

V 1 2

Revised 9/21

A-10 Analog Pressure Sensor

Reads Pressure (PSIG)

Range **10 PSIG (68.947 kPa)**

Resolution 1mv (.0025 PSI /0.017 kPa)

Accuracy <= 0.1 PSI (0.689 kPa)

Connector Tinned leads

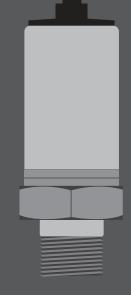
Response Time < 1ms

Data protocol Analog voltage

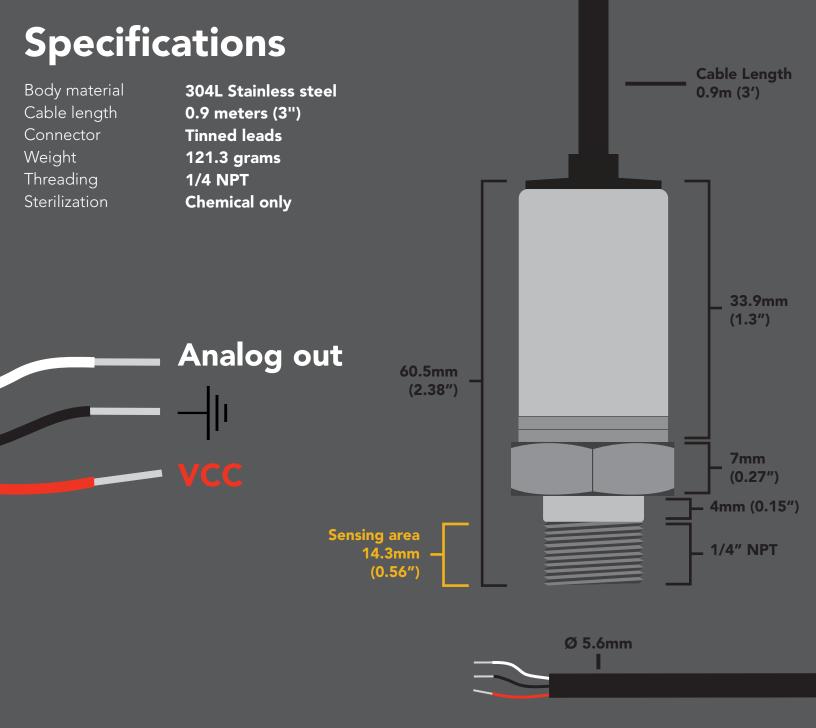
Data format 0.5 VDC - 4.5 VDC

Operating voltage 5 VDC

Durability IP67







Absolute max ratings

VCC

Output current

Operating temperature

Proof pressure

Burst pressure

5.5 VDC 0.45 mA -40°C - 105°C 30 PSI (206 kPa) 300 PSI (2,068 kPa)

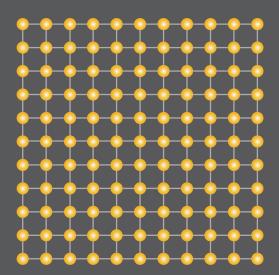
Power consumption

5V **6 mA**

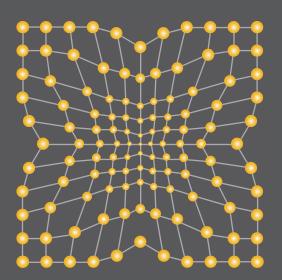


Operating principle

Internally the pressure sensor uses a piezoresistive semiconducting element. The semiconducting element (a silicon wafer) changes its resistance in proportion to pressure. As the pressure increases the atomic spacing of the silicon atoms decreases, this in turn lowers the resistance of the silicon wafer.



Atmospheric pressure $1M\Omega$



10 PSI (68.947 kPa) 500KΩ

An on-board microcontroller monitors the resistance and temperature of the semiconducting element. By combining these two parameters, the microcontroller computes the pressure and convert it into an analog voltage.

Analog Output = 0.5 – 4.5 VDC

Pressure

0 PSI (atmosphere)

2 psi

4 psi

6 psi

8 psi 10 psi

Volts

0.5

1.3

PSI

2.1 2.9

3.7 4.5 Voltage to PSI equation

 $PSI = 2.5 \times (Volts) - 1.25$

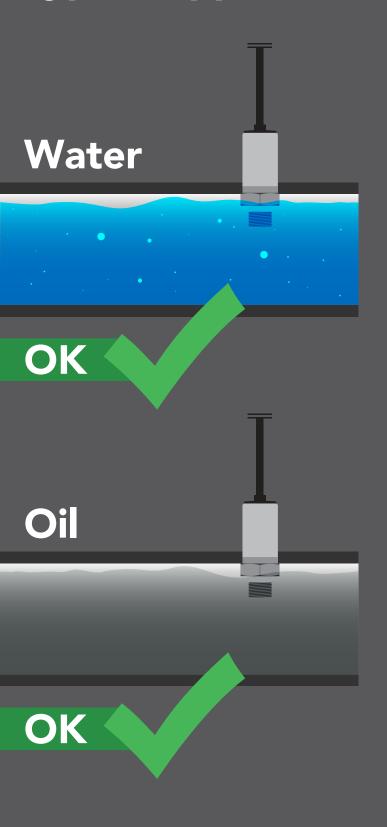
Voltage to kPa equation

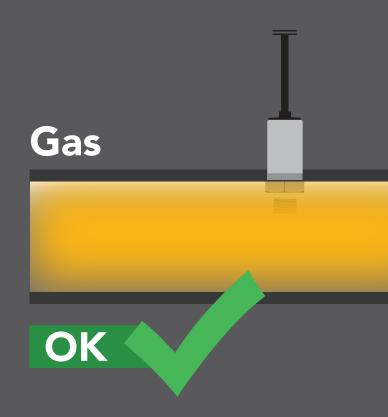
 $kPa = 17.237 \times (Volts) - 8.6185$

When the sensor is not under any pressure it may read a slight negative pressure. It is common to see negative readings from **-0.01** to **-0.04**. This is due to floating point error when the sensor is not under pressure and should be ignored.



Typical applications





Submerge



DO NOT submerge

