

IST8315-L 3D Magnetometer

Datasheet



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1. General Description

iSentek IST8315-L is a 3-axis digital magnetometer with a 1.6 x 1.6 x 1.0 mm³, 12-pin LGA package. It is an integrated chip with 3-axis magnetic sensors, digital control logic, a built-in temperature compensation circuit, and self-testing function. IST8315-L provides an I²C digital output with fast mode up to 400 kHz. Its ultra-high output data rate, ultra-low noise, ultra-low hysteresis and excellent temperature drift performance features make it a perfect candidate for applications requiring high speed and high precision.

Features

- Single-chip 3-axis magnetic sensor
- 1.6 x 1.6 x 1.0 mm³, 12-pin LGA package
- I²C slave, Fast Mode up to 400 kHz
- 14-bit data output
- Built-in FIFO with 32 depths for each axis
- Ultra-high output data rate with a maximum value of 1000 Hz
- Dynamic range of ± 1000 uT.
- Ultra-low hysteresis (< 0.1 %FS)
- Ultra-low sensitivity temperature drift (±0.025 %/°C)
- Ultra-low offset temperature drift (0.016 uT/°C)
- High precision temperature compensation
- Wide operating temperature range
- Built-in self-test function
- Built-in noise suppression filter
- Software and algorithm support are available (for tilt compensation, soft/hard-iron calibration)

Applications

- Augmented/Virtual Reality Applications
- Quadcopter/Drone Applications
- Navigation Applications
- Industrial Applications

- Magnetometry
- IoT devices
- Heading
- Gaming



2. Block Diagram, Package Dimension and Application Circuit

2.1. Block diagram

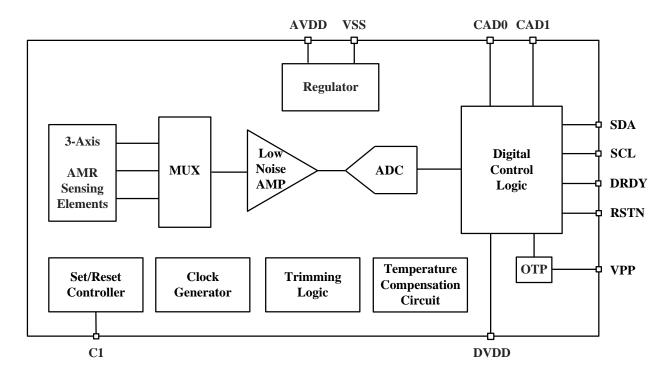


Figure 1. Block Diagram

2.2. Package Dimensions

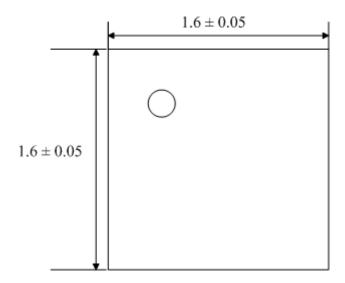


Figure 2. IST8315-L Top View



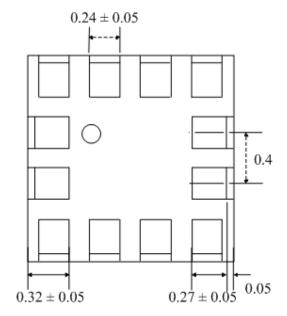
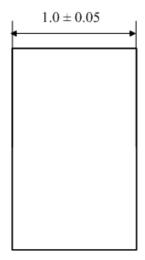


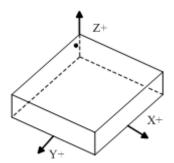
Figure 3. IST8315-L Bottom View



Unit: mm

Figure 4. IST8315-L Side View

IST8315-L 3D Top View





2.3. Application Circuits and Pin Descriptions

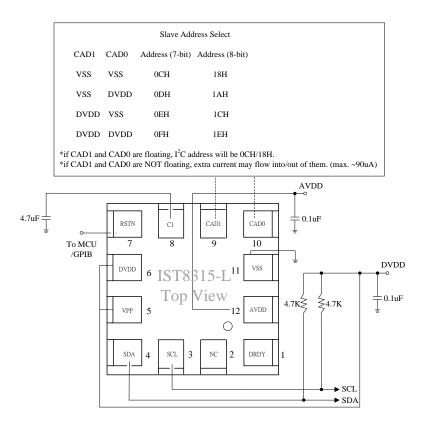


Figure 5. IST8315-L Application Circuit

Pin*1	Name	Function
1	DRDY	Data ready
2	NC	Not use
3	SCL	I ² C serial clock
4	SDA	I ² C serial data
5	VPP	Test pin, connect to DVDD or keep floating*2
6	DVDD	Digital supply voltage, 1.72 ~ 3.6 V
7	RSTN	Reset
8	C1	Set/Reset function
9	CAD1	I ² C slave address select, internally pulled to "high" by default
10	CAD0	I ² C slave address select, internally pulled to "low" by default
11	VSS	GND
12	AVDD	Analog supply voltage, 2.4 ~ 3.6 V

^{*1} Please refer to Figure 2 on page 7.

^{*2} Please keep CAD1 floating if VPP is floating.



3. Electrical Specifications

3.1. Absolute Maximum Ratings

Parameter	Symbol	Limits	Unit	
Storage Temperature	TSTG	-40 to +150	°C	
Analog Supply Voltage	AVDD	-0.5 to +3.6	V	
Digital Supply Voltage	DVDD	-0.5 to +3.6	V	
Digital Input Voltage	VIN	-0.3 to DVDD+0.3	V	
Electrostatic Discharge Voltage*1	VESD_HBM	-4000 to 4000	V	
Electrostatic Discharge Voltage*2	VESD_MM	-300 to 300	V	
Electrostatic Discharge Voltage*3	VESD_CDM	-700 to 700	V	
Reflow Classification	JESD22-A113 with 260 °C Peak Temperature			

^{1.} Human Body Model (HBM)

3.2. Recommended Operating Conditions

Parameter	Symbol	Min.	Тур.	Max.	Unit
Operating Temperature	TA	-40		+85	°C
Analog Supply Voltage	AVDD	2.4	3.3	3.6	V
Digital Supply Voltage	DVDD	1.72	1.8	3.6	V

^{2.} Machine Model (MM)

^{3.} Charge Device Model (CDM)



3.3. Electrical Specifications

(Operating conditions: TA = +25 °C; AVDD = 2.5 V; DVDD = 1.8 V; 4.7 μ F ceramic capacitors tied to C1 pin with maximum allowed line width and 5 mm distance.)

Parameter	Symbol	Conditions	Min.	Тур.	Max	Unit
Operating Current	IDD3A	Full operation with OSR*1=1 setting, at 10 sps 20 sps 50 sps 100 sps 200 sps 333 sps 500 sps 1000 sps		100 200 400 750 1450 2350 3450 6900		uA
Suspend Current	ISPD			2		uA
Output Data Rate (ODR)	ODR				1000*2	Hz
Over Sampling Rate*1	OSR		1		32	
Input Low Voltage	VIL		0		DVDD *30 %	V
Input High Voltage	VIH		DVDD *70 %		DVDD	V
Output Low Voltage	VOL	IOL = +4 mA	0		DVDD *20 %	V
Output High Voltage	VOH	IOH = -100 uA (Except SCL and SDA)	DVDD *80%		DVDD	V

^{1.} Register OSRCNTL(0x41) controls OSR setting.

3.4. Magnetic Sensor Specifications

(Operating conditions: TA = +25 °C; AVDD = 2.5 V; DVDD = 1.8 V; 4.7 μ F ceramic capacitors tied to C1 pin with maximum allowed line width and 5 mm distance.)

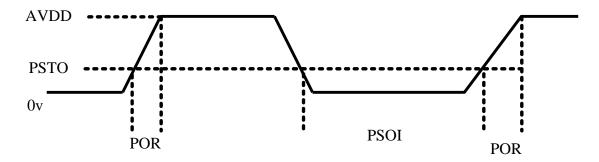
Parameter	Symbol	Condition	Min.	Тур.	Max	Unit
Dynamic Range	DR	TA = 25 °C		±1000		uТ
Linearity	LIN			0.5		%FS
Resolution	RES			0.3		uT/LSB
Sensitivity	SEN			3.3		LSB/uT
Zero Gauss Offset	ZGD			±0.3		uТ
Hysteresis	HS			0.1		%FS

^{2.} 1000Hz ODR can be achieved with OSR = 1.



Sensitivity Temperature Drift	TD_S	-40 ~ 85 °C	±0.025	%/°C
Zero-B Offset Temperature Drift	TD_O	-40 ~ 85 °C	0.016	uT/°C

3.5. Power On Reset (POR) Specifications



PSTO: Power Supply Turn Off voltage
PSOI: Power Supply Turn Off Interval
PSOI: max=0.7volt
PSOI: min=10ms

POR: Power On Reset POR: max:50ms

When POR circuit detects a rise of AVDD voltage, it resets all internal circuits and initializes all registers. After reset, IST8315-L transits to Standby mode.



4. Technology Overview

4.1. AMR Technology

iSentek's patented magnetometer IST8315-L is designed using Anisotropy Magnetoresistance (AMR) technology. The output is generated by the change in resistance of the AMR resistors as the external magnetic field varies. The sensitivity is approximately 50 to 200 times greater than conventional Hall elements. The high sensitivity allows a higher output data rate (ODR), lower noise, and lower power consumption.

4.2. High Reliability Planarized Structure Design

IST8315-L consists of three full Wheatstone Bridges of AMR resistors. The three bridges detecting magnetic components in orthogonal directions are wire-bonded to a control ASIC on a single chip. This planarized structural design offers exceptional thermal shock stability, making our device extremely reliable, whereas other known AMR magnetometers with z-axis sensors placed vertically on the substrate employing 90-degree flip-chip packaging suffer from reliability issues.

4.3. Ultra-low Hysteresis Design

iSentek has developed a specialized high permeability (μ) material for magnetic field detection. This high- μ material has ultra-low residual magnetization below 0.1 %FS in the field range as large as ± 500 G. The ultra-low hysteresis design prevents the magnetometer from experiencing dynamic offset after encountering a strong external magnetic field impact; that is, the angular accuracy is restored automatically without calibration after the removal of the interference field. This feature fulfills the requirements for applications when real-time calibration is unavailable. No calibration is required in general conditions.

4.4. Magnetic Setting Mechanism

AMR sensing resistors consist of permalloy thin film and metallization. Permalloy is a soft magnetic material. Irreversible magnetic rotation may occur when the strength of external magnetic field exceeds half of the anisotropy field of the sensing resistor, resulting in angular error induced by offset. To solve this issue, a magnetic setting mechanism has been introduced in IST8315-L. A magnetic field is generated within IST8315-L to align the magnetization of AMR sensing resistors before every measurement. This auto-zeroing mechanism ensures the stability of the IST8315-L's angular accuracy throughout the operation.



5. Ordering Information

Order Number	Package Type	Packaging	Marking Information
IST8315-L	LGA – 12 pin	Tape and Reel: 3k	$X_1X_2X_3$
		pieces per reel	15●
			X_1 : Last number of the year
			X ₂ X ₃ : Week number
			15: Product code

For more information on iSentek's Magnetic Sensors, please contact +86-132-6706-8686 (China), +86-755-2991-0201 (China) or +886-2-2698-3306 ext: 111 (Taiwan); send an email to sales@isentek.com; or visit us online at www.isentek.com.

The U.S. patents 9297863 and 9562953B2 and the Taiwanese patents I437249, I420128, I463160, and I565958 cover our described magnetic sensor technology.

6. Legal disclaimer

6.1. Warranty and Liability Disclaimer

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