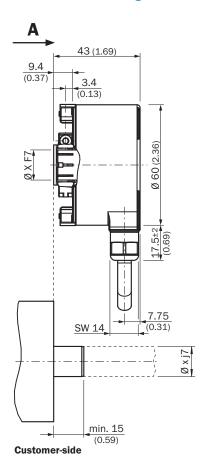
³⁾ Stationary position of the cable.

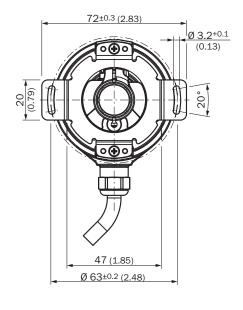
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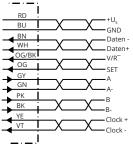
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270502
ECLASS 8.0	27270502
ECLASS 8.1	27270502
ECLASS 9.0	27270502
ECLASS 10.0	27270502
ECLASS 11.0	27270502
ECLASS 12.0	27270502
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))



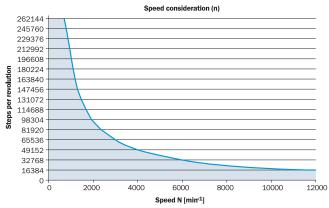


PIN assignment



PIN	Wire colors (cable connection)	Signal Incremental	Explanation
1	Red	U _S	Operating voltage
2	Blue	GND	Ground connection
3	Yellow	Clock +	Interface signals
4	White	Data +	Interface signals
5	Orange	SET	Electronic adjustment
6	Brown	Data -	Interface signals
7	Violet	Clock -	Interface signals
8	Black	- SIN	Signal wire
9	Orange-black	CW/CCW (V/R)	Sequence in direction of rotation
10	Green	- COS	Signal wire
11	Gray	+ COS	Signal wire
12	Pink	+ SIN	Signal wire
		Screen	Screen connected to housing on encoder side. Connected to ground on control side.

Diagrams



The maximum speed is also dependent on the shaft type.

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Recommended accessories

Other models and accessories → www.sick.com/AFS_AFM60_SSI

	Brief description	Туре	Part no.
Others			
	Connection type head A: Male connector, M23, 12-pin, straight, A-coded Signal type: HIPERFACE®, SSI, Incremental, RS-422 Description: HIPERFACE®, SSI, Incremental, RS-422, shielded, M23 male connector Connection systems: Solder connection	STE-2312-G	6027537
	 Connection type head A: Male connector, M23, 12-pin, straight, A-coded Signal type: HIPERFACE[®], SSI, Incremental Description: HIPERFACE[®], SSI, Incremental, shielded, M23 female connector with central fixing (for cabinet bushing) Connection systems: Solder connection 	STE-2312-GX	6028548
	 Connection type head A: Male connector, M23, 12-pin, straight, A-coded Signal type: HIPERFACE[®], SSI, Incremental Description: HIPERFACE[®], SSI, Incremental, shielded, Head A: male connector, M23, 12-pin, straight, for cable diameter 5.5 mm 10.5 mm Head B: - Operating temperature: -40 °C +125 °C Connection systems: Solder connection 	STE-2312-G01	2077273

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For us, that is "Sensor Intelligence."

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