

## AS33-M42M Series

### 42-Bit Full Magnetic Energy Harvesting Multi-Turn Absolute Encoder Module



## Description

The Broadcom® AS33-M42M series is an 18-bit single-turn (ST) absolute magnetic encoder with a 24-bit energy harvesting multi-turn (MT) counter. Hence, the encoder solution has a combined 42-bit absolute resolution. Design of the encoder features state-of-the-art energy harvesting MT technology and angular magnetic hall sensing with sophisticated signal conditioning algorithms. A single magnetic solution is thus responsible for both the ST and MT positions' generation; which greatly improves overall feedback system integrity and simplicity.

The key advantage of the AS33-M42M series encoder is the patented energy harvesting technology for revolution tracking. This technology converts rotating magnetic field into electrical energy, which powers the revolution tracking circuit. The beauty of energy harvesting technology is that the same amount of energy is generated independent of encoder rotation speed and direction. The generated energy is sufficient to power up the MT counter circuitry. Therefore, there is no loss of revolution count even in the absence of an external power supply. On the other hand, when comparing to battery backed-up MT counting, this technology does not require periodic maintenance of the battery backup components and the downtime associated with it. Field servicing of the servo motor systems can then be minimized, which reduces the overall system cost over the service life of the system.

The AS33-M42M series encoder has a built-in communication protocol, which is supported by a full-duplex or half-duplex line transmissions drive, offering good noise immunity for a robust transmission of data up to 10 Mb/s even in harsh industrial applications. This magnetic

technology-based encoder is robust against contamination such as dust and finger prints on the sensing element. As a result, it requires less stringent control in production handling and harsh environments.

## Features

- Patented energy harvesting technology
- Total 42-bit resolution with 18-bit single-turn and 24-bit multi-turn
- Low angular accuracy error of  $<0.1^\circ$
- Overall encoder outer diameter of  $\varnothing 33$  mm and maximum height of 20 mm
- Built-in communication protocol (options):
  - SSI (2 MHz)
  - BiSS-C (10 MHz)
  - RS-485 half-duplex (2.5/5.0/10 MB/s)
- Built-in temperature sensor
- Operating temperature range:  $-40^\circ\text{C}$  to  $115^\circ\text{C}$

## Applications

- Small motors and linear actuators
- Robotic automation and engineering
- Drone and automated guide vehicles
- DC and AC servo motors
- Test and measurement equipment

**NOTE:** This Broadcom product is not specifically designed nor manufactured for use in any specific devices. Customers are solely responsible for determining the suitability of the product for its intended application and liable for all loss, damage, expense, or liability in connection with such use.

# Product Specifications

**Table 1: Absolute Maximum Ratings**

Parameter	Symbol	Min.	Typ.	Max.	Units	Remark <sup>a</sup>
Supply Voltage	VDD	−0.3	—	15	V	
Operating Temperature	T <sub>J</sub>	−40	—	115	°C	
Storage Temperature	T <sub>S</sub>	−40	—	115	°C	
Permissible Speed	—	—	—	12,000	rpm	Note <sup>b</sup>

a. Exposure to absolute maximum rating conditions for extended periods may affect reliability. Stresses greater than the absolute maximum ratings may cause permanent damage to the device.

b. The encoder works reliably up until this permissible speed.

## Recommended Operating Conditions

**Table 2: Electrical Specifications over T<sub>A</sub> = 25°C**

Parameter	Condition	Min.	Typ.	Max.	Units	Remark
Supply Voltage	—	4.5	—	5.5	V	AS33-M42M-x5x
		7	—	12.5	V	AS33-M42M-x7x
Supply Current	Without load	—	55	65	mA	AS33-M42M-x5x
		—	45	55	mA	AS33-M42M-x7x
System Accuracy	With electrical correction <sup>a, b, c</sup>	—	±0.087	—	Degree	

a. Under recommended magnetic shielding enclosure and calibration at ambient 25°C. Any wear-and-tear condition that might affect total indicated runout of the motor shaft causes encoder accuracy drift.

b. The system accuracy measurement is conducted with direct mounting.

c. At power-up conditions, the accuracy error may be higher than the typical value due to the variation in user application and setup. Active compensation takes effect to correct the accuracy error after multiple angular rotations.

**Table 3: Mechanical Specifications**

Parameter	Condition	Min.	Typ.	Max.	Units	Remark
Axial Misalignment	—	—	—	0.2	mm	
Radial Misalignment	—	—	—	0.2	mm	
Vibration	Per IEC 60068-2-6	—	—	10G	—	10~2000 Hz
Shock	Per IEC 60068-2-27	—	—	200G	—	6 ms; half sine

**Table 4: Environmental Specifications**

Parameter	Condition	Min.	Typ.	Max.	Units	Remark
Relative Air Humidity	T <sub>A</sub> = 60°C	—	90	—	RH%	Non-condensing
Electrostatic Discharge	Per IEC 61000-4-2	—	—	4	kV	Module level

**Table 5: Internal Temperature Sensor Specifications**

Parameter	Condition	Min.	Typ.	Max.	Units	Remark
Resolution		—	1	—	°C	
Accuracy of Evaluation Circuit	25°C to 115°C	–5	—	5	°C	
	–40°C to 25°C	–7	—	7	°C	
Temperature Range <sup>a, b</sup>		–40	—	125	°C	
Calculation Time		—	—	100	ms	

a. Temperature error alarm setting = 118°C. Temperature readout is second complement value.

b. Temperature sensor is not available for SSI version product.

**Table 6: Encoder Specifications**

Parameter	Remark
Single-turn Resolution	Programmable 17 bits or 18 bits (maximum 262,143 counts per revolution)
Multi-turn Resolution	Programmable 12, 14, 16, or 24 bits (maximum 16,777,215 counts)
Counting Direction	Default setting: Increase with counter-clockwise (CCW) motor shaft rotation, view from encoder top (programmable to clockwise direction)
Initialization Time	500 ms

Protocol Specifications

SSI Specifications

Table 7: SSI Interface Line Drivers

Interface	Recommended Circuit	Remark
Shift Clock (SCLK)	Transmitter (P/N: ISL3295E)	
Data Output (DAT)	Receiver (P/N: ISL3283E)	

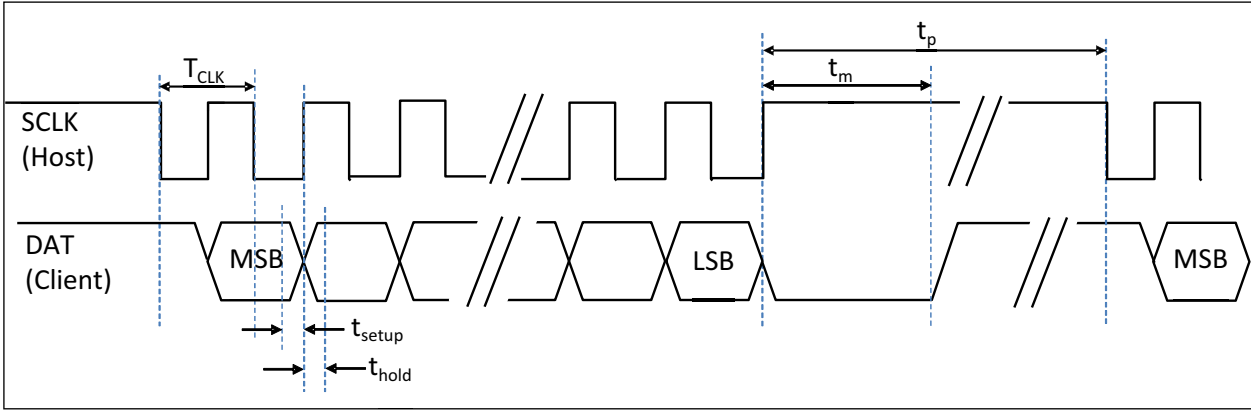
Table 8: SSI Timing Characteristics

Parameter	Symbol	Condition	Min.	Typ.	Max.	Units	Remark
Clock Frequency	$f_{CLK}$	—	100	—	2000	kHz	
Clock Duty	$DUT_{CLK}$	—	—	50	—	%	
Monoflop Time	$t_m$	—	—	—	20	$\mu s$	
Pause Time	$t_p$	—	21	—	—	$\mu s$	

Table 9: SSI Data Field for 42-Bit Data

MT[23:0]	ST[17:0]	Status[0]	Alarm[0]
----------	----------	-----------	----------

Figure 1: SSI Interface Timing Diagram



## Position Zero Reset

Figure 2: A Pulse of >100 ms Resets the Full Position Value to Zero

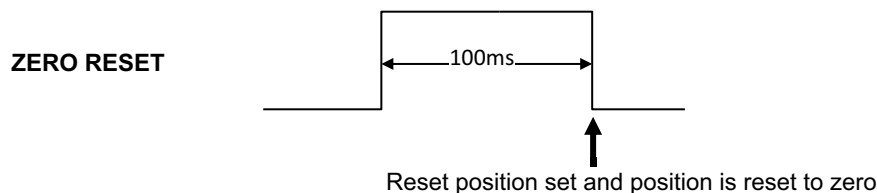


Table 10: Position Zero Reset Command

SSI Command	Signal
Position Zero Reset	Apply a minimum 100-ms Hi Pulse to the Zero Reset Pin (Pin 9); see <a href="#">Table 16</a> for the connector pinout.

## BiSS-C Specifications

Table 11: BiSS-C Interface Transceivers

Interface	Recommended Circuit	Remark
Serial Clock (MA)	Transmitter (P/N: ISL3295E)	
Serial Data Output (SLO)	Receiver (P/N: ISL3283E)	

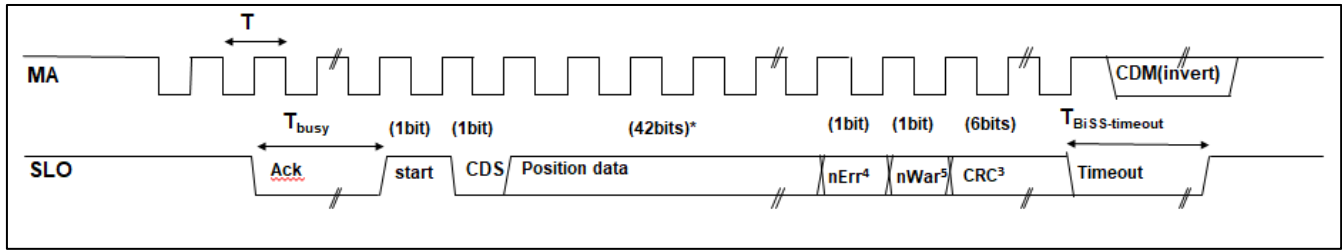
Table 12: BiSS-C Timing Characteristics

Parameter	Symbol	Condition	Min.	Typ.	Max.	Units	Remark
MA Frequency	$f_{MA}$	—	0.08	—	10	MHz	
MA Duty	$DUT_{CLK}$	—	—	50	—	%	
Busy	$T_{busy}$	—	—	—	5	$\mu s$	
Timeout	$t_{BiSS-timeout}$	—	—	—	5	$\mu s$	
Frame to Frame	—	—	—	—	1	$\mu s$	

Table 13: BiSS-C Data Field

MT[23:0]	ST[17:0]	Error[0]	Warning[0]	CRC[5:0]
----------	----------	----------	------------	----------

Figure 3: BiSS-C Interface Timing Diagram



NOTE:

- 1. CRC Polynomial = Invert of (X6 + X1 + X0).
- 2. nErr bit is active low. (Combine all the Error Status and reflect in nErr bit.)
- 3. nWar bit is active low. (Combine all the Warning Status and reflect in nWar bit.)
- 4. Position data varies depending on single-turn and multi-turn resolution.

RS-485 Half-Duplex Specifications

Table 14: RS-485 Half-Duplex Interface Transceivers

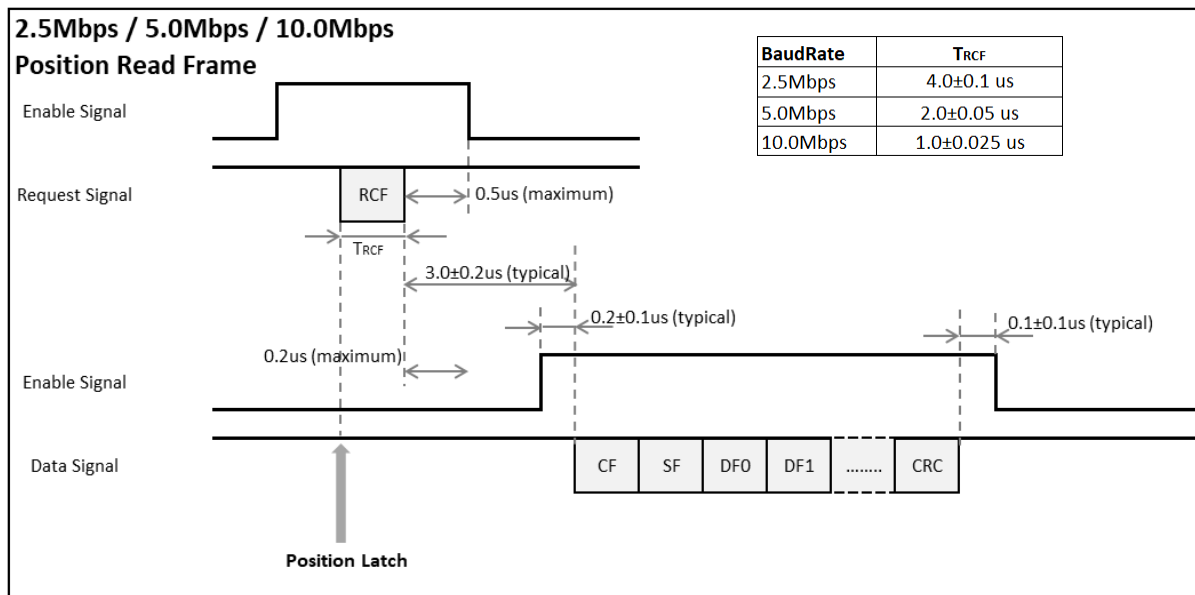
Interface	Recommended Circuit	Remark
RS-485 Serial Data (DAT)	Receiver (P/N: ISL3283E)	
RS-485 Serial Data (DAT)	Transmitter (P/N: ISL3295E)	

Table 15: RS-485 Half-Duplex Timing Characteristics

Parameter	Condition	Min.	Typ.	Max.	Units	Remark
Communication Baud Rate	—	—	—	10	MHz	2.5, 5.0, 10.0 MHz
Frame Length	—	—	10	—	Bit/Frame	
Jitter	—	—	—	100	ns	

## Position Read Frame

Figure 4: Timing Characteristics of Enable, Request, and Data Signals for Position Data Read

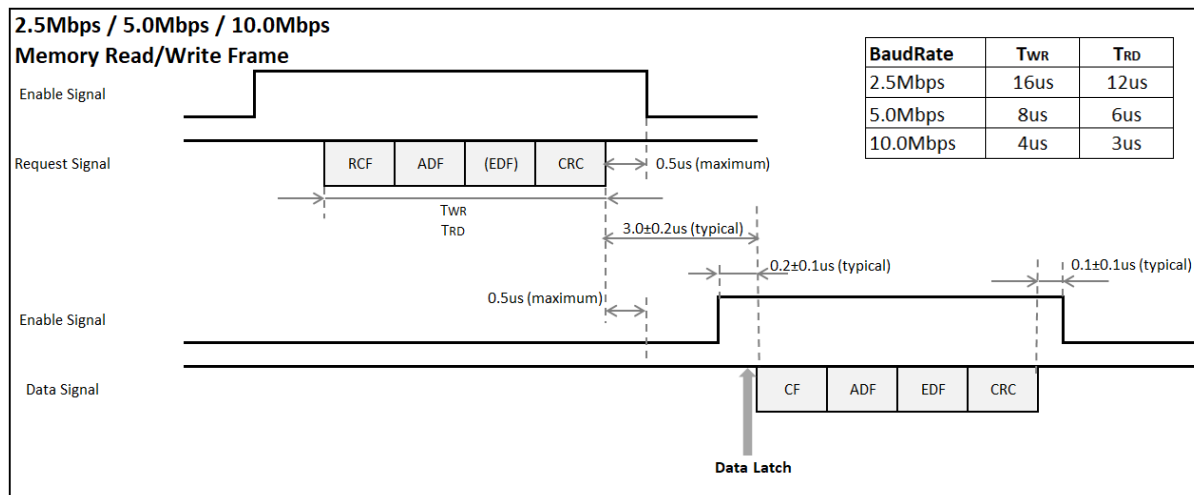


### NOTE:

1. RCF: Request Control Field indicates the start of a transmission frame set.
2. CF: Control Field corresponds to the command frame issued by the host.
3. SF: Status Field.
4. DF0~DF7: Encoder Data Field.
5. CRC: Cyclic Redundancy Check (CRC) frame.

## EEPROM Read/Write Frame

Figure 5: Timing Characteristics of Enable, Request, and Data Signals for Memory Access



### NOTE:

1. ADF: Address Data Frame indicates the memory location to Write.
2. EDF: Memory Data Frame contains the written/read data of the memory.

## Register Communication and Assignment

Refer to the AS33-M42M RS485 software specification document for detailed information.

## Electrical Pinout

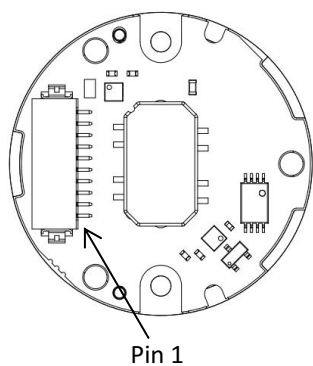
Table 16: Connector Output Assignment

Pin No.	SSI	BiSS-C	RS485 Half-Duplex
1	GND	GND	GND
2	VDD	VDD	VDD
3	SCL-	MA-	NC(1)
4	SCL+	MA+	NC(1)
5	DOUT-	SLO-	DATA-
6	DOUT+	SLO+	DATA+
7	Cal 1 <sup>a</sup>	Cal 1 / NC <sup>a</sup>	Cal 1 / NC <sup>a</sup>
8	Cal 2 <sup>a</sup>	Cal 2 / NC <sup>a</sup>	Cal 2 / NC <sup>a</sup>
9	Zero Reset / Cal 3 <sup>b</sup>	Cal 3 / NC <sup>a</sup>	Cal 3 / NC <sup>a</sup>
10	GND	GND	GND

a. Only for the calibration process. Do not connect during operation (NC).

b. Zero Reset pin for the SSI option only.



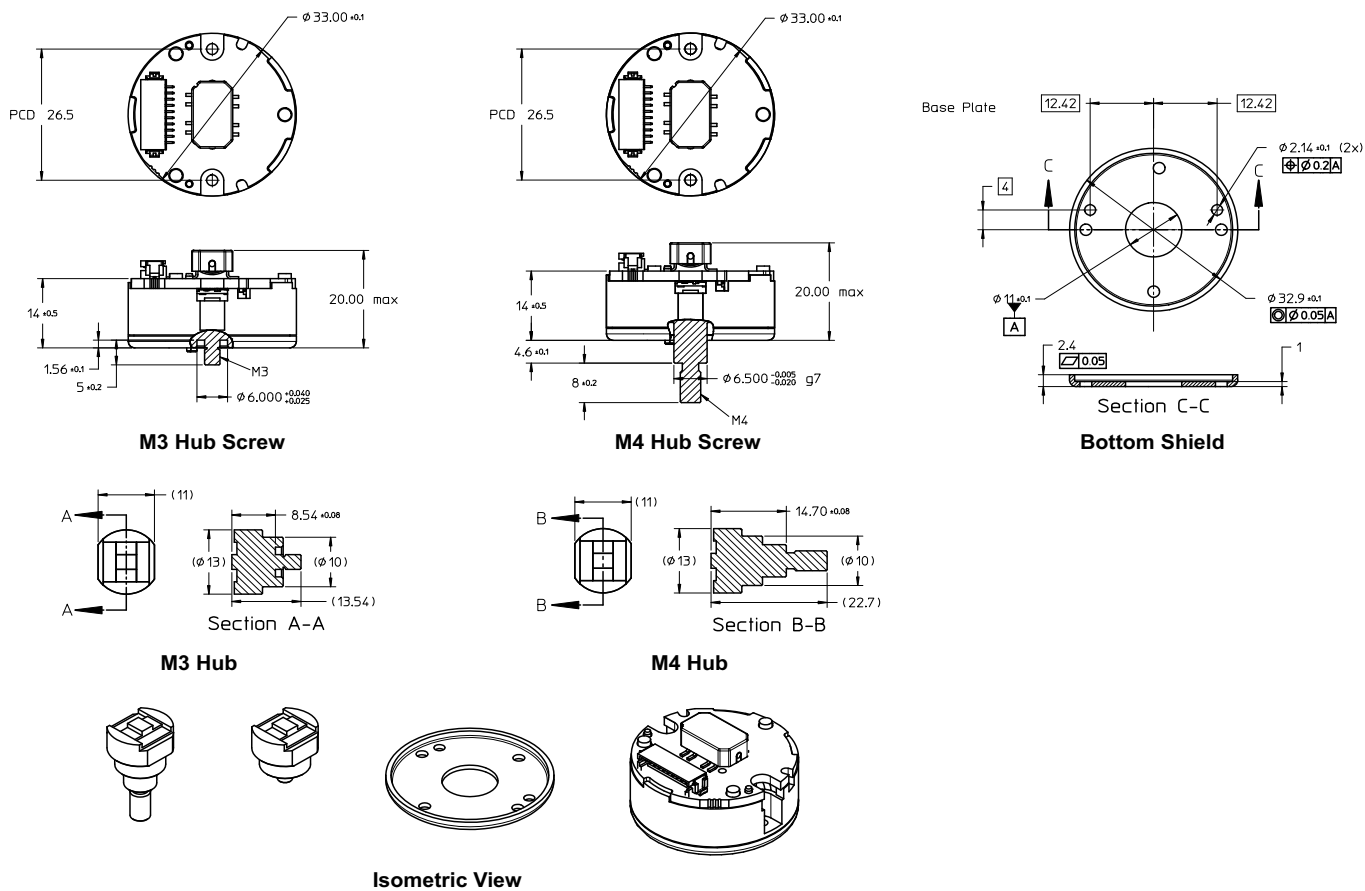
**Figure 6: Pin 1 Location as Viewed from the Encoder Top**

Recommended mating connector:

- Hirose Part No.: DF13-10S-1.25C (CL No. 536-0009-6-00)
- Hirose (Terminal Pin for Wire 26~30AWG): DF13-2630SCF (CL No.536-0300-5)

## Mechanical Dimensions

Figure 7: Package Dimensions



### NOTE:

1. Dimensions are in millimeters.
2. Unless otherwise specified, all tolerances are within  $\pm 0.5$  mm.
3. Use of a ferro-magnetic shaft may affect the magnetic system and hence encoder performance at the final applications. Users are advised to perform their own engineering assessments based on the actual use case.

## Magnetic Shield Design Guidelines

To eliminate or minimize the influence of external magnetic field interference on encoder operation, use of shielding is mandatory. The recommended design of shielding made of 1.2-mm mild steel (SPCC) is shown in the following figure.

**Figure 8: Recommended Magnetic Shield Design**

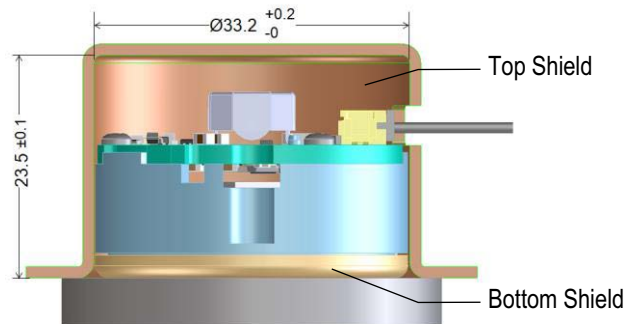
### Shield Requirement

Minimum Thickness: 1.2mm

Material: Mild Steel

Process: Vacuum

Annealing at temperature  
850°C for 1hour

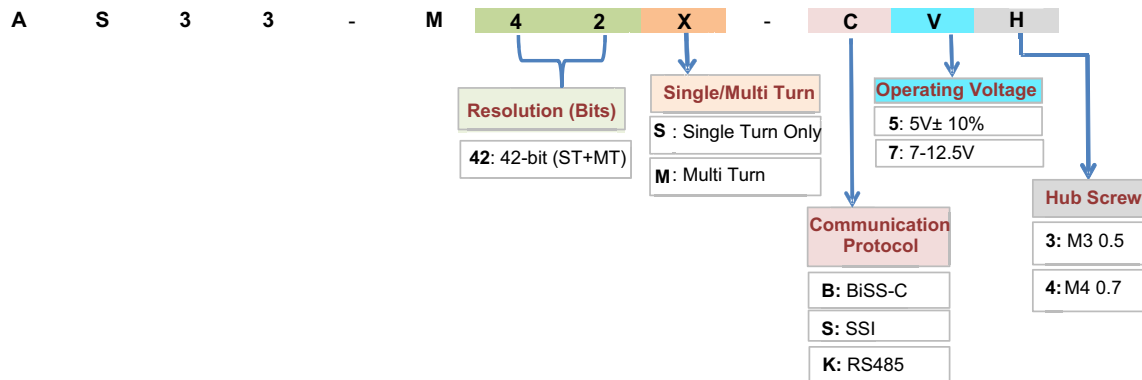


### **NOTE:**

1. External magnetic interference varies by the application and operating environment.
2. The customer conducts a proper study of the external magnetic field to have an appropriate shield design for the targeted application.
3. Consult the factory for technical assistance.

## Ordering Information

### Encoder Part Numbers



### Accessories and Tools

1. AS33-M42-010 Electronic Accuracy Calibration Kit
2. AS33-M42-023 Radial Centering Jig for M3 Hub
3. AS33-M42-024 Radial Centering Jig for M4 Hub
4. AS33-AC18 Benchtop Accuracy Calibration Station
5. AS33-C150 AS33 10-Pin Mating Connector with 150-mm Length Cable

**NOTE:** Refer to the factory for a sample order and lead time.

Copyright © 2020–2022 Broadcom. All Rights Reserved. The term “Broadcom” refers to Broadcom Inc. and/or its subsidiaries. For more information, go to [www.broadcom.com](http://www.broadcom.com). All trademarks, trade names, service marks, and logos referenced herein belong to their respective companies.

Broadcom reserves the right to make changes without further notice to any products or data herein to improve reliability, function, or design. Information furnished by Broadcom is believed to be accurate and reliable. However, Broadcom does not assume any liability arising out of the application or use of this information, nor the application or use of any product or circuit described herein, neither does it convey any license under its patent rights nor the rights of others.

