### Active safety systems

SMI860 combined inertial sensor for vehicle dynamics control





### PRODUCT BENEFITS

- ► Target applications
  - ESP®
  - Roll-over sensing
  - Adaptive cruise control
  - Short-term localization
  - and other safety and ADAS functions
- ► Excellent vibration robustness and offset stability
- ► Developed for systems with requirements up to ASIL D

1 Ball grid array package (BGA), 7 mm × 7 mm × 1.5 mm

# reliable operation

due to excellent vibration resistance

### **TASK**

The SMI860 is especially designed to support safety and ADAS functions with ASIL rating: ESP®, roll-over sensing, adaptive cruise control, hill-hold control, and short-term localization for ADAS functions. The SMI860 is a five axis sensor measuring yaw rate  $(\Omega_z)$ , roll rate  $(\Omega_x)$  and acceleration  $(a_{xyz})$ . It provides all relevant inertial signals in just one sensor. Subsequent system algorithms will use these sensor signals to compute the dynamical driving state of a vehicle or its position.

### **FUNCTION**

The SMI860 sensor is based on MEMS technology combining gyroscope and low-g acceleration sensors.

Its gyros can measure whether a vehicle is rotated around its vertical or lateral axis, the low-g channels will detect whether an acceleration is exerted to the vehicle.

Rotations will deflect a micro machined seismic mass of a MEMS gyro chip, accelerations deflect a MEMS accelerometer chip. As a result of external forces acting on the vehicle, deflections of the seismic masses along the sensitive axis generate changes in the capacity of the system. These movements are detected by a signal conditioning ASIC. Subsequent processing consists of low-pass filtering the signals and translating them into a SafeSPI communication protocol. The sensor is developed according to ISO26262 for use in systems up to ASIL D.

## safe and economical

integrated sensor solution, applicable in systems up to ASIL D requirements

### MEASUREMENT CHARACTERISTICS

Measurement axis	$\Omega_{\textbf{x}}$	$\Omega_{\text{z}}$	a <sub>xy</sub>	a <sub>z</sub>
Range	±300°/s		6 g	
Digital resolution	16-bit		16-bit	
Sensitivity (nominal)	100LSB per°/s		5000LSB perg	
Sensitivity variation <sup>1</sup>	±3%		±3%	
Offset variation <sup>1</sup>	±2°/s	±3°/s	50 mg	55 mg
Noise (rms)	±0.1°/s		4 mg	6 mg

### TECHNICAL CHARACTERISTICS

Communication	SafeSPI
Low pass filter settings: f <sub>-3dB</sub> <sup>2</sup>	10, 20 or 80 Hz
Start-up time³	max. 400 ms

### **OPERATING CONDITIONS**

Supply voltage	3.3 V, 5 V or 6.7 V
Supply current	<28mA
Operating temperature	-40°C to +125°C

<sup>&</sup>lt;sup>1</sup> over lifetime and temperature

<sup>&</sup>lt;sup>2</sup> nominal corner frequency corresponding to programmable filter settings

<sup>&</sup>lt;sup>3</sup> depends on filter settings. Here: incl. up to 3 self-tests for 80 Hz setting