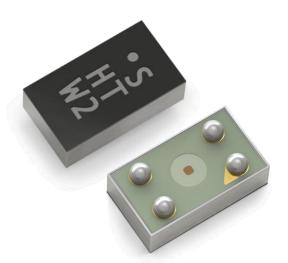


Data Sheet SHTW2

WLCSP Humidity and Temperature Sensor IC

- Ultra-small flip chip package: 1.3 × 0.7 × 0.5 mm³
- Fully calibrated and reflow solderable
- Ultra-low power consumption
- Power-up and measurement within 1 ms
- 1.8 V supply voltage
- Typical accuracy: ±3 %RH and ±0.3 °C



Product Summary

The SHTW2 is a digital humidity and temperature sensor in a flip chip package. This type of package opens up a new category of ultra-small humidity sensors which are suitable for applications with the tightest space constraints. At the same time, the flip chip package impresses with its pure simplicity.

The sensor is based on Sensirion's CMOSens® technology, which offers a complete sensor system on a single chip, consisting of a capacitive humidity sensor, a bandgap temperature sensor, analog and digital signal processing, A/D converter, calibration data memory, and a digital communication interface supporting I²C fast mode.

The sensor covers a humidity measurement range of 0 to 100 %RH and a temperature measurement range of -30 to 100 °C with a typical accuracy of ±3 %RH and ±0.3°C. The operation voltage of 1.8 V and the low power consumption make the SHTW2 suitable for mobile or wireless applications running on the tightest power budgets. With the industry-proven quality and reliability of Sensirion's humidity and temperature sensors and constant accuracy over a large measurement range, the SHTW2 offers an unprecedented performance-to-price ratio. Tape and reel packaging together with suitability for standard SMD assembly processes make the SHTW2 predestined for high-volume applications.

Benefits of Sensirion's CMOSens® Technology

- High reliability and long-term stability
- Industry-proven technology with a track record of more than 10 years
- Designed for mass production
- Optimized for lowest cost
- Best signal-to-noise ratio

Contents of this Data Sheet

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| 4 | Interface Specifications | |
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Block diagram

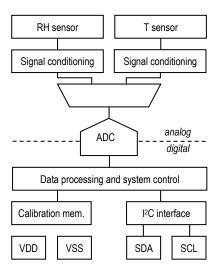


Figure 1 Functional block diagram of the SHTW2.



1 Humidity and Temperature Sensor Specifications

Relative Humidity

| Parameter | Conditions | Value | Units |
|---------------------------------|-----------------------|--------------|-------|
| Accuracy tolerance ¹ | Тур. | ±3.0 | %RH |
| Accuracy tolerance | Max. | see Figure 2 | %RH |
| Repeatability ² | - | 0.1 | %RH |
| Resolution ³ | - | 0.01 | %RH |
| Hysteresis | - | ±1 | %RH |
| Specified range ⁴ | extended ⁵ | 0 to 100 | %RH |
| Response time ⁶ | τ 63% | 8 | S |
| Long-term drift ⁷ | Тур. | <0.25 | %RH/y |

Table 1 Humidity sensor specifications.

ΔRH [%RH] ±10 Maximal tolerance ±8 Typical tolerance ±6 ±4 ±2 ±0 0 10 20 30 40 50 70 80 90 100

Figure 2 Typical and maximal tolerance for the relative humidity in %RH at 25 °C.

Relative humidity [%RH]

Temperature

| Parameter | Conditions | Value | Units |
|---------------------------------|--------------|--------------|-------|
| Accuracy tolerance ¹ | Тур. | ±0.3 | °C |
| Accuracy tolerance | Max. | see Figure 3 | °C |
| Repeatability ² | - | 0.1 | °C |
| Resolution ³ | - | 0.01 | °C |
| Specified range ⁴ | - | -30 to +100 | °C |
| Response time8 | τ 63% | <5 to 30 | S |
| Long-term drift ⁹ | Normal range | <0.02 | °C/y |

Table 2 Temperature sensor specifications.

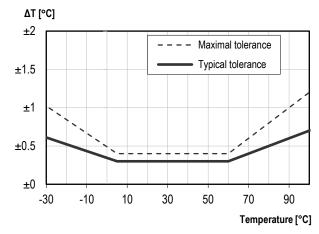


Figure 3 Typical and maximal tolerance for the temperature sensor in °C.

¹ For definition of typ. and max. accuracy tolerance, please refer to the document "Sensirion Humidity Sensor Specification Statement".

 $^{^2}$ The stated repeatability is 3 times the standard deviation (3 σ) of multiple consecutive measurement values at constant conditions and is a measure for the noise on the physical sensor output.

³ Resolution of A/D converter.

 $^{^4}$ Specified range refers to the range for which the humidity or temperature sensor specification is guaranteed.

⁵ For details about recommended humidity and temperature operating range, please refer to section 1.1.

⁶ Time for achieving 63% of a humidity step function, valid at 25°C and 1 m/s airflow. Humidity response time in the application depends on the design-in of the sensor

⁷ Typical value for operation in normal RH/T operating range. Max. value is < 0.5 %RH/y. Value may be higher in environments with vaporized solvents, outgassing tapes, adhesives, packaging materials, etc. For more details please refer to Handling Instructions.</p>

⁸ Temperature response time depends on heat conductivity of sensor substrate and design-in of sensor in application.

 $^{^9}$ Typical value for operation in normal T operating range. Max. value is < 0.04°C/y.



1.1 RH Accuracy at Various Temperatures

Typical RH accuracy at 25°C is defined in Figure 2. For other temperatures, typical accuracy has been evaluated to be as displayed in Figure 4.

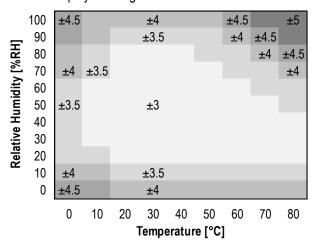


Figure 4 Typical accuracy of relative humidity measurements given in %RH for temperatures 0 - 80°C.

1.2 Recommended Storage and Operating Conditions

The sensor shows best performance when operated within recommended normal temperature and humidity range of 5 – 60 °C and 20 – 80 %RH, respectively. Long term exposure to conditions outside normal range, especially at high humidity, may temporarily offset the RH signal (e.g. +3%RH after 60h at >80%RH). After returning into the normal temperature and humidity range the sensor will slowly come back to calibration state by itself. Prolonged exposure to extreme conditions may accelerate ageing.

To ensure stable operation of the humidity sensor, the conditions described in the document "SHTxx Handling Instructions" regarding exposure to volatile organic compounds have to be met. Please note as well that this does apply not only to transportation and manufacturing, but also to operation of the SHTW2.

2 Electrical Specifications

2.1 Electrical Characteristics

Default conditions of 25 °C and 1.8 V supply voltage apply to values in the table below, unless otherwise stated.

| Parameter | Symbol | Conditions | Min | Тур. | Max | Units | Comments |
|--------------------------|------------------|---------------------|---------------------|------|--------------------------------|-------|--|
| Supply voltage | V_{DD} | - | 1.62 | 1.8 | 1.98 | V | - |
| Power-up/down level | V _{POR} | Static power supply | 1.05 | 1.2 | 1.35 | V | - |
| | | Idle state | - | 0.7 | 1.5 | μΑ | - |
| Supply current | I _{DD} | Measurement | - | 385 | 465 | | Average current consumption while sensor is measuring ¹⁰ |
| очерну очнот | ppry current | Average | , | 4.8 | 1 | μΑ | Average current consumption (continuous operation with one measurement per second) ¹⁰ |
| Power consumption | - | Average | - | 8.6 | - | μW | Average power consumption (continuous operation with one measurement per second) 10 |
| Low level input voltage | VIL | - | -0.5 | - | 0.3 V _{DD} | V | - |
| High level input voltage | VIH | - | 0.7 V _{DD} | - | V _{DD} (max) + 0.5 | V | - |
| Low level output voltage | VoL | 3 mA sink current | - | - | 0.2 V _{DD} | - | - |

Table 3 Electrical specifications.

2.2 Absolute Maximum Ratings

Stress levels beyond those listed in Table 4 may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these conditions cannot be guaranteed. Exposure to the absolute maximum rating conditions for extended periods may affect the reliability of the device.

¹⁰ These values can be reduced by using the low power measurement mode, see separate application note.



| Parameter | Rating |
|---|-----------------|
| Supply voltage, V _{DD} | -0.3 to +2.16 V |
| Operating temperature range | -40 to +125 °C |
| Storage temperature range ¹¹ | -40 to +125 °C |
| ESD HBM | 2 kV |
| ESD MM | 200 V |
| ESD CDM | 500 V |
| Latch up, JESD78 Class II | 100mA |

Table 4 Absolute maximum ratings.

3 Timing Specifications

3.1 Sensor System Timings

Default conditions of 25 °C and 1.8 V supply voltage apply to values specified in the table below, unless otherwise stated. Max. values are measured at -30 °C and 1.98V supply voltage.

| Parameter | Symbol | Conditions | Min. | Тур. | Max. | Units | Comments |
|----------------------|-------------------|--|------|------|------|-------|--|
| Power-up time | t _{PU} | After hard reset, V _{DD} ≥ V _{POR} | 1 | 182 | 239 | μs | Time between V _{DD} reaching V _{PU} and sensor entering idle state |
| Soft reset time | tsr | After soft reset. | - | 173 | 230 | • | Time between ACK of soft reset command and sensor entering idle state |
| Measurement duration | t _{MEAS} | - | 1 | 10.8 | 14.4 | | Duration for a humidity and temperature measurement ¹² |

Table 5 System timing specifications.

3.2 Communication Timings

Default conditions of 25 °C and 1.8 V supply voltage apply to values in the table below, unless otherwise stated.

| Parameter | Symbol | Conditions | Min. | Тур. | Max. | Units | Comments |
|--|---------------------|---|--------------------------------|------|------|-------|----------|
| SCL clock frequency | f _{SCL} | - | 0 | - | 400 | kHz | - |
| Hold time (repeated) START condition | thd;sta | After this period, the first clock pulse is generated | 0.6 | - | - | μs | - |
| LOW period of the SCL clock | t _{LOW} | - | 1.3 | - | - | μs | - |
| HIGH period of the SCL clock | t _{HIGH} | - | 0.6 | - | - | μs | - |
| Set-up time for a repeated START condition | tsu;sta | - | 0.6 | - | - | μs | - |
| SDA hold time | t _{HD;DAT} | - | 0 | - | - | | - |
| SDA set-up time | tsu;dat | - | 100 | - | • | ns | - |
| SCL/SDA rise time | t _R | - | 20 | - | 300 | ns | - |
| SCL/SDA fall time | t _F | - | 20 * (V _{DD} /5.5) | - | 300 | ns | - |
| SDA valid time | t _{VD;DAT} | - | - | - | 0.9 | μs | - |
| Set-up time for STOP condition | tsu;sto | - | 0.6 | - | - | μs | - |
| Capacitive load on bus line | Св | - | - | - | 400 | pF | - |

Table 6 Communication timing specifications. The numbers above are values according to the I²C specification.

¹¹ The recommended storage temperature range is 10-50°C. Please consult the document "SHTxx Handling Instructions" for more information.

¹² These values can be reduced by using the low power measurement mode, see separate application note.



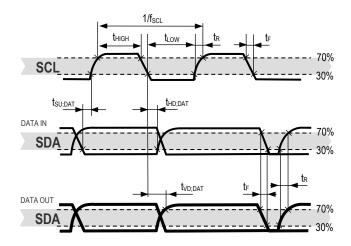


Figure 5 Timing diagram for digital input/output pads. SDA directions are seen from the sensor. Bold SDA lines are controlled by the sensor, plain SDA lines are controlled by the micro-controller. Note that SDA valid read time is triggered by falling edge of preceding toggle.

4 Interface Specifications

The SHTW2 supports I²C fast mode (SCL clock frequency from 0 to 400 kHz) with clock stretching. For detailed information on the I²C protocol, refer to NXP I²C-bus specification and user manual UM10204, Rev. 4, February 13, 2012:

http://ics.nxp.com/support/documents/interface/pdf/I2C.bus.s.specification.pdf

The SHTW2 comes in a 4-pin flip chip package – see Table 7.

| Pin | Name | Comments | |
|-----|------|--------------------------------|---------------------------------|
| 1 | VDD | Supply voltage | 1 4 |
| 2 | SCL | Serial clock, bidirectional | BC |
| 3 | SDA | Serial data, bidirectional | $_{2}$ \times \times $_{3}$ |
| 4 | VSS | Ground | |

Table 7 SHTW2 pin assignment (top view).

Power-supply pins supply voltage (VDD) and ground (VSS) must be decoupled with a 100 nF capacitor that shall be placed as close to the sensor as possible – see Figure 6.

SCL is used to synchronize the communication between microcontroller and the sensor. The master must keep the clock frequency within 0 to 400 kHz as specified in Table 6. The SHTW2 may pull down the SCL line when clock stretching is enabled.

The SDA pin is used to transfer data in and out of the sensor. For safe communication, the timing specifications defined in the I²C manual must be met.

To avoid signal contention, the microcontroller must only drive SDA and SCL low. External pull-up resistors (e.g. $10~\text{k}\Omega$) are required to pull the signal high. For dimensioning resistor sizes please take bus capacity requirements into account. It should be noted that pull-up resistors may be included in I/O circuits of microcontrollers.

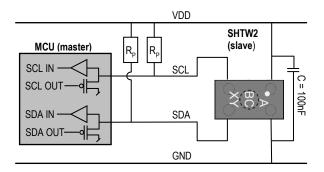


Figure 6 Typical application circuit, including pull-up resistors R_P and decoupling of VDD and VSS by a capacitor.

For good performance of the SHTW2 in the application, it is important to know that the solder balls of the SHTW2 offer the best thermal contact to the temperature sensor. The humidity sensor is centered on the bottom side of the package and must not be obstructed by underfill or other material. For more information on design-in, please refer to the document "SHTxx Design Guide".



5 Operation and Communication

All commands and memory locations of the SHTW2 are mapped to a 16-bit address space which can be accessed via the I²C protocol.

| SHTW2 | Bin. | Dec. | Hex. |
|--------------------------|----------|------|------|
| I ² C address | 111'0000 | 112 | 0x70 |

Table 8 SHTW2 I2C device address.

5.1 Power-Up and Communication Start

Upon VDD reaching the power-up voltage level V_{POR} , the SHTW2 enters idle state after a duration of t_{PU} . In idle state, the SHTW2 is ready to receive commands from the master (microcontroller).

Each transmission sequence begins with START condition (S) and ends with an (optional) STOP condition (P) as described in the I²C-bus specification. Whenever the sensor is powered up, but not performing a measurement or communicating, it automatically enters idle state for energy saving.

Please note that in case VDD is set to 0 V (GND), e.g. in case of a power off of the SHTW2, the SCL and SDA pads are also pulled to GND. Consequently, the I^2C bus is blocked while VDD of the SHTW2 is set to 0 V.

5.2 Measurement Commands

The SHTW2 provides the possibility to define the sensor behavior during measurement as well as the transmission sequence of measurement results. These characteristics are defined by the appropriate measurement command (see Table 9). Each measurement command triggers both a temperature *and* a humidity measurement.

| Clock Stretching | | Clock Stretching | |
|------------------|--------|------------------|--------|
| Enabled | | Disa | bled |
| Read T | Read H | Read T | Read H |
| First | First | First | First |
| 0x7CA2 | 0x5C24 | 0x7866 | 0x58E0 |

Table 9 Measurement commands.

5.3 Starting a Measurement

A measurement communication sequence consists of a START condition followed by the I²C header with the 7-bit I²C device address and a write bit (write W: '0'). The sensor indicates the proper reception of a byte by pulling the SDA pin low (ACK bit) after the falling edge of the 8th SCL clock. Then the sensor is ready to receive a 16-bit measurement command. Again, the SHTW2 acknowledges the proper reception of each byte with ACK condition. A complete measurement cycle is presented in Figure 7.

With the acknowledgement of the measurement command, the SHTW2 starts measuring humidity and temperature.

5.4 Sensor Behavior during Measurement and Clock Stretching

In general, the sensor does not respond to any I²C activity during measurement, i.e. I²C read and write headers are not acknowledged (NACK). However, when clock stretching has been enabled by using a corresponding measurement command, the sensor responds to a read header with an ACK and subsequently pulls down the SCL line until the measurement is complete. As soon as the measurement is complete, the sensor starts sending the measurement results.

For best possible repeatability of humidity and temperature measurements, it is recommended to avoid any communication on the I2C bus while the SHTW2 is measuring. For more information, see application note "SHTC1/SHTW1 Optimization of Repeatibility".

During measurement, the sensor has a current consumption according to Table 3.

5.5 Readout of Measurement Results

After a measurement command has been issued and the sensor has completed the measurement, the master can read the measurement results by sending a START condition followed by an I²C read header. The sensor will acknowledge the reception of the read header and send two bytes of data followed by one byte CRC checksum and another two bytes of data followed by one byte CRC checksum. Each byte must be acknowledged by the microcontroller with an ACK condition for the sensor to continue sending data. If the SHTW2 does not receive an ACK from the master after any byte of data, it will not continue sending data.

Whether the sensor sends out humidity or temperature data first depends on the measurement command that was sent to the sensor to initiate the measurement (see Table 9).

The I²C master can abort the read transfer with a NACK condition after any data byte if it is not interested in subsequent data, e.g. the CRC byte or the second measurement result, in order to save time.

In case the user needs humidity and temperature data but does not want to process CRC data, it is recommended to read the first two bytes of data with the CRC byte (without processing the CRC data) and abort the read transfer after reading the second two data bytes with a NACK. This procedure is more time efficient than starting two different measurements and aborting the read transfer after the first two data bytes each time.

5.6 Soft Reset

The SHTW2 provides a soft reset mechanism that forces the system into a well-defined state without removing the power supply. If the system is in idle state (i.e. if no measurement is in progress) the soft reset command can



be sent to SHTW2 according to Figure 8. This triggers the sensor to reset all internal state machines and reload calibration data from the memory.

| Command | Hex. Code | Bin. Code |
|----------------|-----------|---------------------|
| Software reset | 0x805D | 1000'0000'0101'1101 |

Table 10 Soft reset command.

Read-out of ID Register

The SHTW2 has an ID register which contains an SHTW2specific product code. The read-out of the ID register can be used to verify the presence of the sensor and proper communication. The command to read the ID register is shown in Table 11.

| Command | Hex. Code | Bin. Code |
|------------------|-----------|---------------------|
| Read ID register | 0xEFC8 | 1110'1111'1100'1000 |

Table 11 Read-out command of ID register.

It needs to be sent to the SHTW2 after an I2C write header. After the SHTW2 has acknowledged the proper reception of the command, the master can send an I2C read header and the SHTW2 will submit the 16-bit ID followed by 8 bits of CRC. The structure of the ID is described in Table 12.

| 6-bit ID |
|--|
| xxxx'xxxx'xx 00'0111 |
| bits 5 to 0: SHTW2-specific product code bits 15 to 6: unspecified information |

Table 12 Structure of the 16-bit ID. Bits 15:6 of the ID contain unspecified information (marked as "x"), which may vary from sensor to sensor, while bits 5:0 contain the SHTW2-specific product code.

Checksum Calculation

The 8-bit CRC checksum transmitted after each data word is generated by a CRC algorithm with the properties displayed in Table 13. The CRC covers the contents of the two previously transmitted data bytes.

| Property | Value |
|----------------|--|
| Name | CRC-8 |
| Width | 8 bits |
| Polynomial | $0x31(x^8 + x^5 + x^4 + 1)$ |
| Initialization | 0xFF |
| Reflect input | False |
| Reflect output | False |
| Final XOR | 0x00 |
| Examples | CRC (0x00) = 0xAC CRC (0xBEEF) = 0x92 |

Table 13 SHTW2 I²C CRC properties.



Conversion of Signal Output

Measurement data is always transferred as 16-bit values. These values are already linearized and temperature compensated by the SHTW2. Humidity and temperature values can be calculated with the formulas in given below.

Relative humidity conversion formula (result in %RH):

$$RH = 100 \cdot \frac{S_{RH}}{2^{16}}$$

Temperature conversion formula (result in °C):

$$T = -45 + 175 \cdot \frac{S_T}{2^{16}}$$

S_{RH} and S_T denote the raw sensor output (as decimal values) for humidity and temperature, respectively.



5.10 Communication Data Sequences

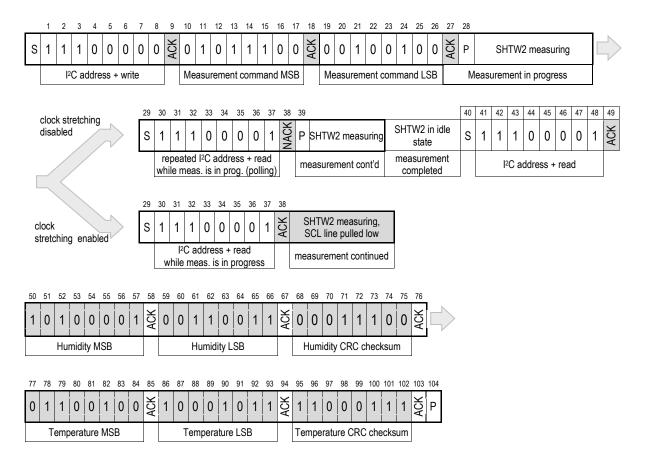


Figure 7 Communication sequence for starting a measurement and reading measurement results displaying both clock stretching options. The numerical example corresponds to a read humidity-first command with clock stretching enabled. The physical values of the transmitted measurement results are 65.6 %RH and 23.7 °C. Clear blocks are controlled by the microcontroller, grey blocks by the SHTW2.

| | | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 | 25 | 26 | 27 | |
|---|----------------------------------|---|---|---|---|-------------|---|---|---|-----|----|-------------|----|----|----|----|----|----|-----|----|----|----|----|----|----|----|----|-----|---|
| S | ; | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | ACK | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | ACK | 0 | 1 | 0 | 1 | 1 | 1 | 0 | 1 | ACK | Р |
| | I ² C address + write | | | | | Command MSB | | | | | | Command LSB | | | | | | | | | | | | | | | | | |

Figure 8 Command access communication sequence. The example shows a soft reset command. Clear blocks are controlled by the microcontroller, grey blocks by the SHTW2.



6 Quality

6.1 Environmental Stability

Qualification of the SHTW2 is performed based on the JEDEC JESD47 qualification test method.

6.2 Material Contents

The SHTW2 is RoHS and REACH compliant.

7 Package and Traceability

SHTW2 sensors are provided in a flip chip package with an outline of $1.31 \times 0.74 \times 0.54$ mm³ and 4 solder balls with a pitch of 0.4 mm. The humidity sensor is centered on the bottomside of the package. The top side of the package is protected with a black epoxy layer. This is called back side coating, because it is applied to the nonfunctional (back) side of the chip.

For a proper measurement it is important that the humidity sensor has good access to the ambient air and is not obstructed by underfill or other material. Therefor the SHTW2 must be assembled without underfill adhesive.

The SHTW2 package consists of silicon and lead-free solder balls. To protect the product from mechanical damage, any mechanical impact on the package shall be avoided. Any vertical or lateral force onto the package (e.g. during handling, assembly and in the application) shall not exceed 2N.

The Moisture Sensitivity Level classification of the SHTW2 is MSL1, according to IPC/JEDEC J-STD-020.

All SHTW2 sensors are marked for easy identification and traceability. The marking on the sensor consists of a 5-digit, alphanumeric tracking code and a pin-1 indicator. The pin-1 indicator is located in the top left corner. The bottom side contains a pin-1 indicator shaped as a teardrop around the solder ball of pin 1. See Figure 9 for illustration.

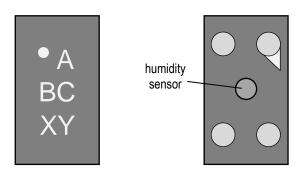


Figure 9 Top side marking (left side): pin-1 indicator and 5-digit alphanumeric tracking code. Bottom side marking (right side): pin-1 indicator.

8 Ordering Information

The SHTW2 can be ordered in tape and reel packaging with different reel sizes. The sensors are supplied in reels

with a diameter of 330 mm (7 inches), sealed into antistatic ESD bags. A drawing of the packaging tape with sensor orientation is shown in Figure 12.

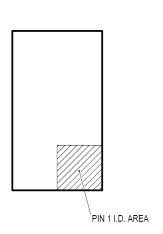
| Quantity | Packaging | Reel Diameter | Order Number |
|----------|-------------|-----------------|--------------|
| 1'000 | Tape & Reel | 180 mm (7 inch) | 1-101484-01 |
| 10'000 | Tape & Reel | 180 mm (7 inch) | 1-101380-01 |

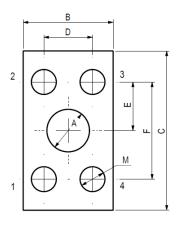
Table 14 SHTW2 ordering options.



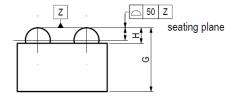
9 Technical Drawings

9.1 Package Outline





| Dim. | Min. | Nom. | Max. |
|------|------|------|------|
| Α | - | 0.16 | - |
| В | 0.71 | 0.74 | 0.77 |
| С | 1.28 | 1.31 | 1.34 |
| D | 0.38 | 0.40 | 0.42 |
| Е | 0.38 | 0.40 | 0.42 |
| F | 0.78 | 0.80 | 0.82 |
| G | 0.48 | 0.54 | 0.60 |
| Н | 0.12 | 0.15 | 0.18 |
| М | 0.17 | 0.20 | 0.23 |



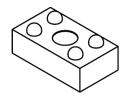


Figure 10 Package outline drawing of the SHTW2.

9.2 Recommended Metal Land Pattern

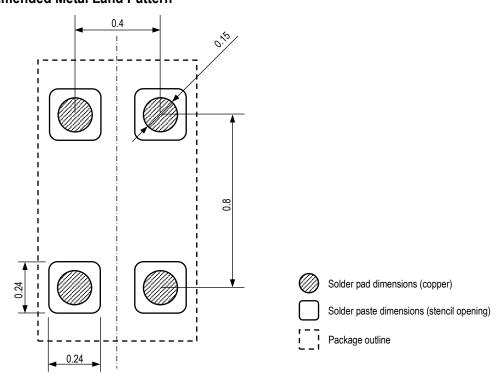


Figure 11 Recommended metal land pattern for SHTW2 (all dimensions are in mm). Recommended solder paste stencil thickness is 75 to $100~\mu m$. The solder pads on the PCB are recommended to be non solder mask defined (NSMD). Copper traces leading towards the solder pads are recommended to have a width of max. 0.09~m m in the direct vicinity of the pads. For general information on land pattern design refer to the IPC-7351 standard.



9.3 Tape & Reel Packaging

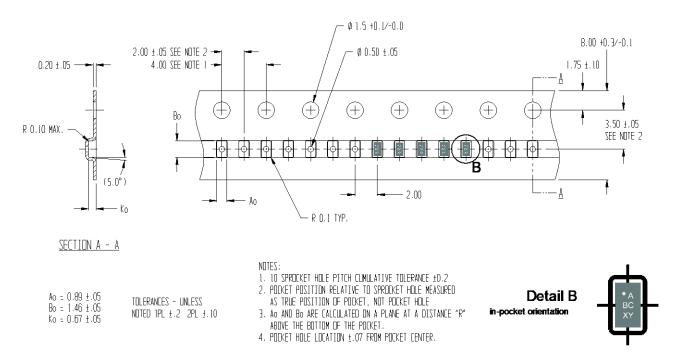


Figure 12 Technical drawing of the packaging tape with sensor orientation in tape. Header tape is to the right and trailer tape to the left on this drawing. Dimensions are given in millimeters.



10 Further Information

For more in-depth information on the SHTW2 and its application please consult the following documents:

| Document Name | Description | Source | | | | | |
|--|--|--|--|--|--|--|--|
| SHTW2 Optimization of Repeatability | Measures for optimization of repeatability of sensor output. | Available for download from the SHTW2 product website: www.sensirion.com/shtw2 | | | | | |
| SHTW2 Low Power Measurement Mode | Description of SHTW2 low power measurement mode. | Available for download from the SHTW2 product website: www.sensirion.com/shtw2 | | | | | |
| SHTxx Design Guide | Design guidelines for designing SHTxx humidity sensors into applications | Available for download at the Sensirion humidity sensors download center: www.sensirion.com/humidity-download | | | | | |
| SHTxx Handling Instructions | Guidelines for proper handling of SHTxx humidity sensors | Available for download at the Sensirion humidity sensors download center: www.sensirion.com/humidity-download | | | | | |
| Sensirion Humidity Sensor Specification Statement | Definition of sensor specifications. | Available for download at the Sensirion humidity sensors download center: www.sensirion.com/humidity-download | | | | | |

Table 15 Documents containing further information relevant for the SHTW2.



Revision History

| Date | Version | Page(s) | Changes |
|-----------------|---------|---------|--|
| 13. May 2016 | 1 | all | Initial released version. Updated product picture, minor adjustments on outline dimensions, added ordering information, correction of typos. |
| 03. August 2016 | 2 | 10 | Pin numbering in Figure 10 aligned with Table 7. |
| 25. July 2017 | 3 | 1, 2 | Temperature accuracy specification improved to typ. ±0.3°C / max. ±0.4°C |
| December 2022 | 4 | 12 | Removed obsolete document from table Table 15. |



Important Notices

Warning, Personal Injury

Do not use this product as safety or emergency stop devices or in any other application where failure of the product could result in personal injury. Do not use this product for applications other than its intended and authorized use. Before installing, handling, using or servicing this product, please consult the data sheet and application notes. Failure to comply with these instructions could result in death or serious injury.

If the Buyer shall purchase or use SENSIRION products for any unintended or unauthorized application, Buyer shall defend, indemnify and hold harmless SENSIRION and its officers, employees, subsidiaries, affiliates and distributors against all claims, costs, damages and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if SENSIRION shall be allegedly negligent with respect to the design or the manufacture of the product.

ESD Precautions

The inherent design of this component causes it to be sensitive to electrostatic discharge (ESD). To prevent ESD-induced damage and/or degradation, take customary and statutory ESD precautions when handling this product.

See application note "ESD, Latchup and EMC" for more information.

Warranty

SENSIRION warrants solely to the original purchaser of this product for a period of 12 months (one year) from the date of delivery that this product shall be of the quality, material and workmanship defined in SENSIRION's published specifications of the product. Within such period, if proven to be defective, SENSIRION shall repair and/or replace this product, in SENSIRION's discretion, free of charge to the Buyer, provided that:

 notice in writing describing the defects shall be given to SENSIRION within fourteen (14) days after their appearance;

- such defects shall be found, to SENSIRION's reasonable satisfaction, to have arisen from SENSIRION's faulty design, material, or workmanship;
- the defective product shall be returned to SENSIRION's factory at the Buyer's expense; and
- the warranty period for any repaired or replaced product shall be limited to the unexpired portion of the original period.

This warranty does not apply to any equipment which has not been installed and used within the specifications recommended by SENSIRION for the intended and proper use of the equipment. EXCEPT FOR THE WARRANTIES EXPRESSLY SET FORTH HEREIN, SENSIRION MAKES NO WARRANTIES, EITHER EXPRESS OR IMPLIED, WITH RESPECT TO THE PRODUCT. ANY AND ALL WARRANTIES, INCLUDING WITHOUT LIMITATION, WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE, ARE EXPRESSLY EXCLUDED AND DECLINED.

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SENSIRION does not assume any liability arising out of any application or use of any product or circuit and specifically disclaims any and all liability, including without limitation consequential or incidental damages. All operating parameters, including without limitation recommended parameters, must be validated for each customer's applications by customer's technical experts. Recommended parameters can and do vary in different applications.

SENSIRION reserves the right, without further notice, (i) to change the product specifications and/or the information in this document and (ii) to improve reliability, functions and design of this product.

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