



# Exo Sense RP User Guide

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*Revision 001*

***ESRB10X*** Exo Sense RP



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**Be sure to always remove the power supply before installing or removing the RP2040 board inside Exo Sense RP.**

**Exo Sense RP must be operated with the plastic case installed.**

**Follow all applicable electrical safety standards, guidelines, specifications and regulations for installation, wiring and operations of Exo Sense RP.**

**Carefully and fully read this Exo Sense RP user guide before installation.**

Exo Sense RP is not authorised for use in safety-critical applications where a failure of the product would reasonably be expected to cause personal injury or death. Safety-critical applications include, without limitation, life support devices and systems, equipment or systems for the operation of nuclear facilities and weapons systems. Exo Sense RP is neither designed nor intended for use in military or aerospace applications or environments and for automotive applications or environment. Customer acknowledges and agrees that any such use of Exo Sense RP is solely at Customer's risk, and that Customer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

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## Safety information

Carefully and fully read this user guide before installation and retain it for future reference.

### Qualified personnel

The product described in this manual must be operated only by personnel qualified for the specific task and installation environment, in accordance with all relevant documentation and safety instructions. A qualified person should be capable of fully identifying all installation and operation risks and avoid potential hazards when working with this product.

### Hazard levels

This manual contains information you must observe to ensure your personal safety and prevent damage to property. Safety information in this manual are highlighted by the safety symbols below, graded according to the degree of danger.



Indicates a hazardous situation which, if not avoided, **will** result in death or serious personal injury.



Indicates a hazardous situation which, if not avoided, **may** result in death or serious personal injury.



Indicates a hazardous situation which, if not avoided, can result in minor or moderate personal injury.



Indicates a situation which, if not avoided, can result in damage of property.

## Safety instructions

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### General safety instructions

Protect the unit against moisture, dirt and any kind of damage during transport, storage and operation. Do not operate the unit outside the specified technical data.

Never open the housing. Do not obstruct cooling of the unit. Keep out of the reach of children.



Life threatening voltages are present within and around an open control cabinet.

When installing this product in a control cabinet or any other areas where dangerous voltages are present, always switch off the power supply to the cabinet or equipment.



Risk of fire if not installed and operated properly.

Follow all applicable electrical safety standards, guidelines, specifications and regulations for installation, wiring and operations of this product.

Ensure that the product is properly installed and ventilated to prevent overheating.



The connection of expansion devices to this product may damage the product and other connected systems, and may violate safety rules and regulations regarding radio interference and electromagnetic compatibility.

Use only appropriate tools when installing this product. Using excessive force with tools may damage the product, alter its characteristics or degrade its safety.

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### Battery

This product uses a small lithium non-rechargeable battery to power its internal real time clock (RTC).



Improper handling of lithium batteries can result in an explosion of the batteries and/or release of harmful substances.

Worn-out or defective batteries can compromise the function of this product.

**KEEP OUT OF REACH OF CHILDREN.** Swallowing may lead to serious injury or death in as little as 2 hours due to chemical burns and potential perforation of the esophagus. Immediately see doctor.

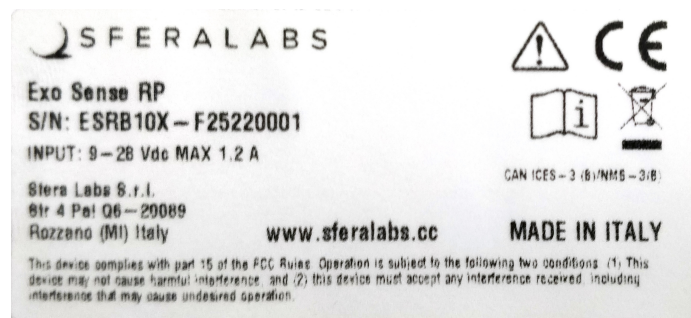
Replace the RTC lithium battery before it is completely discharged. Replace the battery every 5 years even if the battery is still working properly. The lithium battery must be replaced only with an identical **CR1025** Lithium / Manganese Dioxide (Li/MnO<sub>2</sub>) battery.

Do not throw lithium batteries into fire, do not solder on the cell body, do not recharge, do not open, do not short-circuit, do not reverse polarity, do not heat above 100°C and protect from direct sunlight, moisture and condensation.

Dispose of used batteries according to local regulations and the battery manufacturer's instructions.

## Device identification

The device can be identified with the information provided in the rating and identification plate, permanently attached to the internal side of the front cover case.



**EXAMPLE RATING AND IDENTIFICATION PLATE**

## Introduction

Exo Sense RP is an extremely versatile indoor environment sensor. It combines the power and ease of use of the Raspberry Pi RP2040 microcontroller, with several environmental sensors and input/output lines.

Exo Sense RP embeds temperature, humidity, air quality, light and PIR-based motion detection sensors, as well as a microphone for ambient noise measurements and audio recording. Two digital input/output lines and an open-collector output line are available on the terminal block. A real time clock module with battery back-up is also standard. It can optionally have a factory-installed earthquake sensor module.

An ESD-protected RS-485 bus is available for wired serial communication using the industry standard Modbus protocol or any other half-duplex serial protocol.

Exo Sense RP has an embedded RP2040, with a dual-core Arm Cortex M0+ processor, clocked up to 133 MHz, 264KB of SRAM, and a large 16MB on-board Flash memory.

A hidden USB 1.1 port is used to easily flash the microcontroller.



# Features

The Exo Sense RP key features are:

- ✓ 10÷28Vdc power supply, with surge and reverse polarity protection, and 1.1A resettable fuse
- ✓ RP2040, dual-core Arm Cortex M0+ processor, clocked up to 133 MHz, 264KB of SRAM
- ✓ 16MB on-board Flash memory
- ✓ Sensirion SHT40 temperature and humidity sensor
- ✓ Sensirion SGP40 air quality (Volatile Organic Compounds) sensor
- ✓ Texas Instruments OPT3001 digital ambient light sensor (ALS) with high-precision human-eye response
- ✓ Panasonic EKMC PIR motion sensor
- ✓ TDK ICS-43432 digital I<sup>2</sup>S microphone for audio recording and environment noise detection
- ✓ two digital inputs for potential-free contacts or TTL level input/output with 1-Wire, I<sup>2</sup>C and Wiegand support
- ✓ one open collector output with a maximum output current of 100mA, protected against over-current and short circuits
- ✓ standard RS-485 interface to the RP2040 UART serial lines, with electrostatic discharge (ESD) protection
- ✓ real time clock with replaceable CR1025 Lithium / Manganese Dioxide back-up battery
- ✓ Microchip ATECC608 secure element chip
- ✓ GPIO/PWM-controlled piezoelectric buzzer, for acoustic feedback
- ✓ GPIO-controlled LED
- ✓ hidden micro USB port with Micro-AB receptacle, to program and debug the RP2040
- ✓ hidden microSD slot, can be accessed opening the case
- ✓ Optional earthquake sensor module
- ✓ 80x80 mm wall mount ABS case with fast snap-in terminal block for easier installation.

## Hardware setup

For the initial setup, the plastic wall mount case must be removed to access the circuit board and internal connectors.

The case also needs to be opened to access the microUSB connector, and if the factory configuration of the internal jumpers for the RS-485 termination resistors or digital input configuration must be changed.

### NOTICE

Before opening the Exo Sense RP case, disconnect all power sources and any connection to external devices.

## Opening the case

Follow these steps, in the exact order, to open the case:

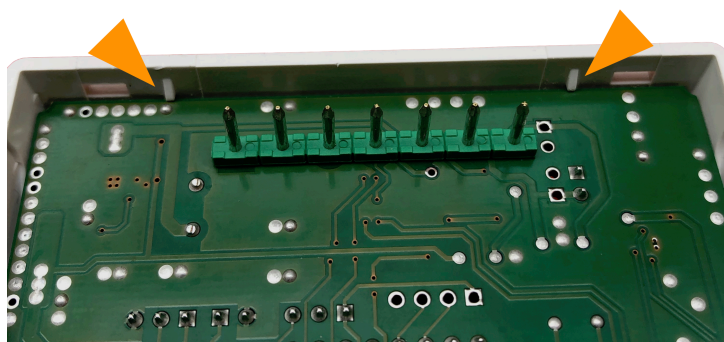
1. Use a small flat screwdriver to gently separate the front plastic cover from the wall mount back
2. The circuit board should remain attached to the front plastic cover; pay attention not to drop the circuit board, as it could be not firmly attached
3. With a small flat screwdriver gently separate the circuit board from the front cover. In some cases the circuit board could separate from the front case and remain connected to the terminal block.



**SEPARATE THE FRONT PLASTIC COVER FROM THE WALL MOUNT BACK**

## Closing the case

4. Replace the circuit board assembly inside the front cover; respect the orientation, with the light sensor aligned to the optical guide
5. Align the front cover and circuit board with the wall mount back, so that the connection pins on the circuit board match the terminal block receptacles on the wall mount back
6. Gently snap in the front plastic cover to the wall mount back.



THE PCB HOLDERS OF THE FRONT COVER



ALIGN THE CONNECTION PINS WITH THE TERMINAL BLOCK

## RP2040 board installation

The RP2040 and flash memory are located on a separate circuit board, that is factory-installed.

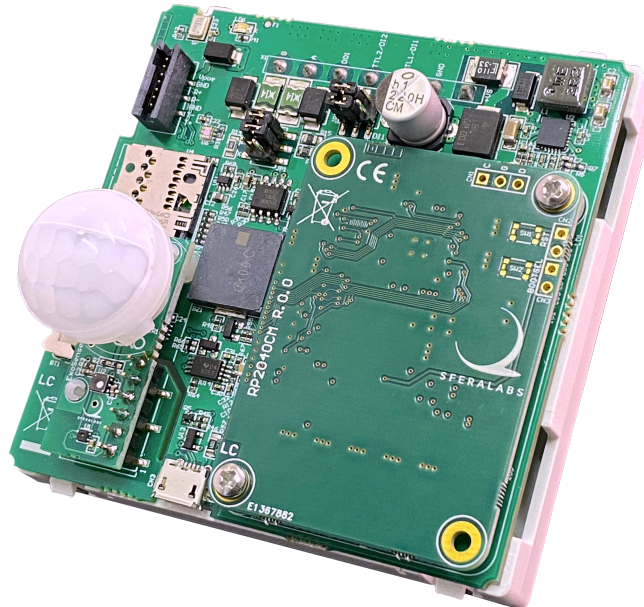
If you need to replace a pre-installed board, only a screwdriver is required.

Align the screw holes and connectors of the RP2040 board with the Exo Sense RP circuit board and gently snap in the board. Two screws secure the RP2040 board to the main Exo Sense RP board.



## NOTICE

Both the RP2040 board and the main Exo Sense RP board will likely be damaged if the connectors are not correctly aligned.



**RP2040 BOARD INSTALLED**

## NOTICE

Static electricity can damage the components in your system. To protect your system's components from static damage during the installation process, touch any of the unpainted metal surfaces on your computer's frame or wear an ESD wrist strap before handling internal components. Either method will safely discharge static electricity that's naturally present in your body.

When handling the Exo Sense RP circuit boards, be sure to hold it along the side edges using your thumb and index finger. Avoid touching the components and pin connectors as damage can occur.

## Replacing the RTC backup battery

The Exo Sense RP RTC uses a **CR1025** Lithium / Manganese Dioxide (Li/MnO<sub>2</sub>) battery.



## WARNING

Improper handling of lithium batteries can result in an explosion of the batteries and/or release of harmful substances.



Worn-out or defective batteries can compromise the function of this product.

**KEEP OUT OF REACH OF CHILDREN.** Swallowing may lead to serious injury or death in as little as 2 hours due to chemical burns and potential perforation of the esophagus. Immediately see doctor.

Replace the RTC lithium battery before it is completely discharged. Replace the battery every 5 years even if the battery is still working properly. The lithium battery must be replaced only with an identical **CR1025** Lithium / Manganese Dioxide (Li/MnO<sub>2</sub>) battery.

Do not throw lithium batteries into fire, do not solder on the cell body, do not recharge, do not open, do not short-circuit, do not reverse polarity, do not heat above 100°C and protect from direct sunlight, moisture and condensation.

Dispose of used batteries according to local regulations and the battery manufacturer's instructions.

The battery is not accessible from the outside. You should first remove the case top cover to gain access to the Exo Sense RP circuit boards.

## NOTICE

Before opening the Exo Sense RP case, disconnect all power sources and any connection to external devices.

Use a non-conductive pin or small tool to help extract the battery from its holder. Insert the new battery with a gentle push. You don't need tools to insert the battery. The battery is held into place by a spring contact.

Be sure to insert the battery so that the positive (+) terminal of the battery is in contact with the outer body of the battery holder, and the negative (-) terminal is in contact with the contact pad of the circuit board, as shown in the photo below.

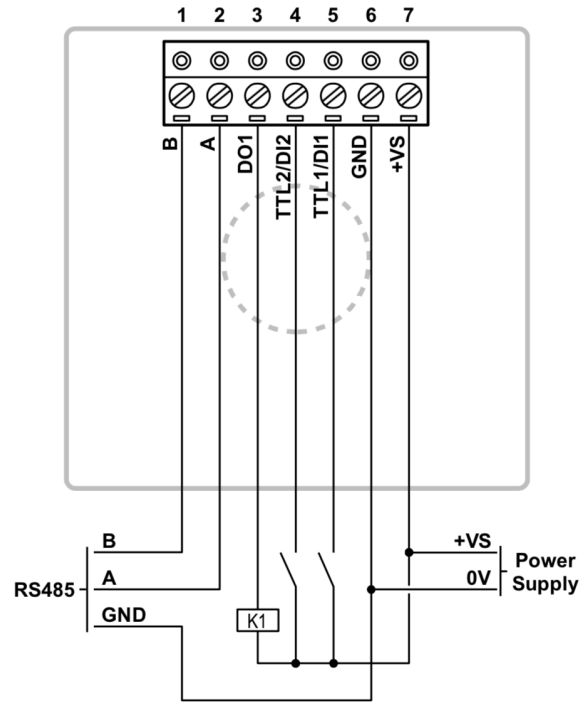
Reversing the battery polarity may damage the product.

The real time clock will reset its time immediately when the RTC backup battery is disconnected.

## Connections

Exo Sense RP has a 7 position terminal block attached to the back of the wall mount case. This terminal block is connected to a 7 pin header soldered to the circuit board.

The maximum conductor cross section is 2.5 mm<sup>2</sup> (14 AWG). Recommended stripping length is 7 mm. Screw thread is M3. Never exceed 0.6 Nm torque when tightening the screws.



CONNECTION EXAMPLE

## WARNING

Ensure that all cables entering the Exo Sense RP case are isolated to avoid electrical contact with the back of the printed circuit board or other conductive elements.

The cables should be routed out of the case through the circular hole at the center of the case back frame.

Ensure the cables cannot be punctured when the case is closed and that they don't exercise mechanical pressure on the printed circuit board.

## Power supply

Exo Sense RP can be powered with DC voltage only:

✓ DC: nominal voltage in the range 10V to 28V (min=9V, max=30V)

Respect the correct polarity shown in the schematic diagram (+ -). The power supply circuit implements reverse polarity protection using an auto resetting fuse and surge protection up to  $\pm 1000\text{V}/20\text{ohms } 1.2/50\mu\text{s}$ .

## Software development

Programming Exo Sense RP is as simple as any other RP2040-based boards, like the original Raspberry Pi Pico board.

You can program it in C/C++ or MicroPython, using any IDE or tool available for the RP2040 microcontroller or Pico board.

Refer to the following link for an overview on how to get started with RP2040 programming:

<https://www.raspberrypi.com/documentation/microcontrollers/rp2040.html>

For resources and examples specific to Exo Sense RP, go to:

<https://github.com/sfera-labs/exo-sense-rp>

## Programming interfaces

Exo Sense RP features the same programming interfaces of the Pico board: USB and SWD.

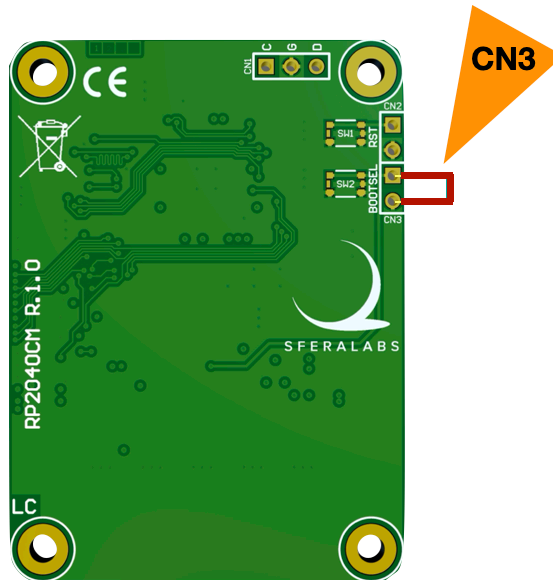
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### USB interface

The simplest way to program Exo Sense RP is by connecting it to a computer via USB, then dragging and dropping a program file onto it or using your IDE's features.

To set Exo Sense RP to *BOOTSEL mode* and have your computer see it as a USB Mass Storage Device:

- Remove power to Exo Sense RP and make sure the USB is unplugged
- Connect a wire jumper to the BOOTSEL CN3 header on the RP2040 board and connect the micro USB cable from your computer
- Turn on power supply to the Exo Sense RP (it can't be powered via the USB cable)
- Remove the BOOTSEL jumper after Exo Sense RP is powered
- It will mount as a Mass Storage Device called RPI-RP2.

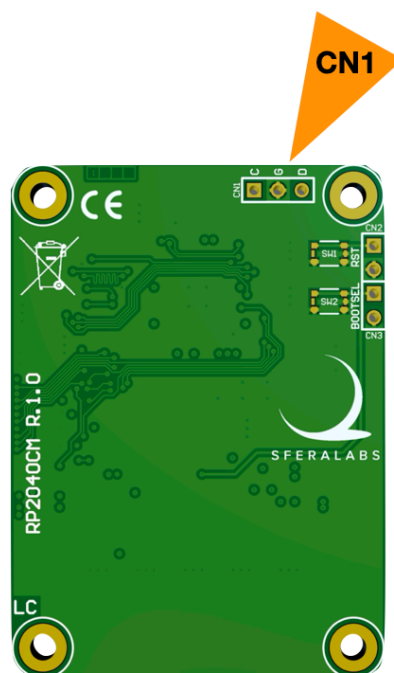


**BOOTSEL JUMPER**

## SWD interface

Serial Wire Debug (SWD) is a standard interface on Cortex-M-based microcontrollers, which the host computer can use to reset the board, load code into flash, set the code running, and interactively debug it.

Exo Sense RP exposes the RP2040 SWD interface on the CN1 header:



**SWD INTERFACE**

where the pin C is the SWCLK line, the pin D is the SWDIO line and G is GND.

When using the SWD interface Exo Sense RP needs to be connected to a power supply or powered via USB.

You can use a standard debug probe, the GPIOs of a Raspberry Pi or a Pico board to connect to the SWD interface.

For more details, refer to chapter 5 and 6 of the "Getting started with Raspberry Pi Pico" guide:

<https://datasheets.raspberrypi.org/pico/getting-started-with-pico.pdf>

## Features details

### Temperature, humidity and air quality sensors

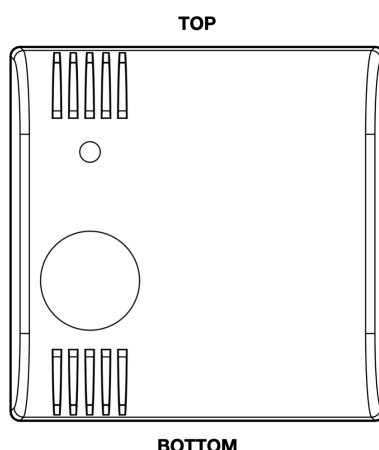
The temperature and humidity sensor is a Sensirion SHT40, connected to the RP2040 I<sup>2</sup>C bus.

The air quality (Volatile Organic Compounds) sensor is a Sensirion SGP40, also connected to the I<sup>2</sup>C bus.

Refer to the data sheets for detailed information on the usage of these sensors.

Both sensors are soldered on a raised printed circuit board close to the lower left ventilation grille. The upper grille, thanks to the air convection movement caused by the small temperature gradient between the inside of the case and the environment air temperature, creates a natural air flow to improve the performance of the sensors.

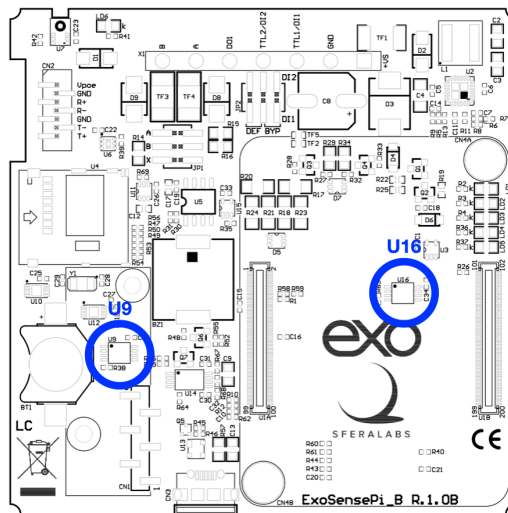
Exo Sense RP must be mounted vertically, possibly on a vertical wall or flat surface, as illustrated. Installing Exo Sense RP in any other position or orientation will make the temperature, humidity and air quality readings completely unreliable.



**EXO SENSE RP WALL MOUNT ORIENTATION**

The heat generated by the RP2040 and the Exo Sense RP components must be taken into account and properly compensated to ensure accurate readings from the SHT40 and SGP40 sensors.

In order to detect and compensate for self-generated heat, two LM75A temperature sensors are placed on the PCB, one underneath the RP2040 board (U16) and one close to the raised PCB where the SHT40 and SGP40 sensors are installed (U9). They are also connected to the I<sup>2</sup>C bus.



**THE PCB TEMPERATURE SENSORS**

## Light sensor

The light sensor is based on the Texas Instruments OPT3001 Ambient Light Sensor.

This I<sup>2</sup>C sensor implements accurate optical filtering to match the human eye response to light and rejects 99% of IR. The light intensity range is from 0.01 lux to 83 klux.

Refer to the Texas Instruments OPT3001 official data sheet for detailed information on the usage of this sensor.

The OPT3001 is soldered on the Exo Sense RP printed circuit board just below the top left ventilation grille. An optical guide is used to direct the external ambient light to the sensor's surface.

Note that the blue LED behind the top grille could theoretically interfere with the light sensor's accuracy. For best performance the LED should be off when reading the light intensity.

## Microphone

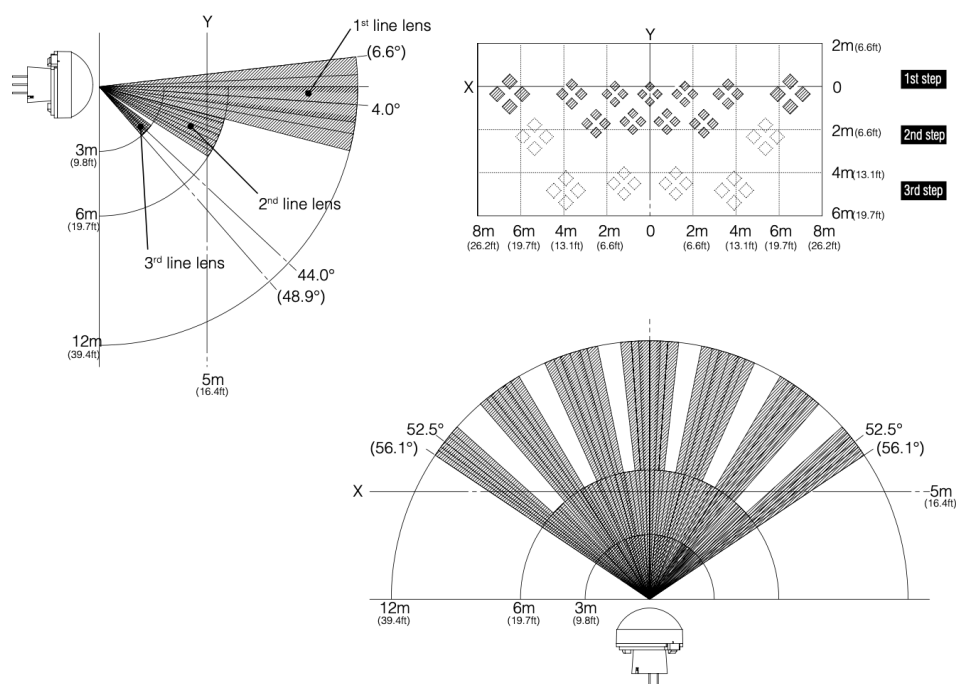
Exo Sense RP has a TDK ICS-43432 digital I<sup>2</sup>S microphone for audio recording and environment noise detection. The I<sup>2</sup>S lines are connected to the RP2040 GPIO lines, GPIO6 (SCK), GPIO7 (WS) and GPIO8 (SD).

Refer to the ICS-43432 data sheet for additional information.

## PIR motion sensor

The Panasonic EKMC1604111 PIR motion sensor has a digital output connected to the GPIO23 line of the RP2040. Its frontal lens is optimised for wall installations. The detection area is shown below.

### X-Y cross section at 5m (16.4ft)

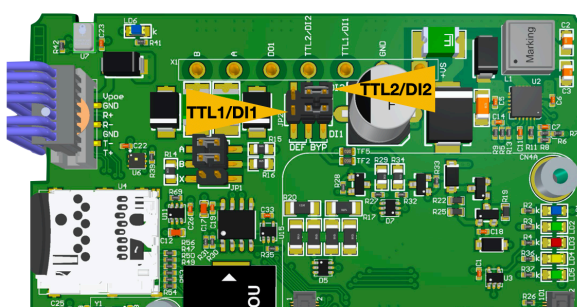


### PIR SENSOR DETECTION AREA

Motion of a human body inside the detection area causes frequent state changes of the digital output.

## TTLx/DIx: TTL input/output or generic digital inputs

TTL1/DI1 and TTL2/DI2 are dual-purpose pins. Using internal jumpers, they serve as TTL I/O lines or generic digital inputs.



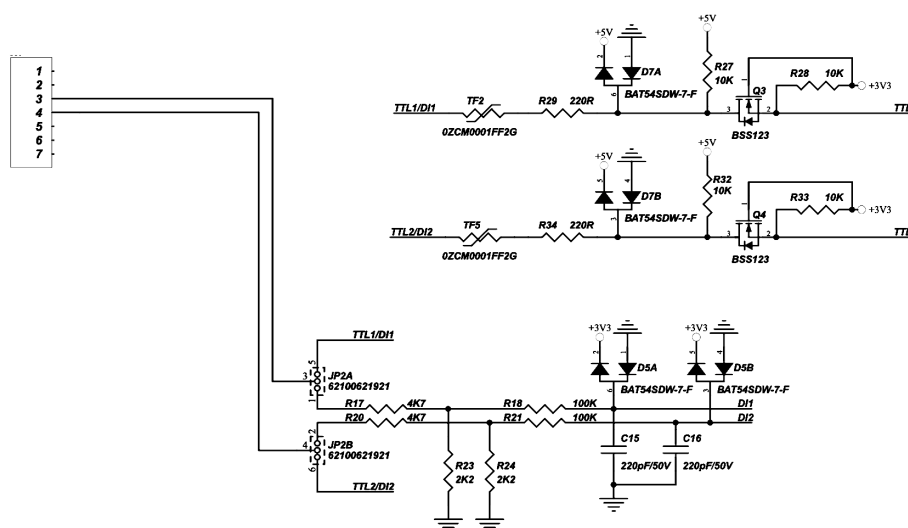
### INPUT MODE SELECTION JUMPERS POSITION



The lower jumper selects TTL1/DI1 configuration, while the upper jumper selects TTL2/DI2.

To use the TTLx/DIx lines as generic inputs, the corresponding jumper should be between the left and center pins (DEF position).

Set the jumper across the center and right pins to use the input as TTL I/O (BYP position).



### TTL LEVEL CONVERTER CIRCUIT AND INPUT MODE SELECTION JUMPERS

When these pins are configured as generic digital inputs, they are protected by a resistor network, and pulled to ground when not connected. They accept positive voltage levels up to 40 Vdc.

The DI1-DI2 front-end circuits have 2.2 kOhm pull-down and series 4.7 kOhm resistors.



Never apply voltage levels outside the specified operating limits to DI1 or DI2.

When configured as TTL I/O lines, they can be used as SDL/SCL lines for a soft-I2C bus, as 1-Wire buses, as a Wiegand interface, or for any other digital protocol electrically compatible.

The TTL1-TTL2 front-end circuits have 10kOhm pull-up and series 220 Ohm resistors.



Note that the Exo Sense RP board and the RP2040 board could be damaged if the jumpers are configured for TTL mode and voltages outside the 0÷5 V range are applied to the inputs.

## DO1: Open collector output

DO1 can be used as open collector (OC) output, controlled by the RP2040 GPIO10 line.

It is connected to a discrete open collector driver with a maximum output current of 100 mA and is protected against over-current and short circuits.

When the over-current protection is triggered, the output will open, stopping the current flow. A simple reset to 0 of GPIO10 will reset the protection.

To drive a load using the OC output, connect its positive input to the +VS power supply pin and the negative input to the OC pin.

## Buzzer

Exo Sense RP has an on-board piezoelectric sounder that can be controlled as either a simple on/off buzzer with a fixed 1 kHz tone, or with a PWM signal to generate variable pitch tones.

The on/off buzzer is driven by GPIO13, while GPIO12 is used for PWM control.

When the buzzer is active, it affects the microphone, as its sound will mask most or all ambient sound.

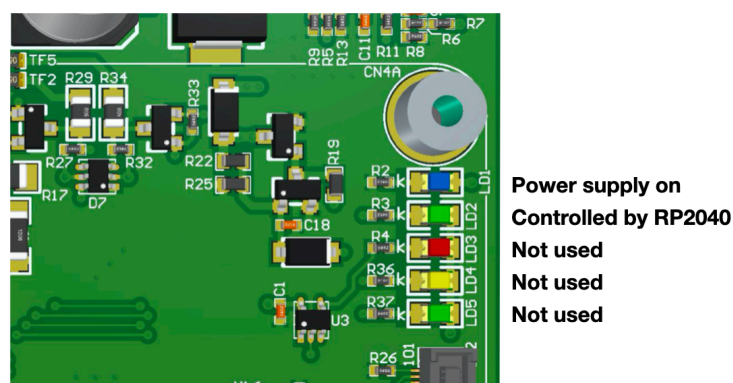
## LEDs

A blue LED, visible through the top grille, is controlled by the RP2040 GPIO14 line. Set GPIO14 high to turn on the LED.

Five status LEDs, only visible with the case removed, are placed on the right side of the circuit board, under the RP2040 board. LD1(blue) is the power supply LED, and is always on when power supply is present.

LD2 (green) is controlled by the RP2040 GPIO11 line. Set GPIO11 low to turn on the LED.

The remaining three LEDs are not used with Exo Sense RP.



STATUS LEDS

## RS-485 serial port

Exo Sense RP uses the RP2040 UART0 TX/RX pins (GPIO16/GPIO17) to implement a standard RS-485 serial port.

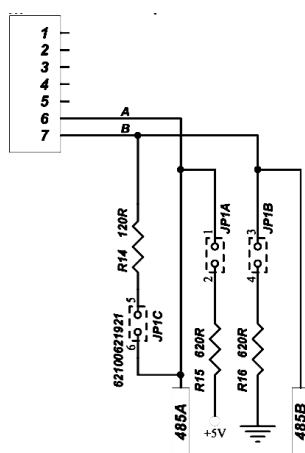
Simply connect the RS-485 A, B and GND to the RS-485 pins of the terminal block.

The RS-485 port is protected from ESD and voltage surges, and supports half-duplex communication up to 115200 bps<sup>1</sup>.

The RS-485 TX/RX switching is controlled by the RP2040 GPIO15 line. You should set GPIO15 low to enable transmission on the RS-485, and set it high to allow reception of incoming data.

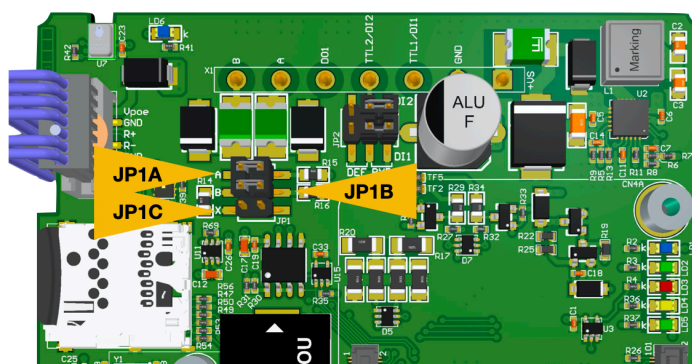
If GPIO15 is left high, the Exo Sense RP RS-485 driver will automatically drive the RS-485 lines in the dominant state, so that it is not strictly required to control GPIO15 in order to transmit data.

A 120 Ohm termination resistor between A and B can be enabled installing jumper JP1C.



RS-485 JUMPERS SCHEMATIC

Polarization jumpers JP1A and JP2A are not factory-installed.



RS-485 TERMINATION JUMPER POSITION

<sup>1</sup> Higher speeds are possible, but not guaranteed to meet EMI requirements

## Real Time Clock

Exo Sense RP has a hardware real time clock with a dedicated long-life non-rechargeable back-up battery.

The battery is only used to power the RTC chip when the main power is not available. Depending on operating conditions it should last up to two years if the Exo Sense RP board is not powered, more if the Exo Sense RP receives external power.

The RTC module is based on the Microchip MCP79410 real-time clock/calendar chip. It is connected to the RP2040 via the I<sup>2</sup>C bus.

## Secure element

Exo Sense RP embeds the ATECC608A or ATECC608B (depending on production lot) secure element chip from Microchip. The chip is connected to the RP2040 via the I<sup>2</sup>C bus.

Its key features are:

- ✓ Cryptographic co-processor with secure hardware-based key storage
- ✓ Protected storage for up to 16 Keys, certificates or data
- ✓ Hardware support for asymmetric sign, verify, key agreement – ECDSA: FIPS186-3 Elliptic Curve Digital Signature
  - ✓ ECDH: FIPS SP800-56A Elliptic Curve Diffie-Hellman
  - ✓ NIST standard P256 elliptic curve support
- ✓ Hardware support for symmetric algorithms
  - ✓ SHA-256 & HMAC hash including off-chip context save/restore
  - ✓ AES-128: encrypt/decrypt, Galois field multiply for GCM
- ✓ Networking key management support
  - ✓ Turnkey PRF/HKDF calculation for TLS 1.2 & 1.3
  - ✓ Ephemeral key generation and key agreement in SRAM – Small message encryption with keys entirely protected
- ✓ Secure boot support
  - ✓ Full ECDSA code signature validation, optional stored digest/signature – optional communication key disablement prior to secure boot
  - ✓ Encryption/Authentication for messages to prevent on-board attacks
- ✓ Internal high-quality FIPS 800-90 A/B/C Random Number Generator (RNG)
- ✓ Two high-endurance monotonic counters
- ✓ Guaranteed unique 72-bit serial number.

## Earthquake sensor module (optional)

Exo Sense RP can be shipped with an optional, factory-installed earthquake sensor module based on the OMRON D7S vibration sensor. It is connected to the RP2040 via the I<sup>2</sup>C bus.

This module is soldered to the Exo Sense RP circuit board and cannot be removed by the user.

## Dedicated GPIO pins

The following table shows the mapping of the inputs and outputs of the Exo Sense RP module to the related pins of the RP2040 microcontroller.

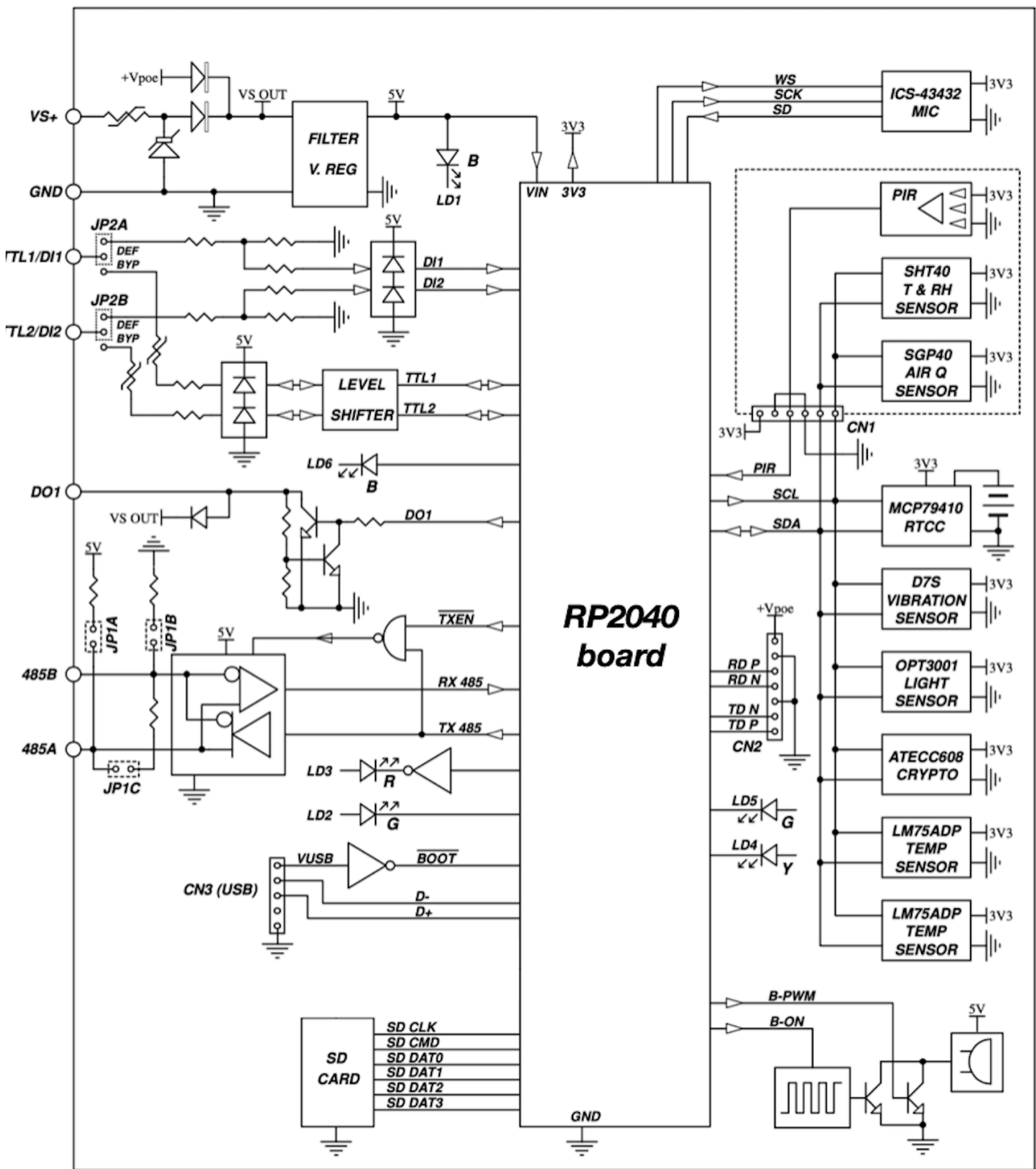
Exo Sense RP inputs and outputs	RP2040
TTL1	GPIO26
TTL2	GPIO27
DI1	GPIO28
DI2	GPIO29
DO1	GPIO10
PIR	GPIO23
Buzzer (on/off)	GPIO13
Buzzer (PWM)	GPIO12
Blue LED	GPIO14
Green LED	GPIO11
RS-485 RX	GPIO17
RS-485 TX	GPIO16
RS-485 TX-ENABLE (N)	GPIO15
I <sup>2</sup> C SDA	GPIO0
I <sup>2</sup> C SCL	GPIO1
Microphone I <sup>2</sup> S SCK	GPIO6
Microphone I <sup>2</sup> S WS	GPIO7
Microphone I <sup>2</sup> S SD	GPIO8

## I<sup>2</sup>C bus addresses

The following table shows the addresses of the devices connected to the primary I<sup>2</sup>C bus ("I2C0") of the RP2040.

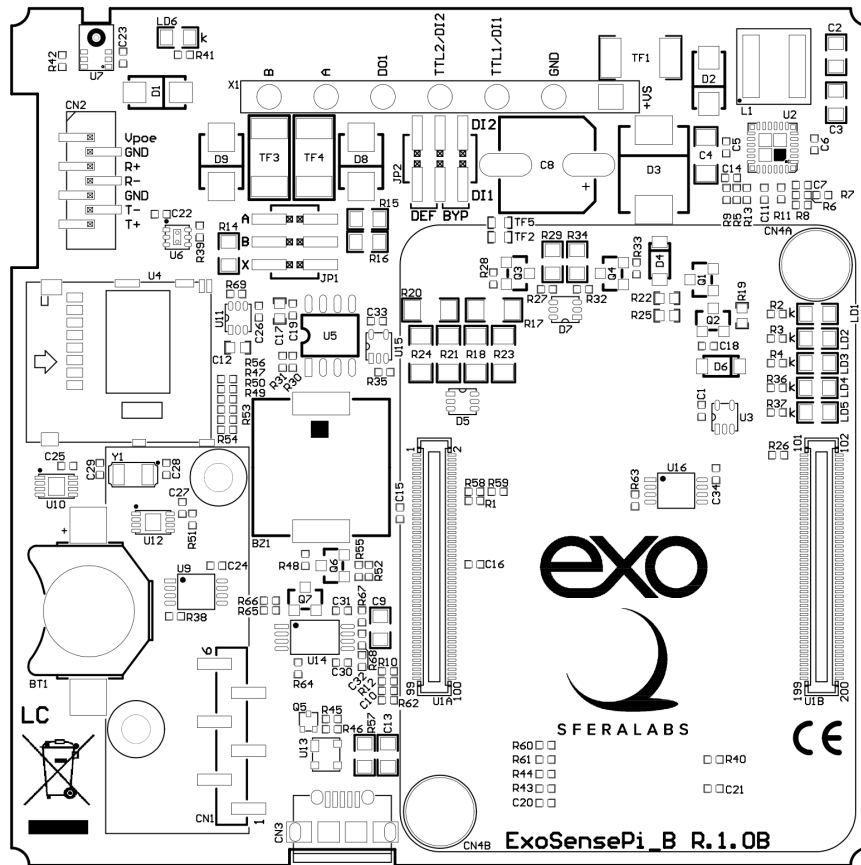
Device	I <sup>2</sup> C address
SHT40	0x44
OPT3001	0x45
LM75A (U9)	0x48
LM75A (U16)	0x49
D7S (optional)	0x55
MCP79410 EEPROM	0x57
SGP40	0x59
ATECC608	0x60
MCP79410 RTC	0x6f

## Block diagram



BLOCK DIAGRAM

# Board layout



BOARD LAYOUT (TOP VIEW)

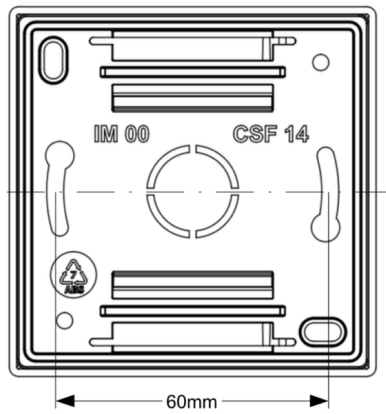
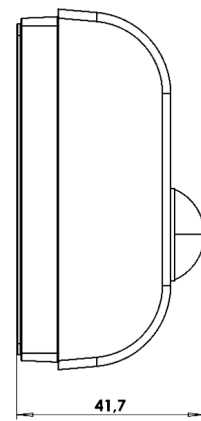
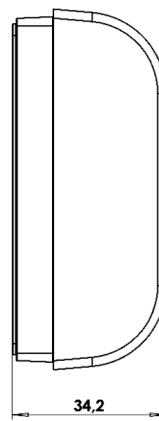
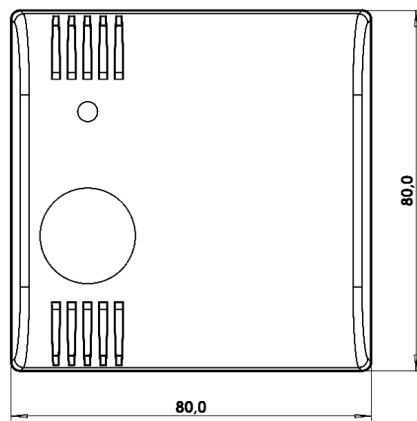


# Technical specifications

POWER SUPPLY	
Power supply operating voltage (VS)	10...28 V <sub>DC</sub> (VDC)  Reverse polarity protection with 1.1 A resettable fuse. Surge protection up to ±1000V/2ohms 1.2/50µs
Current consumption at VS +12 V <sub>DC</sub>	50mA  Actual current consumption may vary based on working conditions
ARCHITECTURE	
Microcontroller	Raspberry Pi RP2040  dual-core Arm Cortex M0+, 133 MHz, 264KB SRAM 16MB on-board Flash memory
COMMUNICATION PORTS	
Serial communication ports	RS-485 Half-Duplex with TX/RX management controlled by GPIO, or passive mode
Baud Rates	1200 to 115200
ESD-Protection Voltage on RS-485 A/B	±15 kV human body model ±8 kV contact discharge
Surge protection on RS-485 A/B	Surge protection up to ±500 V / 2 Ohms 1.2/50 µs; 600 W peak pulse power capability at 10/1000 µs waveform
Fail safe feature on RS-485	Optional with jumpers (not installed)
USB port	Micro-USB B Receptacle USB 1.1
DI1-DI2: DIGITAL INPUTS	
Input voltage range	+0...+40 V
Input impedance	6.5 kOhm
Voltage threshold	VIH: 5.1 V VIL: 3.4 V
Max recommended cable length	30 meters
DI1-DI2: DIGITAL INPUT/OUTPUT	
Output voltage	VOL: 0.1 V VOH: 5.0 V
Input voltage range	+0...+5 V
Input voltage threshold	VIH: 1.4 V VIL: 1.1 V
Pull-up (+5 V)	10 kOhm

Impedance	220 Ohm
Max recommended cable length	10 meters
<b>DO1: OPEN COLLECTOR OUTPUT</b>	
Type	NPN, common on VS, short circuit protected
Max output current	100 mA
Voltage range	+0 V...+VS
Max recommended cable length	2 m
<b>REAL TIME CLOCK</b>	
Oscillator frequency	32768 Hz
Frequency Tolerance	±20.00 ppm
Backup battery	Internal RTCC circuit with backup lithium battery. Only use CR1025 Lithium / Manganese Dioxide (Li/ MnO <sub>2</sub> ) batteries.  Expected battery life without main power supply: ~2 years
<b>EMI IMMUNITY STANDARDS</b>	
Electromagnetic immunity compliance	EN 61000-4-2 (ESD) EN 61000-4-3 (Radiated RF Field) EN 61000-4-4 (Burst/fast transient) EN 61000-4-6 (Conducted) EN 61000-4-8 (Power frequency magnetic field)
<b>ENVIRONMENTAL</b>	
Operating temperature	-10...+50 °C (non-condensing humidity)
Relative humidity	5% to 90% noncondensing
Storage temperature	-20...+0 °C
Protection degree	IP20
<b>MECHANICAL</b>	
7-pin terminal block characteristics	Maximum conductor cross section: 2.5 mm <sup>2</sup> (14 AWG) Recommended stripping length: 7 mm Screw thread: M3 Maximum screws tightening torque: 0.6 Nm
Housing	Wall mount ABS case
Dimensions	width: 80.0 mm height: 80.0 mm depth: 34.2 - 41.7 mm
Weight	90 gr

## Dimensions



## DIMENSIONS

## Disposal

### Waste Electrical & Electronic Equipment



(Applicable in the European Union and other European countries with separate collection systems). This marking on the product, accessories or literature indicates that the product should not be disposed of with other household waste at the end of their working life. To prevent possible harm to the environment or human health from uncontrolled waste disposal, please separate these items from other types of waste and recycle them responsibly to promote the sustainable reuse of material resources. Household users

should contact either the retailer where they purchased this product, or their local government office, for details of where and how they can take these items for environmentally safe recycling. This product and its electronic accessories should not be mixed with other commercial wastes for disposal.

Exo Sense RP contains a small non rechargeable manganese dioxide lithium coin battery.

The battery is not accessible from the outside. You should first open the case body to gain access to the circuit boards. Always remove the battery before disposing of this product.

## Installation and use restrictions

### Standards and regulations

The design and the setting up of electrical systems must be performed according to the relevant standards, guidelines, specifications and regulations of the relevant country. The installation, configuration and programming of the devices must be carried out by trained personnel.

The installation and wiring of connected devices must be performed according to the recommendations of the manufacturers (reported on the specific data sheet of the product) and according to the applicable standards.

All the relevant safety regulations, e.g. accident prevention regulations, law on technical work equipment, must also be observed.

## Safety instructions

Carefully read the safety information section at the beginning of this document.

### Set-up

For the first installation of the device proceed according to the following procedure:

- ✓ make sure all power supplies are disconnected
- ✓ install and wire the device according to the schematic diagrams on the specific data sheet of the product
- ✓ after completing the previous steps, switch on the the power supply and the other related circuits.

# Conformity Information

## EU

This device complies with the following applicable European Community harmonised standards:

- ✓ 2014/30/EU - Electromagnetic Compatibility Directive (EMC)
- ✓ 2011/65/EU and 2015/863/EU - Restriction of the use of certain hazardous substances in electrical and electronic equipment (RoHS)

The following harmonised standards have been used to demonstrate conformity to these directives:

- ✓ EN61000-6-2:2019 - EMC Immunity standard for industrial environments
- ✓ EN 61000-6-3:2007/A1:2011/AC:2012 - EMC Emission standard for residential, commercial and light-industrial environments

The declaration of conformity is available at: <https://www.sferalabs.cc>

## USA

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna
- Increase the separation between the equipment and receiver
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected
- Consult the dealer or an experienced radio/TV technician for help.

Shielded cables must be used with this equipment to maintain compliance with FCC regulations.

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

## **CANADA**

This Class B digital apparatus complies with Canadian ICES-003.

Cet appareil numérique de la classe B est conforme à la norme NMB-003 du Canada.

## **RCM AUSTRALIA / NEW ZEALAND**

This product meets the requirements of the standard EN 61000-6-3:2007/A1:2011/AC:2012 - Emission for residential, commercial and light-industrial environments.